

N32H787

Datasheet

The N32H787 series adopts a high-performance dual-core architecture. The ARM Cortex-M7 core serves as the main core, running at frequencies up to 600MHz, supporting double-precision floating-point operations and DSP instructions. The Cortex-M4 core serves as the auxiliary core with a maximum operating frequency of up to 300 MHz. It features (2/4MB) on-chip FLASH, integrates up to 1504KB of SRAM (including 1024KB TCM SRAM and 480KB SRAM) + 4KB Backup SRAM. It includes 3 12-bit 5Msps ADCs, 4 high-speed comparators, 6 12-bit DACs, and integrates multiple high-speed communication interfaces: U(S)ART, I2C, xSPI, SPI, USBHS Dual Role, CAN-FD, SDRAM, FEMC, SDMMC, and 10/100/1000M Ethernet.

The series supports digital camera interface (DVP), MIPI, TFT-LCD graphical interface, JPEG hardware codec and GPU. It features a built-in high-performance encryption algorithm hardware acceleration engine, supporting AES/TDES, SHA algorithms, TRNG true random number generator, and CRC8/16/32. It supports up to 168 GPIOs, and is available in BGA240+25 packages.

Key Features

- **Dual-core Architecture CPU (Cortex-M7 and Cortex-M4F)**
 - ARM Cortex-M7
 - 32-bit ARM Cortex-M7 core with a double-precision floating-point unit, supporting DSP instructions and MPU
 - Built-in 32 KB instruction Cache and 32 KB data Cache with ECC
 - Maximum operating frequency of 600 MHz, delivering 1284 DMIPS
 - ARM Cortex-M4F
 - 32-bit ARM Cortex-M4F core with FPU, featuring single-cycle hardware multiplication and division instructions, and supporting DSP instructions and MPU
 - Built-in 16 KB instruction Cache and 16 KB data Cache with parity check, supporting zero-wait execution of programs via the Flash accelerator unit
 - Maximum operating frequency of 300 MHz, delivering 375 DMIPS
- **Encrypted Memory**
 - On-chip Flash (2/4MB), supports encrypted storage and automatic program decryption during execution
 - 1504KB built-in SRAM, supports ECC verification
 - 1024KB TCM SRAM, configurable as D-TCM, I-TCM or SRAM
 - 480KB on-chip SRAM
 - 4KB Backup SRAM, supports ECC
- **Operating Modes**
 - Run mode
 - SLEEP mode: AXI enabled, AHB enabled

- Stop0 mode: SRAM, TCM, RTC, LSE, IWDG enabled
- Stop2 mode: Flash standby mode, SRAM, TCM, RTC, LSE, IWDG, Backup SRAM, backup registers enabled, I/O maintained
- Standby mode: Backup SRAM, RTC, IWDG, LSE, backup registers enabled, SRAM, TCM disabled
- VBAT mode: Backup SRAM, RTC, LSE, backup registers enabled
- **Clock**
 - 4MHz~48MHz external high-speed crystal
 - 4MHz~50MHz external clock input
 - 32.768KHz external low-speed crystal
 - Built-in 3 high-speed PLLs
 - Built-in MSI clock, supporting configuration of 31.25K/62.5K/125K/250K/500K/1M/2M/4M/8M/16MHz clocks
 - Internal high-speed RC 64MHz
 - Internal low-speed RC 32KHz
- **Reset**
 - Supports power-on/power-down/external pin reset
 - Supports watchdog reset and software system reset
 - Supports programmable voltage detection
- **High-Speed Communication Interfaces**
 - 8 USART interfaces/7 UART interfaces, supporting ISO7816, IrDA, LIN
 - 2 LPUART interfaces
 - 7 SPI interfaces, supporting master/slave modes, rates up to 50 MHz
 - 10 I2C interfaces, rates up to 3.4 MHz, configurable master/slave modes, dual address response in slave mode
 - 2 USBHS Dual Role interfaces
 - 8 CAN-FD bus interfaces
 - 2 Ethernet MAC interface, ETH1 supports 10M/100M/1000M communication rates, ETH2 supports 10M/100M communication rates. Supports IEEE1588 time synchronization protocol
- **High-Performance Analog Interfaces**
 - 3 12-bit 5Msps ADCs, supporting 12-bit, 10-bit resolution, hardware oversampling up to 16-bit, supporting single-ended and differential modes
 - 4 high-speed analog comparators
 - 6 12-bit DACs, of which 2 1Msps DACs support output with or without Buffer separately, internal output only supports mode without Buffer; simultaneous internal and external output must enable Buffer; the other 2 DACs only support 1 output channel to the internal chip, with 15Msps sampling rate, supporting internal output without Buffer
 - 2 MCO outputs, configurable to output SYSCLK, HSE, MSI, LSE, LSI, HSI64 or PLL clock division
 - Supports 1 reference voltage VREFBUF (configurable as 1.5V/1.8V/2.048V/2.5V)

- 1 temperature sensor
- **Audio Interfaces**
 - 4 I2S, supporting half/full-duplex modes audio sampling frequencies from 8KHz to 192KHz
 - 8 PDM digital microphone interfaces built into DSMU
- **Memory Extension Interfaces**
 - 1 FEMC (Flexible External Memory Controller) interface, bus rate 100 MHz, SRAM/PSRAM/Nor Flash supporting configurable 16/32-bit data width, NAND Flash supporting configurable 8/16-bit data width
 - 1 xSPI interface, supporting 1/2/4/8-bit data width, configurable master/slave, rates up to 133 MHz, can be used for external SRAM, PSRAM and Flash, supports XIP
 - 1 SDRAM interface, rates up to 133 MHz
 - 2 SDMMC interfaces, supporting SD/SDIO 3.0, eMMC 4.51 format, rates up to 104MHz
- **Image Processing Interfaces**
 - 2 digital camera interface (DVP), supporting 8/10/12/16bit, rates up to 110MHz
 - 1 MIPI Display Serial Interface (DSI) controller with an integrated D-PHY
 - 1 TFT-LCD display interface, supporting up to 24-bit parallel digital RGB LCD, providing all signal interfaces, can directly connect to various LCD and TFT panels, resolution up to 1920x1080
 - Built-in 2.5D graphics processor, supporting image scaling, rotation, blending, anti-aliasing, texture mapping, etc.
 - Hardware JPEG codec
- **Maximum support for 168 GPIOs, low-speed GPIOs support 5V tolerance (under VDD = 3.3V ±10% conditions)**
- **Motor control Cordic accelerator, supporting trigonometric and hyperbolic function acceleration, supporting floating-point input and output**
- **Delta Sigma Module Unit (DSMU)**
- **Built-in filtering algorithm accelerator FMAC, supporting FIR, IIR filtering**
- **3 high-speed DMA controllers, each controller supporting 8 channels, 1 MDMA supporting 16 channels, freely configurable channel source and destination addresses**
- **RTC real-time clock, supporting leap year perpetual calendar, alarm events, periodic wake-up, supporting internal and external clock calibration**
- **Timer Counters**
 - 2 16bit super high-resolution timer (SHRTIM1/ SHRTIM2). Supports maximum control precision of 100ps, each super high-resolution timer counter consists of 1 master timer unit and 6 16-bit slave timer units. each timer unit has 2 independent channels. Supports 12 independent PWM outputs or 6 pairs of complementary PWM outputs.

- 4 16-bit advanced timer counters(ATIM1~4), supporting input capture, complementary output, quadrature encoding input and other functions, highest control precision 3.3ns; each timer has 6 independent channels, of which 4 channels support 4 pairs of complementary PWM outputs
- 10 16-bit general-purpose timers (GTIMA1~GTIMA7, GTIMB1~ GTIMB3), each timer with 4 independent channels, supporting input capture, output compare, PWM generation
- 4 32-bit basic timer counters (BTIM1~4)
- 5 16-bit low-power timers (LPTIM1~5), can work in Stop2 mode
- 2x 24-bit SysTick, 2x 14-bit window watchdog (WWDG), 2x 12-bit independent watchdog (IWDG)
- **Programming Methods**
 - Supports SWD/JTAG online debugging interface
 - Supports USB, USART Bootloader
- **Security Features**
 - FLASH has up to 4 encryption partitions, supporting storage encryption
 - Supports write protection (WRP), multiple levels of read protection (RDP) (L0/L1/L2)
 - Built-in password algorithm hardware acceleration engine, supporting AES/TDES, SHA, algorithms
 - TRNG true random number generator, CRC8/16/32 operations
 - Supports secure boot, encrypted program download, secure update, supports external high-speed and low-speed clock failure detection
 - Supports tamper detection
- **OTP supports 128-bit UCID**
- **Operating Conditions**
 - Operating voltage range:
 - 2.3V~3.6V
 - Chip junction temperature range: -40°C~125°C
- **Security Features**
 - USB IF
 - IEC61508 SIL2
- **Security Features**
 - BGA240+25(14mmx14mm)
- **Ordering Models**

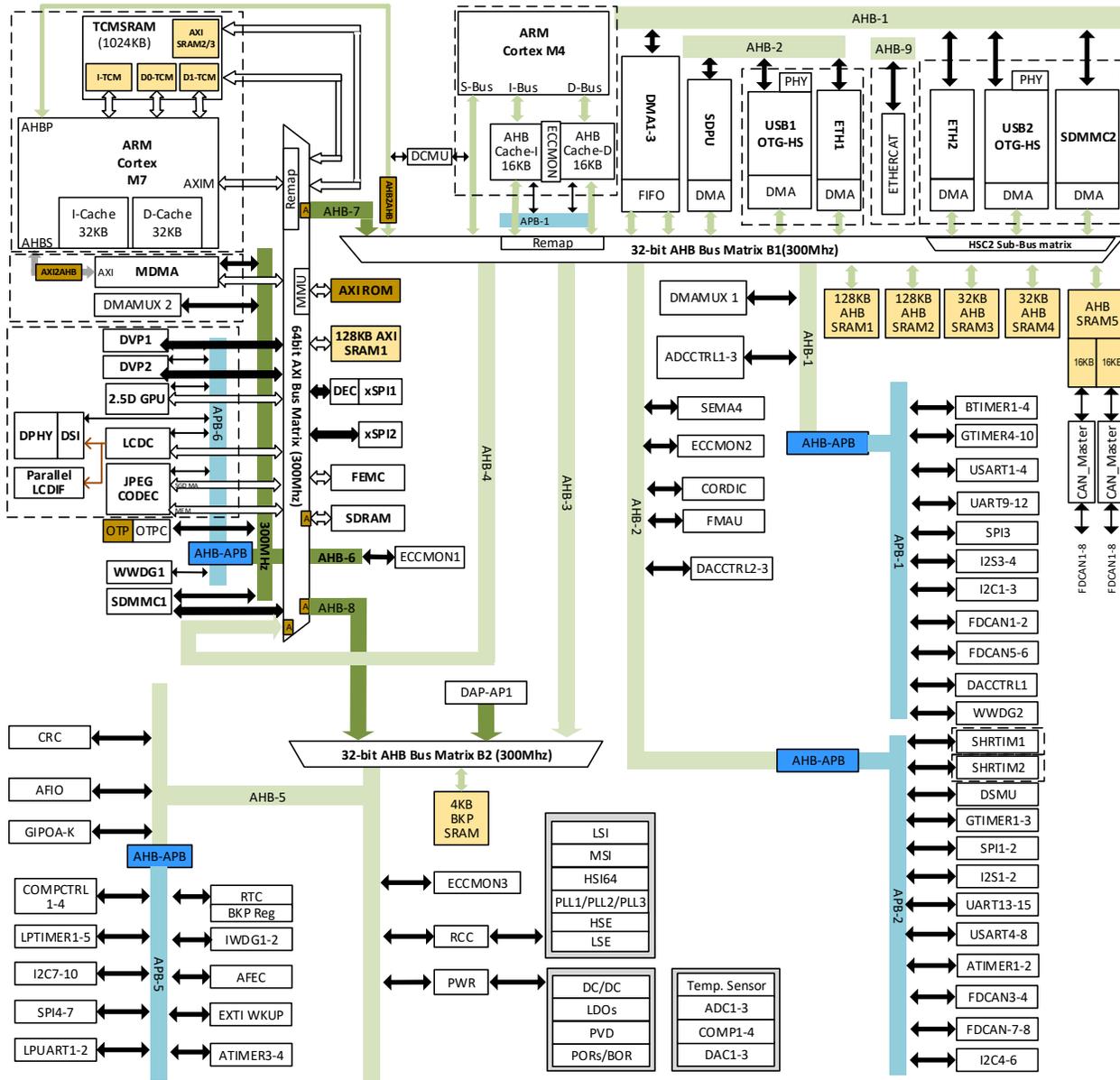
Series	Models
N32H787xxx7	N32H787XKB7, N32H787XIB7

1 Product Introduction

The N32H787 series uses a high-performance dual-core architecture, The ARM Cortex-M7 core serves as the main core, running at frequencies up to 600MHz, supporting double-precision floating-point operations and DSP instructions. The Cortex-M4 core serves as the auxiliary core with a maximum operating frequency of up to 300 MHz. It features (2/4MB) on-chip FLASH, integrates up to 1504KB of SRAM (including 1024KB TCM SRAM and 480KB SRAM) + 4KB Backup SRAM. It includes 3 12-bit 5MSPS ADCs, 4 high-speed comparators, 4 12-bit DACs, and integrates multiple high-speed communication interfaces: U(S)ART, I2C, xSPI, SPI, USBHS Dual Role, CAN-FD, SDRAM, FEMC, SDMMC, and 10/100/1000M Ethernet. The series supports digital camera interface (DVP), MIPI, TFT-LCD graphical interface, JPEG hardware codec and GPU. It features a built-in high-performance encryption algorithm hardware acceleration engine, supporting AES/TDES, SHA, algorithms, TRNG true random number generator, and CRC8/16/32. It supports up to 168 GPIOs, and is available in BGA240+25 packages.

The N32H787 series products can operate stably in a temperature range of -40°C to +105°C, with a supply voltage of 2.3V to 3.6V, offering multiple power consumption modes.

Figure 1-1 shows the bus diagram of this series of products.

Figure 1-1 N32H787 System Block Diagram


Note: This block diagram labels all peripheral resources. For detailed resource information of each series, please refer to Section 1.1.

1.1 Device Overview

Table 1-1 N32H787 Series Resource Configuration

Device Model		N32H787XKB7	N32H787XIB7
Flash (KB)		4096	2048
SRAM (KB)	TCM	1024 ⁽¹⁾	
	System RAM	480	
	Backup RAM	4	
Core	M7	600MHz	
	M4	300MHz	
Operating Voltage		2.3V~3.6V	
DCDC (step-down)		Yes	
Co-processor	Cordic	Yes	
	DSMU	Yes	
	FMAC	Yes	
Timers	SHRTIM	2	
	ADTIM	4*16bit ⁽²⁾	
	GPTIM	10*16bit	
	BSTIM	4*32bit	
	LPTIM	5*16bit	
	SysTick timer	2	
	WWDG	2*14bit	
	IWDG	2*12bit	
	RTC	Yes	
Communication Interfaces	SPI/I2S	7/4 ⁽³⁾	
	I2C	10 ⁽⁴⁾	
	USART	8 ⁽⁵⁾	
	UART	7 ⁽⁶⁾	
	LPUART	2	
	USBHS Dual Role	2	
	CAN FD	8 ⁽⁷⁾	
	10/100M ETH	2 ⁽⁸⁾	
	10/100/1000M ETH	1 ⁽⁸⁾	
Extended memory	SDRAM	Yes	
	xSPI	1 ⁽⁹⁾	
	FEMC	Yes	
	SDMMC	2	
Analog	12bit ADC	3	
	12bit DAC Number of channels	2+4 ⁽¹⁰⁾ 2 External channels	
	Comparators	4	
	VREFBUF	Yes	
Imaging	LCDC	Yes	

	MIPI	Yes
	GPU	Yes
	JPEG	Yes
	DVP	2
GPIO		168
DMA Number of channels		3 24Channel
MDMA Number of channels		1 16Channel
Algorithm support		DES/3DES, AES, SHA1/SHA224/SHA256, CRC8/16/CRC32
Security Protection		Read/write protection (RDP/WRP), storage encryption, secure boot
Packages		BGA240+25(14mm x 14mm)

Note:

1. SRAM is enabled by default upon power-on, and users can independently configure the size allocation of ITCM, DTCM and SRAM.
2. ATIM interfaces: ATIM1~4
3. SPI interfaces: SPI1~7; I2S interfaces: I2S1~4
4. I2C interfaces: I2C1~10
5. USART interfaces: USART1~8
6. UART interfaces: UART9~15
7. FDCAN interfaces: FDCAN1~8
8. ETH1 supports 10M/100M/1000M; ETH2 supports 10M/100M
9. xSPI interface: xSPI2
10. The 4 DACs only support internal connection and cannot output to GPIOs.

2 Functional Overview

2.1 Processor Core

N32H787 series devices are based on the high-performance Arm® Cortex®-M7 and Cortex®-M4 32-bit RISC core. Cortex®-M7 core operating frequency reaches up to 600 MHz, Cortex®-M4 core operating frequency reaches up to 300 MHz. The two core supports floating-point unit (FPU), Arm® single-precision and double-precision(only Cortex®-M7 core) operations and conversions (IEEE 754 compatible), includes a complete set of DSP instructions and memory protection unit (MPU) to enhance application security.

2.1.1 Arm® Cortex®-M7

Arm® Cortex®-M7 is a high-performance processor, its performance is nearly twice that of the Arm® Cortex®-M4. It features a 6-stage superscalar pipeline with an FPU capable of both single-precision and double-precision operations. Instruction and data buses are extended to 64-bit width.

The processor supports the following interfaces:

- 64-bit AXI4 interface
- 32-bit AHB master interface
- 32-bit AHB slave interface
- 64-bit instruction TCM interface
- 2x32-bit data TCM interfaces

Other processor features include:

- 32kB instruction Cache, 32kB data Cache, all Cache memory is protected by ECC
- Memory Protection Unit (MPU), configurable with up to 16 memory protection regions
- Double-precision and single-precision floating-point FPU
- ETM support
- Efficient DSP instructions

2.1.2 Arm® Cortex®-M4

The Arm® Cortex®-M4 is a high-performance 32-bit RISC (Reduced Instruction Set Computer) core with a maximum operating frequency of up to 300 MHz. This core enhances computing capabilities and supports single-precision floating-point operations, DSP instructions, and parallel computing, making it capable of meeting the requirements of hybrid applications involving efficient control and signal processing.

Key features of the processor include:

- Three-stage pipeline
- Harvard bus architecture
- 16 KB instruction cache and 16 KB data cache, with all cache memory protected by ECC
- Single-precision floating-point unit (FPU)

- High-efficiency DSP instructions

2.1.3 MPU

The MPU has configurable memory protection attributes. It allows the definition of up to 16 protected regions, which can be divided into up to 8 independent subregions, where region address, size, and attributes can be configured. Protection ranges from 32B to 4GB of addressable memory. When illegal access occurs, a memory management exception is generated.

2.2 Memory

N32H787 series devices feature on-chip Flash, configurable embedded SRAM, and external memory interfaces such as FEMC, SDRAM, and xSPI2. The configurable architecture provides flexibility to partition memory resources according to application needs, allowing appropriate performance trade-offs in terms of application code size, data size, and power saving. In addition, embedded ROM is used as the initial bootloader and for secure boot.

2.2.1 Embedded SRAM

TCM RAMs (only for Cortex-M7)

TCM RAM consists of 1MB SRAM, which can be configured as ITCM-RAM, DTCM-RAM and AXI-SRAM2/3. Software can flexibly configure D-TCM and I-TCM sizes, with the remaining SRAM automatically configured as AXI-SRAM2/3, in granularity of 128KB. ITCM RAM is mapped to address 0x0000 0000, and can only be accessed by the Cortex®-M7 CPU and MDMA (even when the CPU is in sleep mode). DTCM RAM is mapped at address 0x2000 0000, and can also only be accessed through the Cortex®-M7 CPU core and MDMA.

AXI SRAM

Up to 1152KB of AXI RAM, which can be accessed by byte (8-bit), half-word (16-bit), word (32-bit) or double word (64-bit). AXI SRAM is divided into the following types:

- 128KB of AXI SRAM 1 mapped to address 0x2400 0000
- Up to 512KB of AXI RAM 2 (shared with ITCM and DTCM), mapped to address 0x2402 0000
- Up to 512KB of AXI RAM 3 (shared with ITCM and DTCM), mapped to address 0x240A 0000

AHB SRAM

Up to 352KB of AHB SRAM1-5, which can be accessed by byte, half-word (16-bit) or word (32-bit). AHB SRAM is divided into the following types:

- 128 KB of AHB SRAM1 mapped to address 0x3000 0000
- 128 KB of AHB SRAM2 mapped to address 0x3002 0000
- 32 KB of AHB SRAM3 mapped to address 0x3004 0000
- 32 KB of AHB SRAM4 mapped to address 0x3004 8000
- 32 KB of AHB SRAM5 mapped to address 0x3005 0000

AHB SRAM 5 is divided into two blocks, shared with CANFD1-8, used as CANFD data frame buffer.

Backup SRAM

Backup SRAM is located in AHB bus domain 2, mapped to address 0x3800 0000, and can be accessed by byte, half-word (16-bit) or word (32-bit).

Error Correction Code (ECC)

All internal system RAM includes error correction code (ECC). It can be programmatically configured through their respective ECC monitor (ECCMON) modules. The ECC mechanism is based on the SECDED algorithm, supporting single-bit and double-bit error detection as well as single-bit error correction.

SRAM data protection with ECC:

- 7 ECC bits added for each 32-bit word
- For ITCM-RAM and AXI_SRAM1, 8 ECC bits added for each 64-bit word

2.2.2 Embedded ROM

The N32H787 series devices have a 32KB embedded ROM, mapped to address 0x1FFF0000. It contains a small bootloader, which is divided into two parts: secure code and API. The secure code can only be accessed by the Cortex-M7, while the API can be called by the core CPU.

2.2.3 On-Chip Flash

The maximum capacity of the on-chip Flash is 4MB. The first 128KB is used for BOOTPATCH and option bytes, and the remaining space is used for user application code. When operating in XIP mode, the on-chip Flash supports real-time decryption of AES128 through the RTAD module. The decryption applies to any data stored in Flash.

2.3 System Boot Modes

By default, the system boots to the Cortex®-M7 after reset, The Cortex®-M4 is activated by the Cortex®-M7 application as required. The BOOTROM program supports two modes: Boot Application and Serial Download. These modes can be selected via the Boot pins and option bytes:

- **Boot Application:** After the BOOTROM program runs normally, the application image is launched from the internal Flash/TCM/SRAM based on the BOOTADDR_M7 value in the option bytes.
- **Serial Download:** The BOOTROM program receives the application image via USART1 or USB1 and stores it in internal Flash/TCM/SRAM.

Table 2-1 Boot mode

BOOT pin	Option Bytes (OTP_SYS_CFG_BTM)	Mode	Description
0	!0x5AA5 and !0x4884	Boot Application	boot from on-chip Flash/TCM/SRAM
1	!0x5AA5 and !0x4884	Serial Download	Built communication with Host by UART or USB
*	0x5AA5	Boot Application	boot from on-chip Flash/TCM/SRAM
*	0x4884	Serial Download	Built communication with Host by UART or USB

2.4 Power Supply Scheme

External Power Supplies:

VDD, VDDA, VREF, VBAT, VDDSMPS, VDDLDO, VDD33USB, VDDDSI.

- **VDD** is the main chip power supply, primarily powering the power system and clock system.
- **VDDA** is the analog peripheral power supply, mainly supplying power to analog peripherals.
- **VREF** provides a reference voltage to analog peripherals for higher accuracy.
- **VBAT** connects to a battery and supplies power to the backup domain.
- **VDDSMPS** is the power input for the DC-DC SMPS (Switched-Mode Power Supply).
- **VDDLDO** powers the main LDO (Low Dropout Regulator), supported only on applicable models; otherwise, it is left NC (not connected).
- **VDD33USB** powers the USB PHY.

There are five power domains, each supplied by an external power source for different regions:

- **VDD Domain:**
Voltage range: 2.3V to 3.63V.
Powers: SMPS, Main LDO, most GPIOs, HSE, HSI, PLL, POR/PDR, BOR, PVD, USB PHY, DSI PHY etc.
- **VDDA Domain:**
Voltage range: 2.3V to 3.63V.
Powers: ADC, DAC, COMP, VREFBUF, TS, etc.
- **VDDBK Domain:**
Voltage range: 2.3V to 3.63V.
Powers: WKUP pins, NRST, PC13/14/15, LSE, LSI, etc.
- **VDDD Domain:**
Voltage: 0.9V~0.99V.
Powers: CPU, SRAM, RCC, TRNG, USB PHY digital section, DSI PHY digital section and most peripherals.
The VDDD domain is subdivided into VDDDRET and VDDDMAN subdomains:

- **VDDDRET Domain:**
Powers LPUART, LPTIMER, EXTI, etc., with power supplied from VDDD and controlled by a separate power switch.
- **VDDDMAN Domain:**
Directly powers buses (AXI, AHB, APB), bus adapters, low-speed communication interfaces (SPI, I2C, UART), timers (ATIMER, GTIMER, BTIMER), and includes the following subdomains:
 - **CM7 Subdomain:** Contains CM7 core, TCM memory, and its controller.
 - **MDMA Subdomain:** Contains the MDMA.
 - **HRTIM1 Subdomain:** Contains the digital circuit of HRTIMER 1.
 - **HRTIM2 Subdomain:** Contains the digital circuit of HRTIMER 2.
 - **HRTIMAFE Subdomain:** Contains the shared analog front end for HRTIMER1 and HRTIMER2.
 - **HSC1 Subdomain:** Contains high-speed communication interfaces USB1 and Ethernet 1.
 - **HSC2 Subdomain:** Contains USB2, Ethernet 2, and SDMMC2.
 - **GRAPHICS Subdomain:** Contains GPU, DVP1, DVP2, LCDC, JPEG CODEC and MIPI-DSI modules.

Except for the CM7 core subdomain, which is controlled by hardware, all other subdomain power switches are controlled by software.

- **VDDDBK Domain:**
Voltage: 0.9V~0.99V.
Powers: PWR, Backup SRAM, RTC, WKUP pins, NRST, PC13/14/15, backup IOM, IWDG, RCC_BKP, and backup registers.

2.5 Reset

An internal Power-On Reset (POR) and Power-Down Reset (PDR) circuit is integrated. This circuit remains active at all times, ensuring that the system operates correctly when the supply voltage exceeds 2.3V.

When VDD falls below the defined threshold (VPOR/PDR), the device is forced into a reset state, eliminating the need for an external reset circuit.

2.6 Programmable Voltage Detector

A Programmable Voltage Detector (PVD) is built in. It monitors the VDD power supply and compares it with a threshold voltage V_{PVD} . When V_{DD} drops below or rises above V_{PVD} , an interrupt is generated. The interrupt handler can then issue a warning. The PVD feature must be enabled by software. For specific values of $V_{POR/PDR}$ and V_{PVD} , refer to Table 4-9.

2.7 Low Power Modes

The N32H787 supports five low-power modes:

- SLEEP Mode

In SLEEP mode, only the CPU is stopped. All peripherals remain operational and can wake the CPU through interrupts or events.

- STOP0 Mode

STOP0 is based on the Cortex-M7F deep sleep mode. It allows lower power consumption while maintaining the contents of SRAM and registers. In this mode, all high-speed clocks such as PLL, HSI, and HSE are turned off. Wake-up sources: Any signal configured as EXTI (external interrupt), including 16 external EXTI lines (I/O-related), PVD output, LPTIMER, LPUART, RTC wake-up, or RTC alarm.

- STOP2 Mode

STOP2 mode is based on the Cortex-M7F deep sleep mode. In this mode:

- CPU internal registers are retained, and the contents of the TCM or SRAM used by the running program are not lost.
- The main power domain (VDDDMAN) is powered down, which helps achieve lower power consumption compared to STOP0 mode.
- All high-speed clocks in the main domain, such as PLL, HSI, and HSE, are shut down.
- The retention domain (VDDDRET) remains powered, allowing peripherals like LPUART and LPTIMER to operate using low-speed clocks (LSE or LSI).
- The backup domain (VDDDBKP) is also powered, so peripherals such as RTC and IWDG can function normally.

- STANDBY Mode

- STANDBY mode achieves the lowest power consumption among all low-power modes:
- The internal voltage regulator is turned off.
- Oscillators such as PLL, HSI RC oscillator, and HSE crystal oscillator are shut down.
- The retention domain (VDDDRET) is powered down, so most register contents are lost.
- Backup registers are retained, and backup SRAM can optionally be retained.
- The backup domain (VDDDBKP) circuitry remains operational.

- Wake-up sources include:

- External reset signal on the NRST pin
- IWDG (Independent Watchdog) reset
- Edge on the WKUP pin
- RTC wake-up event or RTC alarm

- VBAT Mode

VBAT mode is entered automatically whenever VDD is powered down but VBAT is still supplied.

In VBAT mode, most I/O pins enter high-impedance state, except: NRST, WKUP, PC13_TAMPER, PC14, PC15

Wake-up condition: Power-up on VDD

2.8 Reset and Clock Control (RCC)

The RCC manages the generation of all clocks, clock gating, and the control of system and peripheral resets. It provides high flexibility in the selection of clock sources and allows the application of clock ratios to optimize power consumption.

2.8.1 Clock Management

The device integrates three internal oscillators, two oscillators with external crystal or resonator, and four PLLs.

The RCC (Reset and Clock Control) has the following clock source inputs:

- **HSI64:** 64 MHz internal high-speed oscillator
The control logic of this oscillator resides in the standby power domain. After initial power-on and upon wake-up from low-power modes (STOP0, STOP2, and STANDBY), this clock is used as the **default system clock**.
- **MSI:** 16 MHz medium-speed oscillator
The control logic of this oscillator resides in the retention power domain. In STOP2 power mode, this clock is used as a high-speed clock by peripherals in the retention domain. It can also be selected as a system clock and core clock for certain peripherals.
- **HSE:** 4 ~ 48 MHz external high-speed oscillator
The control logic of this oscillator resides in the core power domain. This clock can be selected as the system clock, peripheral core clock, or reference clock for certain PHYs (e.g., USB, DIS...).
- **LSI:** 32 kHz internal low-speed oscillator
The control logic of this oscillator resides in the standby power domain. It is the first clock switched to during system power-on and is used by the PWR block in the standby domain to start up the system and wake it from standby and STOP2 modes. It is also used by peripherals in the standby and retention power domains.
- **LSE:** 32.768 kHz external low-speed oscillator
The control logic of this oscillator resides in the standby power domain. It provides a **low-power and accurate clock** to peripherals in the standby and retention power domains.
- **PLL:** 400 MHz ~ 1.25 GHz Phase-Locked Loops
The control logic of the PLLs resides in the core power domain. HSI64, MSI, and HSE can be configured as the input clock source for the PLLs:
 - PLL1: Maximum frequency 800 MHz, used by some peripherals as a system clock source and core clock source.
 - PLL2: Maximum frequency 800 MHz, used by some peripherals as a system clock source and core clock source.
 - PLL3: Maximum frequency 800 MHz, used by some peripherals as a core clock source.
 - SHRPLL: maximum frequency is 1.25 GHz, this PLL is used by the SHRTIMER peripheral as the core clock source.

The clock outputs of PLL1, PLL2, and PLL3 are further divided by configurable digital dividers, and then used as system clocks or peripheral core clocks. The SHRPLL clock output is divided by 4 within the AFE, generating a 312.5 MHz clock for the SHRTIMER peripheral.

2.8.2 System Reset Sources

A system reset resets all registers to their reset values, except for reset flags in the reset status register and certain registers in the standby domain (these registers can only be reset by programming the BDRST register and by a standby domain POR reset).

System resets can originate from the following sources:

- POR
- NRST pin.
- IWDG and WWDG reset requests.
- Reset request from the CPU.
- EMC reset request.
- Low-power reset request from PWR.
- BOR reset (Brown-Out Reset).
- MMU reset request

2.9 SEMA4

The hardware semaphore module provides 32 (32-bit) register-based semaphores. Semaphores can be used to ensure synchronization between different processes running on the cores. SEMA4 offers a non-blocking mechanism to atomically lock semaphores. It provides the following functions:

- Semaphores can be locked in two ways:
 - Two-step locking: Write COREID and PROCID to the semaphore, then perform a read check
 - One-step locking: Read COREID from the semaphore
- Generate an interrupt when a semaphore is released
 - Each semaphore can generate one interrupt
- Semaphore clear protection
 - A semaphore can only be cleared when COREID matches PROCID
- Clear global semaphores based on COREID

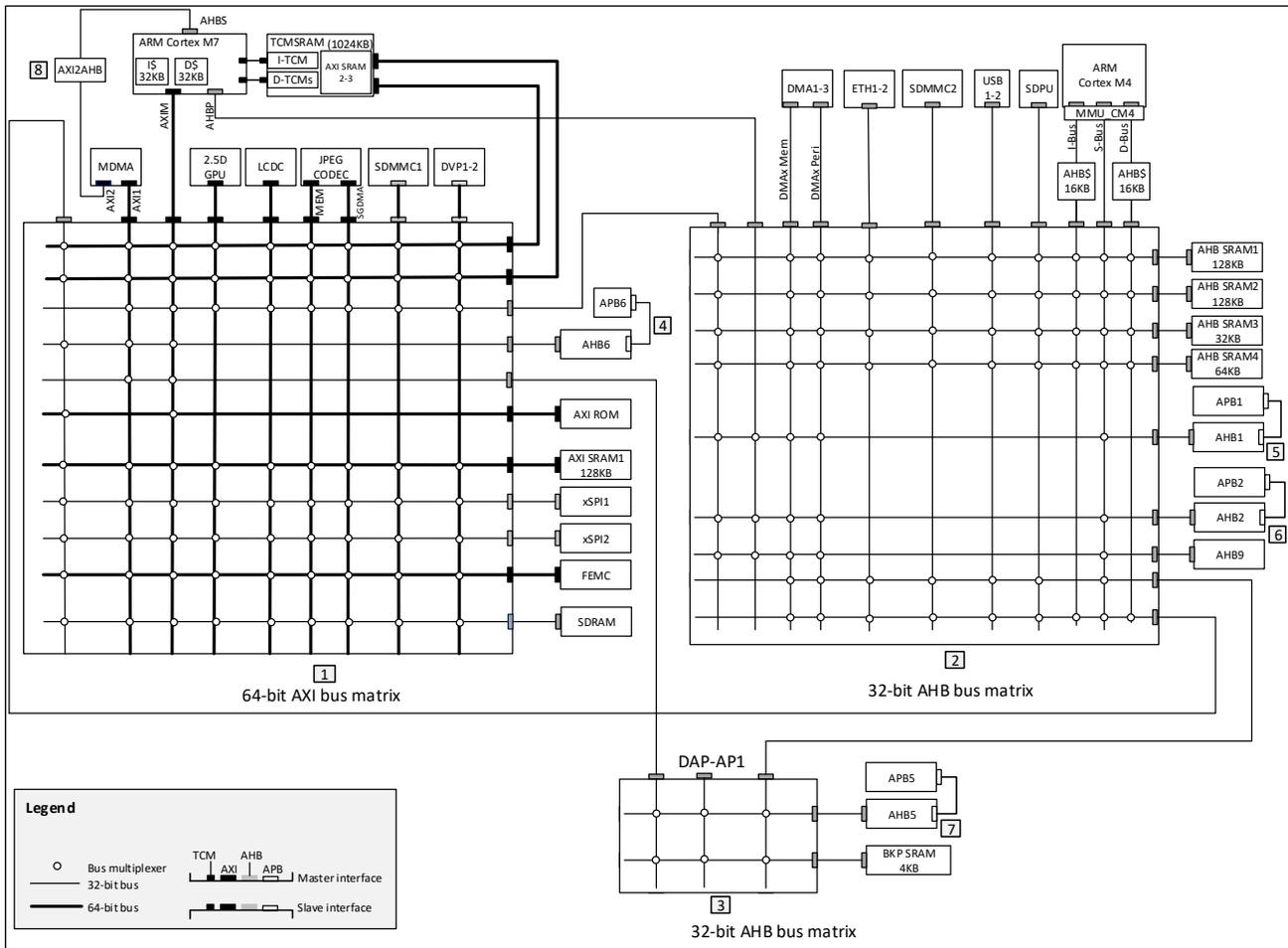
SEMA4 includes the following features:

- 32 (32-bit) semaphores
- 8-bit ProcessID
- 4-bit MasterID
- 1 interrupt line
- Lock indication

2.10 Bus Interconnect Matrix

These devices feature one AXI bus matrix, two AHB bus matrices, and bus bridges, enabling interconnection between bus masters and bus slaves.

Figure 2-1 Bus Matrix Architecture



2.11 General-Purpose Input/Output Interface (GPIO) and Alternate Function Interface (AFIO)

GPIO refers to General-Purpose Input/Output interface, and AFIO refers to Alternate Function Interface. The chip supports up to 168 GPIO pins, which are divided into 11 groups (GPIOA/GPIOB/GPIOC/GPIOD/GPIOE/GPIOF/GPIOG/GPIOH/GPIOI/GPIOJ/GPIOK). Each group has 16 ports (Group K has a total of 8 ports). GPIO ports share pins with other alternate peripheral functions. Users can configure them flexibly according to requirements. Each GPIO pin can be independently configured as output (push-pull or open-drain), input (floating, pull-up, or pull-down), or alternate peripheral function port. Except for analog function pins, other GPIO pins have high current-carrying capacity.

GPIO ports have the following characteristics:

- Each GPIO port can be individually configured by software into the following modes:
 - Floating input
 - Pull-up input
 - Pull-down input
 - Analog function
 - Open-drain output, with configurable pull-up/pull-down
 - Push-pull output, with configurable pull-up/pull-down
 - Push-pull alternate function, with configurable pull-up/pull-down
 - Open-drain alternate function, with configurable pull-up/pull-down
- Independent set or clear functions
- All IOs support external interrupts
- All IOs support low-power mode wake-up, with configurable rising or falling edge
 - 16 EXTIs are available for STOP0 mode wake-up, all IOs can be multiplexed as EXTI
 - PA0/PA2/PC1/PC13/PI8/PI11 can be used for STANDBY mode wake-up
- Support for software remapping of IO alternate functions
- Support for GPIO locking mechanism, which can only be cleared by reset after locking

Each I/O port bit can be programmed arbitrarily through the AHB interface, but I/O port registers must be accessed as 32-bit words, 16-bit half-words, or 8-bit bytes (AFIO registers only support 32-bit word access).

2.12 Nested Vectored Interrupt Controller (NVIC)

The device has an embedded Nested Vectored Interrupt Controller (NVIC).

The NVIC includes the following features:

- 234 maskable interrupt channels
- 16 programmable priority levels

2.13 External Interrupt/Event Controller (EXTI)

外 The External Interrupt/Event Controller (EXTI) controls wake-up through configurable and direct event inputs from on-chip peripherals or external outputs. It sends wake-up events to the PWR and transmits interrupt and event signals to both CPUs.

EXTI wake-up requests allow the system to wake up from STOP0 and STOP2 modes, and can also wake up CPUs from CSLEEP, CSTOP0, and CSTOP2 modes. Interrupt requests and event requests can also be used in Run mode.

The EXTI includes the following features:

- Wakes up the system from CSTOP0 and CSTOP2 modes
- Generates interrupts and events for transmission to CPUs

These requests can be generated from the following event inputs:

- Direct events (generated by on-chip peripherals, event flags are stored or cleared in the source peripheral, not in the EXTI) have the following characteristics:
 - Fixed rising edge triggering
 - Have interrupt and event mask bits
- Configurable events (generated from external devices or on-chip peripherals, only producing pulse events) have the following characteristics:
 - Software triggering
 - Configurable rising edge and falling edge
 - Have interrupt and event mask bits

2.14 DMA Request Multiplexer (DMAMUX)

Peripherals indicate the presence of a DMA transfer request by setting their DMA request signal. The DMA controller processes the DMA request and generates a DMA acknowledgment signal, and the corresponding DMA request signal will also become invalid, but the DMA request remains pending until then.

The DMAMUX request multiplexer can reconfigure (route) DMA request lines between the product's peripherals and the DMA controller. This routing function is ensured through a programmable multi-channel DMA request line multiplexer. Each channel can select a DMA request line without restrictions, or select a DMA request line in synchronization with events from its DMAMUX synchronization input. Additionally, the DMAMUX can also be used as a DMA request generator for programmable events of its input trigger signals.

The main features are as follows:

Table 2-2 DMAMUX Input/Output

Feature	DMAMUX1	DMAMUX2
Number of DMAMUX synchronization inputs	9	1 (internal use or unused)
Number of DMAMUX peripheral requests	210	4
Number of DMAMUX request trigger inputs	26	38
Number of DMAMUX request generator channels	8	16
Number of DMAMUX output request channels	24	16

- Each DMA request generator channel has:
 - DMA request trigger input selector
 - DMA request counter
 - Event overflow flag for the selected DMA request trigger input
- Each DMA request multiplexer channel output has:
 - Up to 210 input DMA request lines from peripherals
 - Up to 3 DMA request line outputs
 - Synchronization input selector
 - DMA request counter
 - Event overflow flag for the selected synchronization input
 - An event output for DMA request linking
- AHB slave interface, burst not supported, only 32-bit access
- DMAMUX overflow interrupt

2.15 DMA Controller (DMA)

The DMA controller is controlled by the CPU and can perform fast data transfers from source to destination. Once configured, data transfers occur without CPU intervention. This frees the CPU to perform other computational/control tasks or reduce the system's overall power consumption.

The chip has three DMA controllers (DMA1, DMA2, DMA3), each with 8 logical channels. Each logical channel processes memory access requests from one or more peripherals. An internal arbiter controls the priority of different DMA channels.

The main features are as follows:

General Features

- Compliant with AMBA 2.0 standard
- AHB slave interface for DMA programming
- Channels
 - Up to eight channels, one channel per source and destination
 - Unidirectional channels—data transfer in one direction only
 - Programmable channel priority
- AHB master interface
 - Up to four independent AHB master interfaces, allowing:**
 - Up to four simultaneous DMA transfers
 - Masters can be located on different AHB layers (multi-layer support)
 - Source and destination can be on different AHB layers (pseudo fly-by performance)
 - Configurable data bus width for each AHB master interface (up to 256 bits)
 - Configurable byte ordering for master interfaces
- Transfers
 - Support for memory-to-memory, memory-to-peripheral, peripheral-to-memory, and peripheral-to-peripheral DMA transfers
 - DMA transfers between APB peripherals via the APB bridge
- Configurable identification registers
- Component ID parameters for configurable software driver support
- Configuration for DesignWare AHB Lite systems
- Last beat DMA burst indication
- Support for little-endian, address-invariant (AI) big-endian scheme, and BE-32 (word-invariant) scheme for data access on AHB slave interface and each AHB master interface
- Arbitration scheme to determine which request line gets access to a specific master bus interface

Address Generation

- Programmable source and destination addresses (on AHB bus)
- Address increment, decrement, or fixed
- Multi-block transfers implemented through:
 - Linked list (block chaining)
 - Automatic reload of channel registers
 - Contiguous addressing between blocks
- Independent source and destination selection for multi-block transfer types
- Scatter/gather

Channel Buffering

- Single FIFO per channel for source and destination
- Configurable FIFO depth
- D flip-flop-based FIFO
- Automatic data packing or unpacking to accommodate FIFO width

Channel Control

- Programmable source and destination for each channel
- Programmable transfer type per channel (memory-to-memory, memory-to-peripheral, peripheral-to-memory, peripheral-to-peripheral)
- Programmable burst transaction size per channel
- Programmable enable and disable of DMA channels
- Support for disabling channels without losing data
- Support for pausing DMA operations
- Support for RETRY, SPLIT, and ERROR responses
- Programmable maximum burst transfer size per channel
- Configurable maximum transaction size
- Configurable maximum block size
- Bus locking—programmable at transaction, block, or DMA transfer level
- Channel locking—programmable at transaction, block, or DMA transfer level
- Hardcoded multi-block transfer type options
- Option to disable writeback of channel control registers at end of each block transfer

Transfer Initiation

- Handshaking interface for source and destination peripherals (up to 8)
 - Hardware handshaking interface
 - Software handshaking interface
 - Peripheral interrupt handshaking interface

- Handshaking interface supports single or burst DMA transactions
- Polarity control for hardware handshaking interface
- Enable and disable individual DMA handshaking interfaces

Flow Control

- Programmable flow control at block transfer level (source, destination, or DMA controller)
- Software control of source data prefetch when destination is the flow controller

Interrupts

- Consolidated and separate interrupt requests
- Interrupts occur when:
 - DMA transfer (multi-block) completes
 - Block transfer completes
 - Single and burst transactions complete
 - Error conditions
- Support for interrupt enabling and masking

Low Power Modes

- Global clock gating
- Channel-specific clock gating

2.16 MDMA Controller (MDMA)

MDMA is a highly configurable, highly programmable, high-performance, multi-master multi-channel DMA controller that uses AXI as the data transfer bus interface.

The main features are as follows:

General Features

- Independent core, slave interface, and master interface clocks
- Up to 24 channels, one channel per source and destination
- Unidirectional data transfers only (each channel is unidirectional)
- Up to two AXI master interfaces:
 - Two master interfaces supporting multiple layers
 - Multiple AXI master interfaces can connect directly to peripherals on different AXI interconnects, improving bus performance
 - Support for different ACLK on different AMBA layers
- Memory-to-memory, memory-to-peripheral, peripheral-to-memory, and peripheral-to-peripheral DMA transfers
- Separate external memory interface (per channel) for connecting SRAM or register file-based memory to channel FIFO
- AMBA 3 AXI/AMBA 4 AXI compatible master interfaces
- AHB/APB4 slave interface for DMA controller programming
 - AHB slave interface supports only single transfers (hburst = 3'b000)
- AXI master data bus width up to 512 bits (applicable to both AXI master interfaces)
- Static or dynamic selection of endian mode for AXI master interfaces
- Input pins for dynamic endian selection
- Configurable independent control of endian mode for linked list access on master interfaces
- Optional identification registers
- Support for channel locking
 - Support for internal channel arbitration locking the master bus interface at different transfer levels
- DMAC status indication output
 - Idle/busy indication
- DMA hold function
- Output pin indicating the last write transfer at DMA transaction level
- Multi-level DMA transfer hierarchy
 - DMA transfers divided into transaction level, block level, and complete DMA transfer level
- Support for AXI unaligned transfers
- Support for context-sensitive low-power options

- Support for unique ID functionality, generating AXI read/write transfers with unique IDs on AXI read/write channels

Channel Buffering

- One FIFO per channel
- FIFO depth
- Automatic packing/unpacking of data to accommodate FIFO width

Channel Control

- Programmable transfer type per channel (memory-to-memory, memory-to-peripheral, peripheral-to-memory, and peripheral-to-peripheral)
- Single or multiple DMA transactions
- Programmable multi-transaction size per channel
- Programmable maximum AMBA burst transfer size per channel
- Disabling channels without losing data
- Channel pause and resume
- Programmable channel priority
- Internal channel arbitration locking the master bus interface at different transfer levels
- Programmable multi-block transfers using linked lists, contiguous addressing, auto-reload, and shadow register methods
- Dynamic extension of linked lists
- Independent configuration of SRC/DST multi-block transfer types
- Multiple state machines, one each for SRC and DST per channel
- Independent state machines for data and LLI access
- Control signals such as cache and protection programmable for each DMA block
- Programmable transfer length (block length)
- Error status registers for debugging when errors occur

Flow Control

- Programmable flow control at DMA transfer level
 - DMA controller is the flow controller at DMA block transfer level if the size of the block transfer is known before DMA initialization
 - Either source peripheral or destination peripheral is the flow controller for undefined length (demand mode) DMA block transfers if the size of the DMA block transfer is not known before DMA initialization

Handshaking Interface

- Programmable software and hardware handshaking interfaces for non-memory peripherals
- Up to 64 hardware handshaking interfaces/peripherals

- Programmable mapping between enabling/disabling individual handshaking interface peripherals and channels; many-to-one mapping with only one peripheral active at a time
- Memory-mapped registers to control DMA transfers in software handshaking mode

Interrupt Outputs

- Consolidated and separate interrupt outputs
- Interrupt generation:
 - DMA transfer completion
 - Block transfer completion
 - Single or multiple transaction completion
 - Error conditions
 - Channel pause or disable
- Interrupt enabling and masking

Bus Interface

- Master interfaces using AMBA 3 AXI and AMBA 4 AXI protocols, slave interfaces using AHB, AXI4-Lite, and APB 3 protocols
- Data bus width up to 512 bits for master interfaces
- Outstanding transactions on master interfaces
- Setting outstanding transaction limits per channel on master interfaces
- Configurable AXI transfer width
- Out-of-order transaction support for different channels connected to the same master interface; transactions for a specific channel are always initiated in order
- Incremental and fixed address transfers on master interfaces
- Source address and destination address data transfers; must be aligned with respective transfer widths
- Data bus width of 32/64 bits for slave interfaces
- Transfer size (width) used by slave interfaces; must be the same as the data bus width

Security Features

- Parity protection feature for all common registers and channel-specific registers at interface level, with data integrity checking through parity
- Error Correction Code (ECC) protection feature correcting single-bit errors and detecting double-bit errors, enabled to prevent data corruption
 - ECC protection feature for FIFO memory interfaces
 - ECC protection feature for UID memory interfaces
 - ECC protection feature for AXI master interfaces
- Lock-step functionality for safety-critical applications, increasing security and reliability to withstand adverse operating conditions such as Single Event Upsets (SEU) and extreme EMI/EMC

2.17 AES Real-Time Decryption (RTAD)

Main features are as follows:

- Real-time 128-bit decryption (single or multiple) during XSPI memory-mapped read operations.
 - Uses AES in Counter (CTR) mode, with a key stream FIFO queue (depth = 4).
 - Supports any read size.
 - Physical address of the read is used for encryption/decryption.
 - Up to four independent encrypted regions.
 - Region definition granularity: 4096 bytes.
 - Region configuration write lock mechanism.
 - Two optional decryption modes: Execute-Only and Never-Execute.
 - Each region has its own 128-bit key, two-byte firmware version, and eight-byte application-defined nonce. At least one of these must change each time the application performs encryption.
- Confidentiality and integrity protection for encryption keys.
 - Write-only registers, with software lock mechanism.
 - 8-bit CRC provided as public key information.
- Supports xSPI prefetch mechanism.
- In Execute-Only mode, an enhanced encryption mode can be selected, adding a proprietary protection layer on top of the AES stream cipher.

AMBA AHB slave peripheral, accessible only through 32-bit word single accesses (otherwise an AHB bus error is generated, and write accesses are ignored).

2.18 SDRAM (Synchronous Dynamic Random Access Memory)

Supports an SDRAM controller connected to the AHB bus, capable of accessing up to two external SDRAM/LPSDRAM memory devices.

Main features are as follows:

- Two SDRAM memory devices that can be configured independently
- Data bus width of 8-bit, 16-bit, or 32-bit
- 13-bit row address, 11-bit column address, 4 internal memory banks: 4x16Mx32bit (256 MB), 4x16Mx16bit (128 MB), 4x16Mx8bit (64 MB)
- Configurable row address of 11-bit, 12-bit, or 13-bit; configurable column address of 8-bit, 9-bit, 10-bit, or 11-bit
- Supports word, half-word, and byte access
- Automatic row and bank boundary management
- Supports burst mode
- Write access protection
- Programmable timing parameters
- Supports software reset
- SDRAM power-up initialization via software
- CAS latency of 1, 2, 3
- Supports automatic refresh operations with programmable refresh rate
- Supports suspend and resume via software

2.19 Filter Algorithm Accelerator (FMAC)

The Filter Mathematics Acceleration Unit is used for arithmetic operations on vectors, including a multiplier, accumulator, and address generation logic capable of indexing vector elements in local memory. This unit supports input and output circular buffers to facilitate digital filters such as Finite Impulse Response (FIR) and Infinite Impulse Response (IIR).

The unit frees the processor from frequent or lengthy filtering operations, allowing it to perform other tasks. In many cases, it can accelerate such calculations compared to software implementations, thus speeding up time-critical tasks.

Main features are as follows:

- 16 x 16-bit multiplier
- 24 + 2-bit accumulator, with addition and subtraction capabilities
- 16-bit fixed-point input and output data
- 256 x 16-bit data buffer
- Up to three data buffers can be defined in memory (two inputs, one output), defined by programmable base address pointers and associated size registers
- Input and output buffers can be used cyclically
- Filter functions: FIR, IIR (direct form 1)
- Vector functions: dot product, convolution, correlation
- Supports DMA read and write operations

2.20 CORDIC Coprocessor (CORDIC)

The CORDIC hardware computation unit provides hardware acceleration for mathematical functions (primarily trigonometric functions). It is commonly used to accelerate mathematical function calculations in applications such as motor control, metering, and signal processing.

Main features are as follows:

- Supports rotation and vector calculation modes
- Supports circular and hyperbolic coordinate systems
- Once calculation begins, any read operation to result registers puts the bus in a wait state until calculation completes, allowing results to be read after completion without polling or interrupts
- Supports acceleration of 10 functions: sine, cosine, sinh, cosh, atan, atan2, atanh, modulus, square root, natural logarithm
- Supports fixed-point and floating-point data input/output modes
- Supports interrupt, polling, and DMA read/write modes
- Configurable iteration precision

2.21 Sigma-Delta Modulator Digital Filter Unit (DSMU)

The DSMU is a high-performance module for connecting external Σ - Δ modulators, featuring 8 external digital serial channels and 4 flexibly configurable Sigma-Delta digital filters that can provide up to 24-bit final ADC resolution. The external serial channels can be configured as SPI interfaces or Manchester-encoded single-wire interfaces (with configurable parameters) to accommodate various modulators. It also supports internal parallel data input channels for receiving 16-bit parallel data streams from ADC peripherals or device memory.

The DSMU can operate in single conversion mode or continuous mode and provides analog watchdogs with independently configurable digital filters, as well as short-circuit detection, extremum detection, and other functions. It also supports two power modes: normal mode and stop mode.

Main features of the DSMU are as follows:

- 8 configurable external digital serial input channels:
 - Supports SPI interface for connecting various Σ - Δ modulators
 - Supports Manchester-encoded single-wire interface
 - Supports output clock for external Σ - Δ modulators
- 8 internal digital parallel input channels:
 - Up to 16-bit resolution
 - Data sources: ADC data or memory (CPU/DMA) data stream
- 4 configurable data signal processing units:
 - 1 Sincx filter: filter order/type (1..5), oversampling ratio (up to 1..1024)
 - 1 integrator: oversampling ratio (1..256)
- Up to 24-bit signed data output
 - Final output data right-aligned (0..31 bits)
- Signed data output
- Automatic data offset correction (offset written by user to specified register)
- Supports continuous or single conversion
- Conversion start supports the following synchronization methods:
 - Software trigger
 - Internal timer
 - External event
 - Synchronized conversion with the first DSMU filter (DSMU_FLT0)
- Supports analog watchdog
 - Low and high thresholds can be configured separately
 - Supports independently configurable Sincx digital filter (filter order = 1..3, oversampling ratio = 1..32)
 - Configurable data source: output data register, one or more serial digital input channels

- Continuous data monitoring independent of normal conversion
- Supports short-circuit detector for detecting saturated analog input data (below negative threshold or above positive threshold)
 - 8-bit counter for detecting 1..256 consecutive 0s or 1s in the data stream
 - Continuous monitoring of each channel (8 serial channel transceiver outputs)
- Brake signal can be generated after analog watchdog events or short-circuit detection events
- Supports extremum detection
 - Automatic storage of maximum and minimum output data values
 - Software refresh
- Supports pulse jump function for beam-forming applications (similar to delay line)
- Supports DMA reading of conversion data
- Supports interrupts: end of conversion, out-of-bounds, analog watchdog, short circuit, channel clock missing
- Supports regular and injected conversions
 - Regular conversions can be performed at any time, even in continuous mode without affecting injected conversions
 - Injected conversions enable precise timing and have high priority

2.22 Real-Time Clock (RTC)

The RTC is a set of continuously running counters with an integrated calendar clock module that provides perpetual calendar functionality, along with alarm interrupts and periodic interrupt capabilities.

Main features are as follows:

- Real-Time Clock (RTC) is an independent BCD timer/counter
- Software support for Daylight Saving Time compensation
- Programmable periodic auto-wakeup timer
- Two 32-bit registers containing hours, minutes, seconds, year, month, date, weekday
- Independent 32-bit register containing sub-seconds
- Two programmable alarms
- Two 32-bit registers containing programmable alarm hours, minutes, seconds, year, month, date, weekday
- Two independent 32-bit registers containing programmable alarm sub-seconds
- Digital precision calibration function
- Reference clock detection: a more precise external clock source (50 or 60Hz) can be used to improve calendar accuracy
- Three configurable tamper detection events with filtering and internal pull-up, five internal tamper detection events
- Timestamp function
- 32 backup registers that retain data in low-power modes
- Multiple interrupt/event wakeup sources, including Alarm A, Alarm B, wakeup timer, timestamp, tamper
- RCC register enables the RTC module and as long as voltage remains within operating range, the RTC never stops in any mode (including RUN mode, SLEEP mode, STOP0 mode, STOP2 mode, STANDBY mode, and VBAT mode)
- RTC provides multiple wakeup sources that can wake the MCU from all low-power modes (SLEEP mode, STOP0 mode, STOP2 mode, and STANDBY mode)

2.23 Analog/Digital Converter (ADC)

The 12-bit ADC is a high-speed analog-to-digital converter using successive approximation. There are 3 ADCs in total, with ADC1/ADC2 capable of forming a dual ADC configuration, and ADC1/ADC2/ADC3 capable of forming a triple ADC configuration. Each ADC has up to 20 multiplexed channels, and A/D conversion on each channel can be performed in single, continuous, scan, or discontinuous modes. ADC conversion values are stored (left-aligned/right-aligned) in 16-bit data registers. Input voltages can be monitored through analog watchdogs 1/2/3 to detect if they are within user-defined high/low thresholds, and the maximum input clock frequency for the ADC is 20MHz.

The main features of the ADC are described as follows:

- Supports 3 ADCs with single-ended and differential inputs
- Supports 12-bit and 10-bit resolution
- Supports triggered sampling, including EXTI/TIMER
- Each ADC has 3 analog watchdogs
- Interrupts can be triggered when ADC is ready, sampling complete, conversion complete, or analog watchdog 1/2/3 events
- Supports 4 conversion modes:
 - Single conversion
 - Continuous conversion
 - Discontinuous mode
 - Scan mode
- Supports self-calibration
- Data alignment with embedded data consistency
- Independently programmable sampling time intervals for all channels
- Supports management of single-ended or differential inputs (programmable by channel)
- ADC operating clock derived from PLL clock or AHB clock
- Data can be managed by DSMU, DMA
- Regular channel conversion based on FIFO implementation
- Conversion start methods:
 - Start regular and injected conversions through software
 - Start regular and injected conversions through polarity-configurable external triggers (GPIO input events or internal timer events)
- Oversampling:
 - Adjustable oversampling ratios: x1, x2, x4, x8, x16, x32, x64, x128, x256, x512, x1024
 - Configurable right shift 0-10 bits
 - 16-bit data result register

- Data preprocessing:
 - Supports gain compensation
 - Supports offset compensation
- Multi-ADC modes:
 - Dual ADC mode: combination of ADC1 and ADC2
 - Triple ADC mode: combination of ADC1, ADC2, and ADC3
- ADC operating voltage between 2.3V and 3.6V
- ADC supports conversion of voltages between VREF- and VREF+

2.24 Digital-to-Analog Converter (DAC)

The DAC is a digital-to-analog converter, primarily taking digital input and producing voltage output. DAC data is available in either 8-bit or 12-bit modes and supports DMA functionality. When configured in 12-bit mode, DAC data can be left-aligned or right-aligned; when configured in 8-bit mode, DAC data is right-aligned. Each DAC has an independent converter that can perform conversions independently. In dual DAC mode, each DAC can either operate independently or two DACs (DAC1&DAC2, DAC3&DAC4 as pairs) can perform conversions and updates simultaneously. VREF+ is input through a pin as the DAC reference voltage, providing higher precision for DAC conversion data.

When DAC output is internally connected to on-chip peripherals, the DACx_OUT pin can be used as a general-purpose input/output (GPIO). The DAC output buffer can be selectively enabled to obtain high driving output current.

Main features include:

- Each corresponding to an independent DAC converter
- Supports 8-bit or 12-bit output, with data in 12-bit mode available in both right-aligned and left-aligned formats
- Dual DAC supports synchronous or independent conversion
- Each DAC supports DMA functionality and DMA underflow error detection
- DMA dual data mode to save bus bandwidth
- Noise wave, triangular wave, and sawtooth wave generation
- DAC output supports connection to on-chip peripherals
- Buffer offset calibration
- Input reference voltage supports VREF+
- External event triggered conversion

2.25 Analog Comparator (COMP)

The COMP module is used to compare the magnitude of two input analog voltages and output a high/low level based on the comparison result. When the voltage at the "INP" input terminal is higher than the voltage at the "INM" input terminal, the comparator outputs a high level. When the voltage at the "INP" input terminal is lower than the voltage at the "INM" input terminal, the comparator outputs a low level.

The main functions of the comparator are as follows:

- Two built-in 64-level programmable comparison voltage reference sources VREF1 and VREF2
- Supports filter clock and filter reset
- Output polarity can be configured as high or low
- Supports 4 programmable hysteresis levels
- Comparison results can be output to I/O ports or trigger timers for capture events, OCREF_CLR events, brake events, and interrupt generation
- Input channels can multiplex I/O ports, VREF1, VREF2, and general 12-bit DAC channel outputs
- Can be configured as read-only or read-write; when locked, reset is required to unlock
- Supports blanking, with configurable blanking sources
- COMP1/COMP2 and COMP3/COMP4 can form window comparators
- Can wake up the system from Sleep mode by generating interrupts
- Configurable filter window size
- Configurable filter threshold size
- Configurable sampling frequency for filtering

2.26 Voltage Reference Buffer (VREFBUF)

The chip has a built-in voltage reference buffer that can be used as a voltage reference for ADC, 12bit-DAC, and COMP internal 6bit-DAC. It can also be used as a voltage reference for external components through the VREF+ pin.

2.27 Timers and Watchdogs

The chip supports up to 4 advanced timers, 7 general-purpose timers A, 3 general-purpose timers B, 4 basic timers, 5 low-power timers, as well as 2 independent watchdog timer, 2 window watchdog timer, and 2 system tick timer.

The following table compares the functions of advanced timers, general-purpose timers, basic timers, and low-power timers:

Table 2-3 Timer Function Comparison

Timer	Counter Resolution	Counter Type	Capture/Compare Channels	Capture/Compare Channels	Complementary Output
ATIM1~4	16-bit	Up, Down, Up/Down	Any integer between 1~65536	4	4
GTIMA1~7	16-bit	Up, Down, Up/Down	Any integer between 1~65536	4	None
GTIMB1~3	16-bit	Up, Down, Up/Down	Any integer between 1~65536	4	1
BTIM1~4	32-bit	Up	Any integer between 1~65536	0	None
LPTIM1~5	16-bit	Up	1, 2, 4, 8, 16, 32, 64, 128	0	None

2.27.1 Super High-Resolution Timer (SHRTIM)

Supports two super high-resolution timers

High-resolution timers can generate up to 12 highly precise digital timing signals, primarily used for driving power conversion systems such as switch-mode power supplies or lighting systems, but can also be used for applications requiring extremely high time resolution.

The timer adopts a modular architecture and can generate independent or coupled waveforms. Waveforms are determined by independent timing signals (using counters and comparison units) and various external events (such as analog or digital feedback and synchronization signals), enabling the generation of a wide variety of control signals (PWM, phase shift, constant Ton...) to meet the needs of most conversion topologies.

For control and monitoring purposes, the timer also has timing measurement functions and is connected to built-in ADC and DAC converters. Additionally, the timer has a light load management mode and can handle various fault mechanisms to achieve safe shutdown.

Main features:

- **Multiple timing units**
 - 100ps resolution, all outputs support full resolution, with adjustable duty cycle, frequency, and pulse width in triggered single-pulse mode
 - 6 16-bit timing units (each timing unit includes 1 independent counter and 5 comparison units (comparison unit 5 dedicated to ADC triggering))
 - 12 outputs controllable by any timing unit, with up to 32 set/reset sources per channel
 - Modular structure meets the needs of various independent converters with 1 or 2 switches, as well as some large multi-switch topologies
- **Up to 10 external events, usable for any timing unit**
 - Programmable polarity and edge validity
 - 10 events for fast asynchronous mode
 - 10 events for programmable digital filtering
 - Pseudo-event filtering using blanking and window modes
 - All 10 external events fully mapped to any GPIO or any analog comparator
- **Multiple channels connected to built-in analog peripherals**
 - 10 trigger signals for ADC converters, ADC trigger signals fully mappable to any comparison unit
 - 3 trigger signals for DAC converters
 - 7 comparators for analog signal conditioning
- **Rich protection mechanisms**
 - 6 fault inputs can be used in combination and associated with any timing unit

- All 6 fault inputs fully mappable to any analog comparator
- Programmable polarity and edge validity, digital filters
- Specialized delay protection for resonant converters
- **Multiple SHRTIM instances can be synchronized with external synchronization inputs/outputs**
- **Multifunctional output stage**
 - Full resolution time insertion
 - Programmable output polarity
 - Chopper mode
- **Burst mode controller, capable of handling light load operations on multiple converters simultaneously, supporting 32-bit burst mode counting**
- **8 interrupt vectors, each with up to 14 sources**
- **7 DMA requests, with up to 14 sources, enabling multi-register updates through burst mode**

2.27.2 Advanced Timer (ATIM1~4)

Advanced control timers (ATIMx) are mainly used for: counting input signals, measuring input signal pulse width, and generating output waveforms. Advanced timers feature complementary outputs, dead-time insertion, and brake functions. They are suitable for motor control.

Main features include:

- 16-bit auto-reload counter (can implement up counting, down counting, up/down counting)
- 16-bit programmable prescaler (division factor configurable to any value between 1 and 65536)
- Programmable repetition counter
- Up to 9 channels for ATIMx
- 4 capture/compare channels, operating modes: PWM output, output compare, one-pulse mode output, input capture
- 2 brake input signals with digital filtering support
- Interrupts/DMA generated when the following events occur:
 - Update event
 - Trigger event
 - Input capture
 - Output compare
 - Brake signal input
- Complementary outputs with programmable dead time
 - For ATIMx, channels 1, 2, 3, and 4 support this feature
- Timer control via external signals
- Multiple timers internally connected to achieve timer synchronization or linking
- Incremental (quadrature) encoder interface: for tracking running trajectory and decoding rotational position
- Hall sensor interface: for three-phase motor control
- Trigger input as external clock or for cycle-by-cycle current management

2.27.3 General-Purpose Timer (GTIMA1~7)

General-purpose control timers (GTIMAx) are mainly used for: counting input signals, measuring input signal pulse width, and generating output waveforms.

Main features include:

- 16-bit auto-reload counter (can implement up counting, down counting, up/down counting)
- 16-bit programmable prescaler (division factor configurable to any value between 1 and 65536)
- Up to 4 channels for GTIMAx
- Channel operating modes: PWM output, output compare, one-pulse mode output, input capture
- Interrupts/DMA generated when the following events occur:
 - Update event
 - Trigger event
 - Input capture
 - Output compare
- Timer control via external signals
- Multiple timers internally connected to achieve timer synchronization or linking
- Incremental (quadrature) encoder interface: for tracking running trajectory and decoding rotational position
- Hall sensor interface: for three-phase motor control

2.27.4 General-Purpose Timer (GTIMB1~3)

General-purpose control timers (GTIMBx) are mainly used for: counting input signals, measuring input signal pulse width, and generating output waveforms. General-purpose timers (GTIMBx) feature complementary outputs, dead-time insertion, and brake functions.

Main features include:

- 16-bit auto-reload counter (can implement up counting, down counting, up/down counting)
- 16-bit programmable prescaler (division factor configurable to any value between 1 and 65536)
- Programmable repetition counter
- Up to 5 channels for GTIMBx
- 4 capture/compare channels, operating modes: PWM output, output compare, one-pulse mode output, input capture
- 1 brake input signal with digital filtering support
- Interrupts/DMA generated when the following events occur:
 - Update event
 - Trigger event
 - Input capture
 - Output compare
 - Brake signal input
- Complementary outputs with programmable dead time
 - For GTIMBx, channel 1 supports this feature
- Timer control via external signals
- Multiple timers internally connected to achieve timer synchronization or linking
- Incremental (quadrature) encoder interface: for tracking running trajectory and decoding rotational position
- Hall sensor interface: for three-phase motor control
- Trigger input as external clock or for cycle-by-cycle current management

2.27.5 Basic Timer (BTIM1~4)

Basic timers include a 32-bit auto-reload counter.

Main features include:

- 32-bit auto-reload up-counting counter
- 16-bit programmable prescaler (division factor configurable to any value between 1 and 65536)
- Events generating interrupts/DMA:
 - Update event

2.27.6 Low-Power Timer (LPTIM1~5)

LPTIM is a 16-bit timer with multiple clock sources that can continue running in all power modes. LPTIM can operate without an internal clock source and can be used as a "pulse counter." Additionally, LPTIM can wake up the system from low-power modes, implementing a "timeout function" with extremely low power consumption.

Main features include:

- 16-bit up counter
- 3-bit prescaler, 8 division factors (1, 2, 4, 8, 16, 32, 64, 128)
- Multiple clock sources:
 - Internal clock sources: LSE, LSI, HSI, MSI, or APB clock
 - External clock source: External clock input through LPTIM Input1 (operates without LP oscillator running, used for pulse counter applications)
- 16-bit auto-reload register (LPTIM_ARR)
- 16-bit compare register (LPTIM_CMP)
- Continuous or single-trigger counting mode
- Programmable software or hardware input trigger
- Programmable digital filter for glitch filtering
- Configurable output (PWM)
- Configurable IO polarity
- Encoder mode
- Pulse counting mode, supporting single-pulse counting, dual-pulse counting (quadrature and non-quadrature)

2.27.7 Watchdog Timer (WDG)

Built-in independent watchdog (IWDG) and window watchdog (WWDG) timers solve problems caused by software errors. Watchdog timers are very flexible to use, improving system security and timing control accuracy.

Independent Watchdog (IWDG)

The Independent Watchdog (IWDG) is driven by the low-speed internal clock (LSI clock) running at 32KHz, and it can continue to run even when dead loop events or MCU hangs occur. This provides a higher level of security, timing accuracy, and watchdog flexibility. It can solve system failures caused by software faults through reset. IWDG is most suitable for applications that require the watchdog to run as a completely independent process outside the main application but with lower timing precision requirements.

Main features include:

- Independent 12-bit down counter
- RC oscillator provides an independent clock source, can work in SLEEP, STOP0, and STANDBY modes
- Can match reset and low-power wake-up
- System reset when the down counter reaches 0x000 (if the watchdog is activated)

Window Watchdog (WWDG)

The Window Watchdog (WWDG) clock is derived from the APB1 clock frequency divided by 4096, and it detects program abnormalities through time window configuration. Therefore, WWDG is suitable for precise timing and is commonly used to monitor software failures caused by external interference or unforeseeable logical conditions that cause applications to deviate from their normal operating sequence.

Main features include:

- 14-bit independent programmable down counter
- When WWDG is enabled, reset occurs in the following cases:
 - When the down counter value is less than 0x40
 - When the counter value after decrement is greater than the window register value during reload
- Early wake-up interrupt

2.28 I²C Bus Interface

I²C (Inter-Integrated Circuit) bus is a widely used bus structure that uses only two bidirectional lines: the data bus (SDA) and the clock bus (SCL). Through these two lines, all I²C bus-compatible devices can communicate directly with each other.

The I²C bus interface handles communication between the microcontroller and the serial I²C bus. It provides multi-master functionality and can control all I²C bus-specific sequences, protocols, arbitration, and timing. It supports Standard Mode (Sm), Fast Mode (Fm), Fast Mode Plus (Fm+) and High-Speed Mode(HS). It is also compatible with SMBus (System Management Bus) and PMBus (Power Management Bus). The I²C interface module also supports DMA mode, which can effectively reduce CPU load.

The main features of the I²C interface are described as follows:

- I²C bus specification v3 compatibility:
 - Slave mode and master mode
 - Multi-master functionality
 - Standard Mode (up to 100 kHz) / Fast Mode (up to 400 kHz)
 - Fast Mode Plus (up to 1 MHz) / High-Speed Mode (up to 3.4 MHz)
 - 7-bit and 10-bit addressing modes
 - Multiple 7-bit slave addresses (2 slave address registers, 1 with configurable mask segment)
 - All 7-bit address acknowledge mode
 - Broadcast call
 - Software-configurable data setup and hold times on the bus
 - Interrupts and clock stretching
- SMBus specification v3.0 compatibility:
 - Hardware CRC (packet error checking) generation and verification with ACK control
 - Command and data acknowledgment control
 - Support for Address Resolution Protocol (ARP)
 - Host and device support
 - SMBus alert
 - Timeout and idle state detection
- PMBus rev 1.3 standard

Other features:

- Programmable buffer up to 8 bytes / burst buffer with DMA
- Programmable analog and digital noise filters
- Independent clock source, making I²C communication speed unaffected by i2c_pclk reprogramming

2.29 Flexible External Memory Controller (FEMC)

The Flexible External Memory Controller (FEMC) is used to access various off-chip memory devices. It allows for convenient expansion of different types of large-capacity static memory according to application needs, enabling the simultaneous expansion of multiple different types of static memory without adding external interfaces. All external memories share the address, data, and control signals output by the FEMC controller, and the FEMC distinguishes different external devices through a unique chip select signal.

Main features include:

- Supports external expansion of the following devices:
 - SRAM
 - PSRAM
 - ROM
 - NOR Flash
 - NAND Flash (SLC)
 - LCD (8080/6800)
- Supports two NAND flash blocks, hardware 1bit-ECC can detect up to 2KB of data
- Supports burst access mode for synchronous devices, such as NOR flash and PSRAM
- Supports 8/16/32-bit data bus
- Each memory block has independent chip select control
- Various devices can be supported through timing programming
- Automatically converts 64-bit AXI access requests to consecutive 32-bit or 16-bit or 8-bit access requests based on the data width of the external memory, to communicate with external 32-bit or 16-bit or 8-bit memory devices
- Supports write enable and byte select output for PSRAM and SRAM devices
- External asynchronous wait control
- Supports low-power management

2.30 Universal Synchronous Asynchronous Receiver Transmitter (USART)

The Universal Synchronous Asynchronous Receiver Transmitter (USART) is a full-duplex serial data exchange interface that supports synchronous or asynchronous communication. It can be flexibly configured to facilitate full-duplex data exchange with various external devices.

The USART interface transmit and receive baud rates are configurable, and it also supports continuous communication via DMA. USART also supports multi-processor communication, LIN mode, synchronous mode, single-wire half-duplex communication, smart card asynchronous protocol, IrDA SIR ENDEC functionality, and hardware flow control.

Main features include:

- Supports full-duplex, asynchronous communication
- Supports single-wire half-duplex communication
- Configurable baud rate, with maximum baud rate up to 37.5Mbit/s
- Supports 8x or 16x oversampling
- Supports 8-bit or 9-bit data frames
- Supports two internal FIFOs for transmitting and receiving data
- Supports 1-bit or 2-bit stop bits
- Supports hardware-generated parity bits and parity checking
- Supports hardware flow control: RTS, CTS
- Supports RS-485
- Supports DMA transmit and receive
- Supports multi-processor communication: enters silent mode if address doesn't match, can be awakened by idle bus detection or address identification
- Supports synchronous mode, allowing user control of bidirectional synchronous serial communication in master mode
- Supports smart card asynchronous protocol, compliant with ISO7816-3 standard
- Supports Serial Infrared Protocol (IrDA SIR) encoding and decoding, providing normal and low-power operating modes
- Supports LIN mode
- Supports multiple clock error detection: data overflow error, frame error, noise error, parity error
- Supports multiple interrupt requests: transmit data register empty, CTS flag, transmission complete, data received, data overflow, bus idle, parity error, LIN mode break frame detection, and noise flag/overflow error/frame error in multi-buffer communication

Mode configuration:

Communication Mode	USART1~USART7	UART9~UART15
Asynchronous Mode	Y	Y
Multi-processor	Y	Y
LIN	Y	Y

Synchronous Mode	Y	N
Single-wire Mode (Half-duplex)	Y	Y
Smart Card Mode	Y	N
IrDA Infrared Mode	Y	Y
DMA Communication Mode	Y	Y
Hardware Flow Control Mode	Y	Y

Y = Mode supported, N = Mode not supported

2.31 Low-Power Universal Asynchronous Receiver Transmitter (LPUART)

The Low-Power Universal Asynchronous Receiver Transmitter (LPUART) is a low-power, full-duplex, asynchronous serial communication interface. LPUART can be clocked by LSE, HSE, HSI, MSI, SYSCCLK, and PCLK. When the 32.768kHz LSE is selected as the clock source, LPUART can operate in STOP0/2 low-power modes with a maximum communication rate of up to 9600bps. LPUART supports wake-up by receiving data. By configuring wake-up events, the CPU in STOP0/2 mode can be awakened.

At the same time, when the MCU is working in RUN mode, LPUART can also be used as a regular asynchronous serial port. Users can switch the clock source to HSI, SYSCCLK, and PCLK to achieve higher communication speeds.

The main features of LPUART are as follows:

- Full-duplex asynchronous communication
- Selectable HSI, HSE, LSE, MSI, SYSCCLK, or PCLK clock sources
- Fractional baud rate generator system: programmable baud rate up to 5Mbits/s shared between transmit and receive; baud rates from 300bps to 9600bps when using a 32.768 kHz clock source (LSE)
- Fixed 8-bit data word length, 1 stop bit, and optional 1 parity bit
- Supports DMA data transfer
- Supports hardware flow control
- Transmission detection flags: receive buffer full, receive buffer half-full, receive buffer not empty, receive buffer overflow, transmission complete, transmit buffer full, transmit buffer half-full, transmit buffer not empty
- Parity control: parity selection, parity can be disabled
- Error detection flags: parity error, overflow error, noise error
- 32-byte receive buffer, 8-byte transmit buffer
- Low-frequency baud rate error correction
- Configurable sampling method with 1 or 3 samples
- Noise detection
- Configurable RTS threshold for flow control
- Supports configurable source modes in STOP0/2 mode: start bit detection, receive buffer not empty detection, one configurable receive byte (1~32 bytes), and programmable 8-byte frame

2.32 Flexible Data-rate Controller Area Network (FDCAN)

The FDCAN module complies with the ISO 11898-1:2015 standard, supports CAN 2.0A/B and CAN FD protocols, and is compatible with the non-ISO standard Bosch protocol.

In addition, the CAN modules FDCAN1&2&3&4 also support Time-Triggered CAN (TTCAN) as specified in ISO 11898-4, including event-synchronized time-triggered communication, global system time, and clock drift compensation. FDCAN1&2&3&4 include additional registers dedicated to time-triggered functionality. CANFD can optionally be used with event-triggered and time-triggered CAN communication.

The FDCAN modules share two message RAM areas, and each FDCAN can freely select SRAM5 BANK1 or SRAM5 BANK2 for receive message filters, receive FIFOs, receive buffers, transmit buffers, transmit event FIFOs (and TTCAN triggers). The message RAM is located in the MCU's internal SRAM, with configurable start addresses, and a single FDCAN can be allocated up to 4480 words (32-bit).

Main features include:

- Complies with ISO 11898-1:2015 and ISO 11898-4 standards
- Supports CAN FD with up to 64 bytes of data
- Supports fully hardware-implemented TTCAN Level 1 and Level 2 (only supported by FDCAN1/2/3/4)
- Supports CAN error logging
- Supports AUTOSAR standard
- Supports SAE J1939 standard
- Enhanced receive filter functionality
- Two configurable receive FIFOs
- Separate signal indication when receiving high-priority messages
- Up to 64 dedicated receive buffers
- Up to 32 dedicated transmit buffers
- Configurable transmit FIFO or queue
- Configurable transmit event FIFO
- Supports configurable message RAM, shared by 8 FDCAN controllers
- Programmable loopback test mode
- Maskable module interrupts
- Two clock domains: CAN core clock and APB bus clock
- Supports power-down mode

2.33 Serial Peripheral Interface/Inter-IC Sound Bus (SPI/I2S)

SPI allows chips to communicate with external devices in half/full duplex, synchronous, serial mode. SPI can be configured in master mode and multi-master mode, and provides communication clock (SCK) for external slave devices. It can be used for various purposes, including dual-line simplex synchronous transmission using a single bidirectional data line, and also supports hardware CRC verification.

I2S is also a synchronous serial interface communication protocol. It supports four audio standards, including Philips I2S standard, MSB and LSB aligned standards, and PCM standard. In half-duplex communication, it can work in both master and slave modes. When acting as a master device, it can provide clock signals to external slave devices through the interface.

The main features of the SPI interface are as follows:

- Full-duplex and simplex synchronous modes
- Support for master mode, slave mode and multi-master mode
- Support for 8-bit or 16-bit data frame formats
- Programmable data bit order
- Hardware or software chip select management
- Configurable clock polarity and clock phase
- Hardware CRC calculation and verification support for transmission and reception
- Support for DMA transfer function
- 8-byte receive/transmit FIFO

The main features of the I2S interface are as follows:

- Half-duplex and full-duplex synchronous modes
- Support for master mode and slave mode operation
- 4 audio standards supported: Philips I2S standard, MSB-aligned standard, LSB-aligned standard, and PCM standard
- Configurable audio sampling frequency, ranging from 8KHz to 192KHz
- Configurable steady-state clock polarity
- MSB data direction
- Support for DMA transfer function
- Support for multiple selectable clock sources

2.34 Multi-line Serial Peripheral Interface (xSPI)

xSPI is an interface for single/dual/quad/octal line SPI peripheral communication. It can operate in two modes: indirect mode and memory-mapped mode.

Supported modes:

- Indirect mode: all operations executed using xSPI registers
- Memory-mapped mode: external flash is mapped to the microcontroller address space, allowing the system to treat it as internal storage

Main features:

- Data communication supports single/dual/quad/octal line modes
- Supports Single SPI/Normal SPI, DUAL SPI, QUAD SPI, Dual-QUAD, OCTAL SPI modes
- Maximum transfer rate up to 133 MHz
- Supports Motorola SPI:
 - Standard/Dual/Quad/Octal SPI
- Supports Single Data Rate (SDR) and Double Data Rate (DDR) modes
- Read data strobe and data masking support for DDR transfers
- Supports clock extension
- Frame format and operation codes are software configurable in both indirect and memory-mapped modes
- Integrated FIFO for transmission and reception
- Allows 8/16/32-bit data access
- Dedicated 32x32bit TX FIFO and 32x32bit RX FIFO
- Supports DMA
- XIP mode supports SPI read, does not support XIP write
- Supports continuous transfer mode
- Supports data prefetching
- Supports automatic code decryption for XSPI peripherals: XSPI peripheral code is stored encrypted, automatically decrypted when executing without affecting peripheral access speed; decryption can be enabled/disabled via software; root key stored in NVR area, not accessible to users
- Supports serial NAND FLASH, NOR FLASH, and PSRAM
- Host mode supports 4 external chip select outputs; slave mode supports 1 chip select input; all IOs that are multiplexed as chip select outputs in host mode can be multiplexed as chip select inputs in slave mode
- Supports multi-master arbitration function

2.35 Universal Serial Bus High-Speed Dual Role Interface (USB_HS_DualRole)

The USB High-Speed Dual Role interface (USB HS Dual Role), referred to as USBHS. The USBHS controller is designed to provide high-speed data transfer and a standard interface for connecting external devices. USBHS supports both Host mode and Device mode and includes an internal USB high-speed PHY that can be configured for high-speed or full-speed operation, eliminating the need for external PHY chips. USBHS can support all four transfer types defined by the USB 2.0 protocol (control transfer, bulk transfer, interrupt transfer, and isochronous transfer). Additionally, USBHS includes an internal DMA that can accelerate data transfer between USBHS and the system as an AHB bus master.

Main features:

- Supports USB 2.0 High-speed (480Mb/s)/Full-speed (12Mb/s)/Low-speed (1.5Mb/s) Host mode
- Supports USB 2.0 High-speed (480Mb/s)/Full-speed (12Mb/s) Device mode
- Supports all 4 transfer types: control transfer, bulk transfer, interrupt transfer, and isochronous transfer
- Built-in high-speed PHY supporting high-speed, full-speed, and low-speed modes without external PHY
- Supports HS SOF, FS SOF, and LS Keep-alive tokens
- SOF pulse can be output through PAD
- SOF pulse internally connected to timer (TIMx)
- Supports A-B device identification (ID line)
- Embedded DMA with software-configurable AHB bulk transfer type
- Power-saving features such as stopping the system during USB suspension, turning off digital module clock, and managing PHY and DFIFO power
- Has 4 KB dedicated RAM
- Contains 16 host channels in Host mode, each supporting any type of USB transfer
- Built-in hardware scheduler in Host mode:
 - Stores up to 16 interrupt isochronous transfer requests in periodic hardware queue
 - Stores up to 16 control bulk transfer requests in non-periodic hardware queue
- In Host mode, includes one RX FIFO, one periodic transfer TX FIFO, and one non-periodic transfer TX FIFO
- In Device mode, includes 1 bidirectional control endpoint 0, 8 IN endpoints and 8 OUT endpoints; both IN and OUT endpoints can be configured for bulk, interrupt, or isochronous transfers
- Device mode includes a shared RX FIFO and a TX-OUT FIFO, 9 dedicated TX-IN FIFOs
- Supports soft disconnect function

2.36 Secure Digital Multimedia Card (SDMMC)

SDMMC provides host interface for SD storage cards, SDIO cards, and MMC devices, supporting only one protocol stack version of SD/SDIO/MMC card at a time.

The basic transfer of bus communication is command/response, which directly transfers information in the command or response structure. Data transfers include block mode, SDIO multi-byte mode, and MMC continuous data stream mode.

Main features:

- Compatible with SD Host Controller Standard Specification V3.00
- Compatible with SD Physical Layer Interface Specification V3.00
- Compatible with SDIO Standard Specification V3.00
- Compatible with eMMC Standard Specification V4.51
- Supports 1-bit/4-bit SD card and SDIO modes
- Supports UHS-I interface, requiring level conversion when external devices use 1.8V power supply
- Supports DS, HS, SDR12, SDR25, SDR50, DDR50, and SDR104 transfer modes
- Supports 1-bit, 4-bit, and 8-bit MMC modes and BOOT mode
- Supports single block/multi-block read and write
- Supports maximum block size of 512 bytes in SD&SDIO mode, 2048 bytes in eMMC mode
- EMMC maximum clock frequency 200MHz (limited by maximum I/O frequency), maximum transfer rate up to 1.6Gbps (HS200 mode, 8-bit)
- Fully configurable 2048*2 byte read/write FIFO
- Supports internal dedicated DMA functionality

2.37 DSI Host (DSI)

The DSI Host is a dedicated peripheral for interfacing with MIPI DSI-compliant displays. The MIPI DSI Host Controller serves as the digital core that implements all protocol functions specified in the MIPI DSI specification. It provides an interface between the system and the MIPI D-PHY, enabling communication between the user and DSI-compliant displays.

Key Features:

- Implements all three DSI-2 layers (Pixel-to-Byte Encapsulation, Low-Level Protocol, Lane Management)
- Integrated MIPI D-PHY
- Supports a resolution of 2048x1536 @ 30Hz

Supports input data formats: RGB888/666/565

- 16-bit RGB565
- 18-bit RGB666
- 24-bit RGB888
- Supports command mode and video mode
- Supports scalable data lanes, with 1 to 4 data lanes available
- Lane 0 supports bidirectional transmission
- Supports high-speed (2.5 Gbit/s) D-PHY operation
- Supports virtual channels
- Supports ULPS (Ultra-Low Power State) mode
- Supports continuous and non-continuous clock lane operation
- Supports transmission of multiple packets per transaction
- Supports all three video packet sequences
- Non-burst mode with sync pulses
- Non-burst mode with sync events
- Supports burst mode
- Supports bus turning signals

2.38 DVP Interface

DVP is a flexible and powerful CMOS optical sensor interface that can easily implement customer image acquisition requirements without CPU intervention during the entire acquisition process. With a 100MHz pixel clock, the data transmission rate of the camera interface can reach 200 Mbyte/s.

Main features:

- Supports 8-bit, 10-bit, 12-bit, and 16-bit traditional synchronous parallel interfaces
- Supports 8-bit and 10-bit ITU-R BT.656 video formats
- Supports 8-bit and 16-bit YCbCr, YUV, and RGB data formats
- Supports 8-bit, 10-bit, and 16-bit Bayer data formats
- Supports clock output (via MCO output, typical value 48MHz), providing clock to external CMOS optical sensors
- Input pixel clock DVP_PCLK, frame sync signal DVP_VSYNC, line sync signal DVP_HSYNC polarities can all be independently configured
- Features 320x8 byte FIFO for receiving pixel data
- Supports FIFO overflow protection
- Supports hardware inversion of acquired image data
- Supports continuous mode and snapshot mode
- Supports hardware cropping
- Supports multiple data formats:
 - YCbCr422 progressive video
 - RGB565 progressive video
 - Compressed data (JPEG)

2.39 LCD Controller (LCDC)

The LCD controller provides 24-bit parallel digital RGB as well as horizontal synchronization, vertical synchronization, pixel clock, and data enable signals, which are directly output to the interface of the LCD panel.

Main features:

- 24-bit RGB parallel output (RGB888)
- Color Look-Up Table (CLUT), with a maximum of 256 colors per layer (256 x 24 bit)
- Supports the following pixel formats and also user-defined formats:
 - ARGB8888
 - ABGR8888
 - RGBA8888
 - BGRA8888
 - RGB565
 - BGR565
 - RGB888
- Pseudo-random dithering for the lower bits of each channel
- 2-bit dithering width for red, green, and blue
- Flexible mixing between two layers using alpha values
- Color keying
- Programmable window position and size
- Gamma correction
- Scaling function
- Horizontal mirroring and vertical flipping
- Dual view

2.40 Graphics Processing Unit (GPU)

Supports a 2.5D GPU for high-resolution displays in embedded systems. This module is optimized even when processing millions of pixels per frame.

Main features supported by the 2.5D GPU:

- High rendering quality
 - Sub-pixel accurate rendering
 - Direct edge anti-aliasing
 - Primitive edge blur
 - Static dithering during frame buffer writeback can enhance RGB565 output
- High performance
 - 300M pixels/second fill rate (300MHz clock, single pipeline)
 - Prefetch cache
- Hardware accelerated primitives
 - Fast clear/rectangle fill
 - Lines
 - Triangles
 - Quadrilaterals
 - Bezier curves
 - Advanced Blit operations, supporting scaling, stretching, rotation, tinting, and Alpha blending
 - Convolution filtering
- Blending
 - Normal Alpha blending
 - Independent Alpha/color blending
 - Source/destination factors: 0, 1, source Alpha, 1-source Alpha
- Textures
 - Supports 4096 x 4096 texture size
 - Flexible texture color format handling
 - ARGB8888, RGBA888, RGB888, BGR888, ARGB8565, RGBA5658, ARGB4444, RGBA4444, ARGB1555, RGBA5551, RGB565, AL88, AL44, AL17, AL8, AL4, AL2, AL1, ARGB2222, RGBA2222
 - CLUT (Color Look-Up Table) index formats
 - Applicable to all ALx formats
 - RLE texture decompression
 - Texture addressing modes

- Standard linear
- Scramble
- Reverse scramble
- Virtual tiling
- Frame buffer
 - Supports 4096 x 4096
 - ARGB8888, RGBA888, RGB888, BGR888, ARGB8565, RGBA5658, ARGB4444, RGBA4444, ARGB1555, RGBA5551, RGB565, A8, L8, AL17, ARGB2222, RGBA2222
 - Blending modes: blend, multiply, multiply-add, darken, lighten
- Performance verification
 - Performance counters
 - Visual enumeration efficiency
 - Visual cache burst access length

2.41 Image Codec (JPEG)

Supports a JPEG codec for encoding or decoding uncompressed image data streams in JPEG compression mode, compliant with ISO/IEC 10918-1 standard.

Main features supported by the ENCODER:

- Supports single frame images and Motion JPEG payload
- Supports 3 8-bit color component sampling
- Supports up to 3 color components
- Supports maximum image size of 64K x 64K
- Supports YCbCr and BW (grayscale) image color spaces
- YCbCr/YUV 4:4:4, 4:2:2, 4:2:0
- Configurable JPEG header generator
- 3 programmable 8-bit quantization tables
- 4 programmable Huffman tables (two AC tables and two DC tables)
- Minimum Coding Unit (MCU) fixed at 8 x 8

Main features supported by the DECODER:

- Supports single frame images and Motion JPEG payload
- Supports 8-bit color component sampling
- Supports up to 3 color components
- Supports maximum image size of 64K x 64K
- Supports YCbCr and BW (grayscale) image color spaces
- YCbCr/YUV 4:4:4, 4:2:2, 4:2:0
- Configurable JPEG header generator
- 4 programmable 8-bit quantization tables
- 4 programmable Huffman tables (two AC tables and two DC tables)

2.42 Ethernet (ETH)

The N32H787 supports two Ethernet peripheral modules, ETH1 contains 10/100/1000Mbps Ethernet MAC and ETH2 contains 10/100Mbps Ethernet MAC. The Ethernet module uses dedicated DMA to optimize the performance of transmitting and receiving packets. The ETH module supports standard interfaces to communicate with the physical layer (PHY): MII, RMII, GMII (Note: ETH2 does not support GMII interface) to realize the transmission and reception of Ethernet packets.

The Ethernet module adheres to the following standards:

MAC Tx and Rx Common Features

- Separate transmission, reception, and control interfaces to the application
- 10, 100, and 1000 Mbps data transfer rates with the following PHY interfaces:
 - MII interface to communicate with external Fast Ethernet PHY
 - RMII interface to communicate with an external Fast Ethernet PHY
 - GMII interface to communicate with external Gigabit Ethernet PHY
- Half-duplex operation:
 - CSMA/CD Protocol support
 - Flow control using backpressure support
- 32-bit data transfer interface on the application side
- Full-duplex flow control operations (IEEE 802.3x Pause packets and Priority flow control)
- Support network statistics with RMON or MIB Counters (RFC2819/RFC2665)
- Support Ethernet packet timestamping as described in IEEE 1588-2002 and IEEE 1588-2008 (64-bit timestamps given in the Tx or Rx status of PTP packet). Both one-step and two-step timestamping is supported in TX direction
- Flexibility to control the Pulse-Per-Second (PPS) output signal
- MDIO (Clause 22 and Clause 45) master interface for PHY device configuration and management

MAC Tx Features

- Preamble and start of packet data (SFD) insertion
- Separate 32-bit status for each packet transmitted from the application
- Automatic CRC and pad generation controllable on a per-packet basis
- Programmable packet length to support Standard or Jumbo Ethernet packets with up to 16 KB of size
- Programmable Inter Packet Gap (40–96 bit times in steps of 8)
- IEEE 802.3x Flow Control automatic transmission of zero-quanta Pause packet when flow control input transitions from assertion to de-assertion (in full-duplex mode)
- Source Address field insertion or replacement, and VLAN insertion, replacement, and deletion in transmitted packets with per-packet or static-global control
- Insertion, replacement, or deletion of up to two VLAN tags

- Transmit packets with reduced preamble size in full-duplex mode
- Insert, replace, or delete queue/channel-based VLAN tags

MAC Rx Features

- Automatic Pad and CRC Stripping
- Preamble and SFD deletion
- Programmable watchdog timeout limit
- Flexible address filtering modes:
 - four 48-bit perfect (DA) address filters with masks for each byte
 - four 48-bit SA address comparison check with masks for each byte
 - 64 bit Hash filter for multicast and unicast (DA) addresses
 - Support to pass all multi-cast addressed packets
 - Promiscuous mode to pass all packets without any filtering for network monitoring
 - Pass all incoming packets (as per filter) with a status report
- Additional packet filtering:
 - VLAN tag-based: Perfect match and Hash-based (optional) filtering. Filtering based on either outer or inner
- VLAN tag is possible
 - Layer 3 and Layer 4-based: TCP or UDP over IPv4 or IPv6
- IEEE 802.1Q VLAN tag detection and delete the VLAN tags in received packets
- Detect remote wake-up packets and AMD magic packets
- Forwarding of received Pause packets to the application (in full-duplex mode)
- Receive module for Layer 3/Layer 4 checksum offload for received packets

MTL Tx and Rx Common Features

- 32-bit Transaction Layer block (bridges the application and the MAC)
- Data transfers executed using simple FIFO protocol
- Optimization for packet-oriented transfers with packets delimiters
- Dual-port RAM based asynchronous FIFO controllers
- Programmable burst length, up to half the size of the MTL Rx queue or Tx queue size, to support burst data transfer in the MTL configuration
- Programmable threshold capability for each queue (default of 64 bytes)

MTL Tx Features

- 2KB transmit FIFO with programmable threshold capability
- One queues on the Transmit path
- Store-and-Forward mechanism or threshold mode (cut-through) for transmission to the MAC

- Automatic retransmission of collision packets in half-duplex mode
- Discard packets on late collision, excessive collisions, excessive deferral, and under-run conditions with appropriate status
- Calculate and insert IPv4 header checksum and TCP, UDP, or ICMP checksum
- Statistics by generating pulses for packets dropped (because of underflow) in the Tx FIFO
- Packet-level control for:
 - VLAN tag insertion or replacement
 - Ethernet source address insertion
 - Layer3/Layer4 Checksum insertion control
 - One-step timestamp
 - Timestamp control
 - CRC and pad control

MTL Rx Features

- 2KB receive FIFO with programmable threshold capability
- One queues on the Receive path
- Insertion of Rx Status vectors into the Rx queue after the EOP transfer (in Threshold mode) and before SOP (in Store-and-Forward mode)
- Programmable Rx queue threshold (default fixed at 64 bytes) in Threshold (or cut-through) mode
- Filter all error packets on reception and not forward them to the application in the store-and-forward mode
- Forward the undersized good packets
- Statistics by generating pulses for packets dropped (because of overflow) in the Rx FIFO
- Automatic generation of Pause packet control or backpressure signal to the MAC based on the Rx Queue filllevel

DMA Features

- 32-bit data transfers
- Separate DMA for transmit and receive paths
- Optimization for packet-oriented DMA transfers with packet delimiters
- Byte-aligned addressing for data buffer support
- Dual-buffer (ring) descriptor support
- Descriptor architecture to allow large blocks of data transfer with minimum CPU intervention (each descriptor can transfer up to 32 KB of data)
- Comprehensive status reporting for normal operation and transfers with errors

- Individual programmable burst length for Tx DMA and Rx DMA engines for optimal host bus utilization
- Programmable interrupt options for different operational conditions
- Per-packet Transmit or Receive Complete Interrupt control
- Round-robin or fixed-priority arbitration between the Receive and Transmit engines
- Start and Stop modes
- Separate ports for host CSR access and host data interface
- TCP Segmentation Offload (TSO)

Bus Features

AHB Master Interface Features

- 32-bit, Interfaces with the application through AHB
- Little-endian modes
- Software-selected type of AHB burst (fixed burst, indefinite burst, or mix of both)

AHB Slave Interface Features

- 32-bit, AHB slave interface for CSR access
- Little-endian modes
- All AHB burst types

Monitoring, Testing, and Debugging Features

- Internal loopback from Tx to Rx on the GMII or MII for debugging
- DMA states (Tx and Rx) as status bits
- Debug status register that gives status of FSMs in Transmit and Receive data paths and FIFO fill-levels
- Application Abort status bits
- MMC (RMON) module
- Current Tx or Rx Buffer pointer as status registers
- Current Tx or Rx Descriptor pointer as status registers
- Tx or Rx Queues memory accessible through Slave port for debug

2.43 Cyclic Redundancy Check Unit (CRC)

The CRC calculation unit can generate CRC calculation results in 8-bit, 16-bit, or 32-bit input data according to specified generating polynomials. In other applications, CRC-based techniques are used to verify data transmission or storage integrity. Within the scope of functional safety standards, they provide a method to verify flash memory integrity. The CRC calculation unit helps calculate software signatures at runtime for comparison with reference signatures generated at link time and stored at given memory locations.

Main features:

- Default use of CRC-32 (Ethernet) generating polynomial: $0x4C11DB7$
 - $X^{32} + X^{26} + X^{23} + X^{22} + X^{16} + X^{12} + X^{11} + X^{10} + X^8 + X^7 + X^5 + X^4 + X^2 + X + 1$
- Supports user-defined generating polynomials with configurable size: 7-bit, 8-bit, 16-bit, or 32-bit
- Can process 8-bit, 16-bit, or 32-bit input data
- Configurable CRC initial value
- Single input or output data register
- Built-in input buffer to avoid bus stalling during calculation
- 32-bit data CRC calculation completed in 4 AHB clock cycles (HCLK)
- Supports general-purpose 32-bit register (available for temporary data storage)
- Configurable input and output data bit order
- Supports XOR operations between input/output data and specified (configurable) data

2.44 Secure Data Processing Unit (SDPU)

SDPU combines SAC and SDMA modules, with SAC including AES, DES, SM4, SHA, and RNGC (entropy post-processing) algorithms. SDMA transfers computation data from SRAM to SAC and transfers computation results from SAC to SRAM.

SDPU main features:

- Supports DES symmetric algorithm
 - Supports DES and 3DES encryption/decryption operations
 - TDES supports 2KEY and 3KEY modes
 - Supports CBC and ECB modes
- Supports AES symmetric algorithm
 - Supports 128bit/192bit/256bit key lengths
 - Supports CBC, ECB, CTR modes
- Supports SM4 symmetric algorithm
 - Supports CBC, ECB modes
- Supports SHA hashing algorithm
 - Supports SHA1/SHA224/SHA256/SHA384/SHA512
- Supports Random Number Generator (RNG)
 - Supports True Random Number (TRNG) and Pseudo-Random Number (PRNG) modes
 - Supports LFSR129 post-processing
 - Supports XOR combining of all sources
 - Supports FIPS-140 CAVP
- Supports simultaneous operation of RNG and other algorithms
- Supports FIFO configuration
 - Supports algorithm data configuration through FIFO
- Supports SDMA data transfer
 - Supports automatic data transfer from SRAM to SRAM as master data via AHB interface
 - Supports SRAM base address transfer through parameters
 - Supports maximum data transfer size of 4KB (1024 words)
 - Supports data transfer size checking
 - Supports CRC16 verification
 - SRAM supports maximum 2MB (512K words)
 - Supports data reconnection in cases of source/destination address offset = 1/2/3

2.45 Debug Interface (DBG)

Embeds ARM's SWJ-DP interface, enabling software developers to debug and trace embedded firmware using industry-standard debugging tools via JTAG or serial single-wire debug access port. Trace data can be captured through the trace port for recording and analysis.

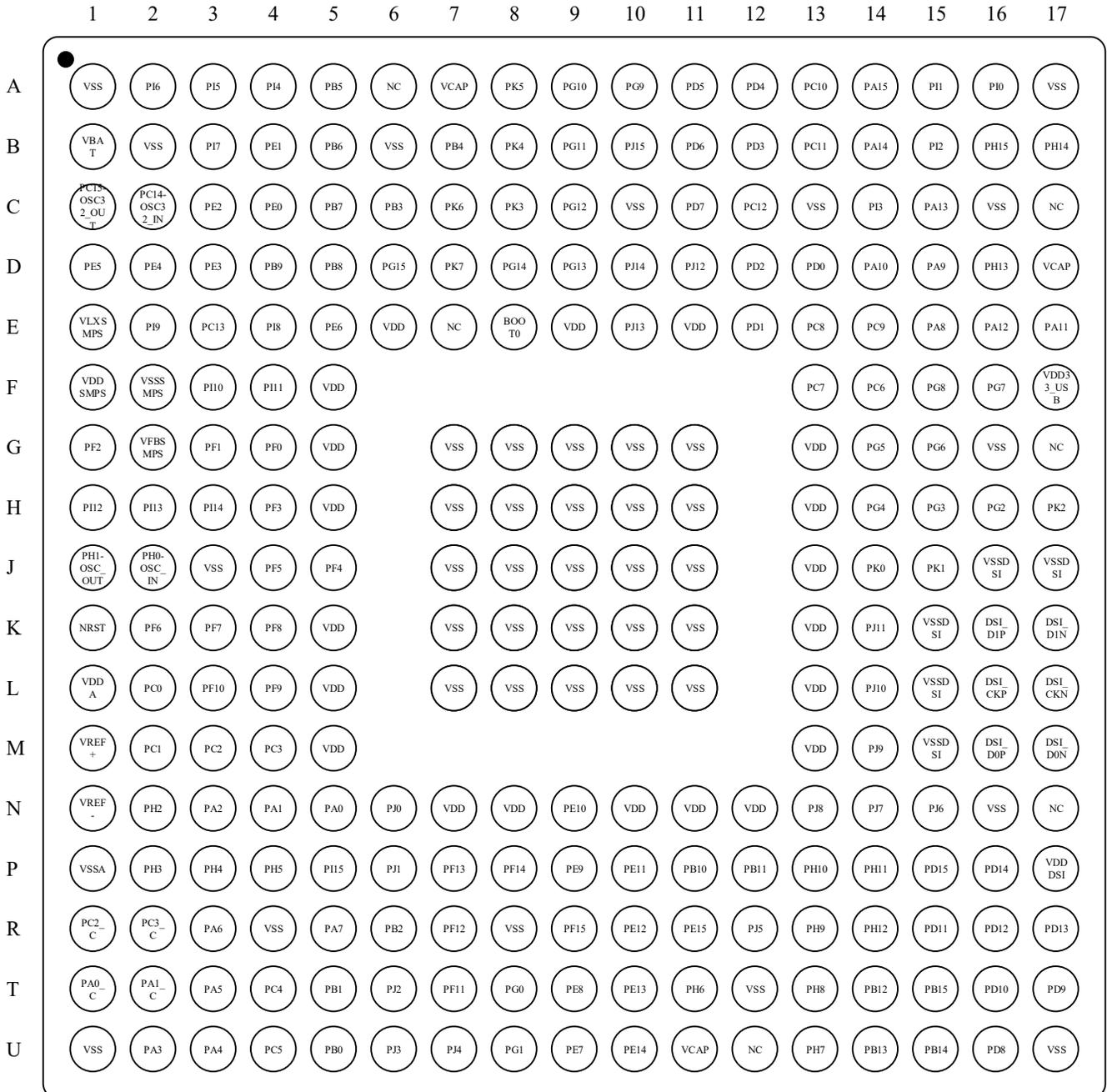
DBG main features:

- Breakpoint debugging
- Code execution tracing
- Software instructions
- JTAG debug port
- Serial line debug port
- Trigger inputs and outputs
- Serial line trace port
- Synchronous trace port
- Debugging and tracing in low-power modes

3 Pin Definition and Description

3.1 Package Diagram

3.1.1 BGA240+25 Pin Distribution



3.2 Pin Description

Note: The following IO definitions cover all functions supported on the respective pins. For the actual supported peripheral resources, please refer to Section 1.1.

Table 3-1 Pin description

Package	Pin Name	Type ⁽¹⁾	I/O Structure ⁽²⁾	Fail-safe ⁽³⁾ Alternate Functions	Support Optional Multiplexed Functions	
					Alternate Functions	Additional Functions
BGA240+ 25						
C3	PE2	IO	TT	Yes	TRACECLK SPI6_SCK ETH1_MII_TXD3/ETH1_GMII_TXD3 GTIMB1_ETR DVP2_D0 FEMC_A23 USART5_RX FDCAN4_TX	-
D3	PE3	IO	TT	Yes	TRACED0 ETH1_MII_TXD2/ETH1_GMII_TXD2 SHRTIM2_EEV GTIMB1_BRK DVP2_D1 FEMC_A19 USART5_TX FDCAN4_RX	-
D2	PE4	IO	FT	Yes	TRACED1 SPI6_NSS ETH2_PHY_INTN SHRTIM1_FLT GTIMB1_CH1N DVP1_D4 LCD_B0 FEMC_A20 USART6_RX DSMU_DATIN3	-
D1	PE5	IO	TT	Yes	TRACED2 SPI6_MISO xSPI2_NCS1 GTIMB1_CH1P DVP1_D6 LCD_G0 FEMC_A21 USART6_TX DSMU_CKIN3	-
E5	PE6	IO	FT	Yes	TRACED3 SPI6_MOSI SHRTIM1_EEV ATIM1_BKIN2 GTIMB1_CH2 DVP1_D7 LCD_G1 FEMC_A22	-
A1/B2	VSS	S	-	-	-	-

B1	VBAT	S	-	-	VBAT	-
E4	PI8	IO	FT	Yes	RTC_OUT2 RTC_TAMP2 PWR_WKUP4 SPI7_SCK ETH2_MII_TX_CLK LPTIM3_IN1 SDMMC1_SEL SDMMC2_SEL FDCAN1_TX	-
E3	PC13	IO	FT	Yes	RTC_OUT1 RTC_TAMP1 RTC_TS PWR_WKUP3	-
C2	PC14-OSC32_IN	IO	FT	Yes	PC14-OSC32_IN	-
C1	PC15-OSC32_OUT	IO	FT	Yes	PC15-OSC32_OUT	-
E2	PI9	IO	TT	Yes	xSPI2_IO0 SHRTIM2_FLT GTIMA7_CH3 LPTIM3_IN2 LCD_VSYNC FEMC_D30 SDRAM_D30 UART9_RX FDCAN1_RX I2C9_SMBA SDRAM_D6	-
F3	PI10	IO	TT	Yes	xSPI2_IO1 ETH1_MII_RX_ER/ETH1_GMII_RX_ER GTIMA7_CH4 LPTIM3_ETR LCD_HSYNC FEMC_D31 SDRAM_D31 FDCAN4_TX I2C9_SDA SDRAM_D7	-
F4	PI11	IO	TT	Yes	PWR_WKUP5 xSPI2_IO2 SHRTIM2_EEV GTIMA7_ETR LCD_G6 SDMMC1_LEDCTRL SDMMC2_LEDCTRL FDCAN4_RX I2C9_SCL FEMC_D0/FEMC_DA0	-
A17	VSS	S	-	-	-	-
E6	VDD	S	-	-	-	-
F2	VSSSMPS	S	-	-	-	-
E1	VLXSMPS	S	-	-	-	-
F1	VDDSMPS	S	-	-	-	-
G2	VFBSMPS	S	-	-	-	-
G4	PF0	IO	TT	Yes	xSPI2_IO0 ETH1_GMII_TXD4 SHRTIM2_CHA1 GTIMA1_CH1 GTIMA5_CH1 DVP2_D0 FEMC_A0	COMP3_OUT

					SDRAM_A0 USART1_TX FDCAN4_TX I2C2_SDA I2C5_SDA	
G3	PF1	IO	TT	Yes	xSPI2_IO1 ETH1_GMII_TXD5 SHRTIM2_CHA2 GTIMA1_CH2 GTIMA5_CH2 DVP2_D1 FEMC_A1 SDRAM_A1 USART1_RX FDCAN4_RX I2C2_SCL I2C5_SCL SDRAM_D5	COMP3_INM
G1	PF2	IO	TT	Yes	SPI6_NSS xSPI2_IO2 ETH1_GMII_TXD6 SHRTIM2_CHB1 GTIMA1_CH3 GTIMA5_CH3 GTIMB2_ETR DVP2_D2 FEMC_A2 SDRAM_A2 USART1_CK I2C2_SMBA I2C5_SMBA	COMP3_INP
H1	PI12	IO	TT	Yes	SPI7_NSS xSPI2_IO3 GTIMA7_CH3 DVP2_D2 LCD_HSYNC FDCAN6_TX I2C7_SDA FEMC_A4	-
H2	PI13	IO	TT	Yes	SPI7_MISO xSPI2_CLK/xSPI2_CLKIN SHRTIM2_FLT GTIMA7_CH4 DVP2_D3 LCD_VSYNC FDCAN6_RX I2C7_SCL FEMC_A7	-
H3	PI14	IO	TT	Yes	SPI7_MOSI xSPI2_NCLK SHRTIM1_EEV ATIM3_BKIN2 GTIMA7_ETR DVP2_D4 LCD_CLK I2C7_SMBA FEMC_A9	-
H4	PF3	IO	TT	Yes	SPI6_SCK xSPI2_IO3 ETH1_GMII_TXD7 SHRTIM2_CHB2	ADC3_INP5 COMP1_INM

					GTIMA1_CH4 GTIMA5_CH4 GTIMB2_CH4 DVP2_D3 FEMC_A3 SDRAM_A3 USART1_CTS/USART1_NSS I2C6_SDA	
J5	PF4	IO	TT	Yes	SPI6_MISO xSPI2_CLK/xSPI2_CLKIN ETH2_MII_RX_CLK/ETH2_RMII_REF_CLK SHRTIM2_CHC1 GTIMA1_ETR GTIMB2_CH3 DVP2_D4 FEMC_A4 SDRAM_A4 USART1_DE/USART1_RTS FDCAN5_TX I2C6_SCL SDRAM_D4	ADC3_INN5 ADC3_INP9
J4	PF5	IO	TT	Yes	SPI6_MOSI xSPI2_NCLK ETH1_GMII_GTX_CLK SHRTIM2_CHC2 ATIM3_BKIN1 GTIMB2_CH2 DVP2_D5 FEMC_A5 SDRAM_A5 FDCAN5_RX I2C6_SMBA	ADC3_INP4 COMP1_INP
C10	VSS	S	-	-	-	-
E9	VDD	S	-	-	-	-
K2	PF6	IO	TT	Yes	SPI5_NSS xSPI2_IO3 ETH2_MDIO ATIM3_ETR ATIM4_ETR GTIMA5_CH1 GTIMB2_CH1P DVP1_PIXCLK DVP2_D5 UART11_RX FDCAN3_RX	ADC3_INN4 ADC3_INP8 COMP2_INM
K3	PF7	IO	TT	Yes	SPI5_SCK xSPI2_IO2 ETH2_MDC ATIM3_CH4 ATIM4_CH3 GTIMA5_CH2 GTIMB3_CH1P DVP2_PIXCLK UART11_TX FDCAN3_TX	ADC3_INP3 COMP2_INP
K4	PF8	IO	TT	Yes	SPI5_MISO xSPI2_IO0 ETH2_MII_COL ATIM3_CH1 ATIM4_CH4 GTIMA5_CH3	ADC3_INN3 ADC3_INP7 COMP4_INM

					GTIMB2_CH1N DVP2_HSYNC SDMMC2_LEDCTRL UART11_DE/UART11 RTS	
L4	PF9	IO	TT	Yes	SPI5_MOSI xSPI2_IO1 ETH2_MII_CRS SHRTIM2_FLT ATIM3_CH2 ATIM4_CH1 GTIMA5_CH4 GTIMB3_CH1N DVP2_VSYNC SDMMC1_LEDCTRL UART11_CTS	ADC3_INP2
L3	PF10	IO	TT	Yes	xSPI2_CLK/xSPI2_CLKIN ETH2_PPS_OUT SHRTIM2_EEV ATIM3_CH3 ATIM4_CH2 GTIMB2_BRK DVP1_D11 LCD_DE FEMC_A3	ADC3_INN2 ADC3_INP6 COMP4_INP
J2	PH0-OSC IN	IO	FT	Yes	PH0-OSC IN	-
J1	PH1-OSC_OUT	IO	FT	Yes	PH1-OSC_OUT	-
K1	NRST	I-O	NRST	-	NRST	-
L2	PC0	IO	TT	Yes	ETH2_MII_RX_DV/ETH2_RMII_CRS_DV LCD_G2 LCD_R5 FEMC_A25 FEMC_D12/FEMC_DA12 SDRAM_NWE SDRAM_D12 DSMU_CKIN0 DSMU_DATIN4	ADC1_INP10 ADC2_INP10 ADC3_INP10
M2	PC1	IO	TT	Yes	TRACED0 RTC_TAMP3 PWR_WKUP6 SPI2_MOSI I2S2_SD_EXT ETH1_MDC LCD_G5 SDMMC2_CK FEMC_D0/FEMC_DA0 DSMU_CKIN4 DSMU_DATIN0	ADC1_INN10 ADC1_INP11 ADC2_INN10 ADC2_INP11 ADC3_INN10 ADC3_INP11
M3	PC2	IO	TT	Yes	SPI2_MISO I2S2_SD ETH1_MII_TXD2/ETH1_GMII_TXD2 DVP2_D6 SDRAM_NCE0 DSMU_CKIN1 DSMU_CKOUT	ADC1_INN11 ADC1_INP12 ADC2_INN11 ADC2_INP12 ADC3_INN11 ADC3_INP12
R1	PC2_C	IO	TT	Yes	-	ADC2_INN1 ADC2_INP0 ADC3_INN1 ADC3_INP0
M4	PC3	IO	TT	Yes	SPI2_MOSI I2S2_SD_EXT	ADC1_INN12 ADC1_INP13

					ETH1_MII_TX_CLK/ETH1_GMII_TX_CLK DVP2_D7 SDRAM_CKE0 DSMU_DATIN1	ADC2_INN12 ADC2_INP13
R2	PC3_C	IO	TT	Yes	-	ADC2_INP1 ADC3_INP1
E11	VDD	S	-	-	-	-
C13	VSS	S	-	-	-	-
P1	VSSA	S	-	-	-	-
N1	VREF-	S	-	-	-	-
M1	VREF+	S	-	-	-	-
L1	VDDA	S	-	-	-	-
N5	PA0	IO	TT	Yes	PWR_WKUP1 SPI4_NSS I2S4_WS ETH1_MII_CRX/ETH1_GMII_CRX ATIM2_ETR GTIMA1_CH1 GTIMA1_ETR GTIMA4_CH1 GTIMB1_BRK SDMMC2_CMD FEMC_A19 USART2_CTS/USART2_NSS UART9_TX	ADC1_INP16
T1	PA0_C	IO	TT	Yes	-	ADC1_INN1 ADC1_INP0 ADC2_INN1 ADC2_INP0
N4	PA1	IO	TT	Yes	ETH1_MII_RX_CLK/ETH1_RMII_REF_CLK/ETH1_GMII_RX_CLK GTIMA1_CH2 GTIMA4_CH2 GTIMB1_CH1N LPTIM3_OUT LCD_R2 USART2_DE/USART2_RTS UART9_RX	ADC1_INN16 ADC1_INP17
T2	PA1_C	IO	TT	Yes	-	ADC1_INP1 ADC2_INP1
N3	PA2	IO	TT	Yes	PWR_WKUP2 ETH1_MDIO SHRTIM2_EEV GTIMA1_CH3 GTIMA4_CH3 GTIMB1_CH1P LPTIM4_OUT LCD_R1 USART2_TX	ADC1_INP14 ADC2_INP14
N2	PH2	IO	TT	Yes	xSPI2_IO4 ETH1_MII_CRX/ETH1_GMII_CRX SHRTIM2_CHD1 GTIMB3_CH2 LPTIM1_IN2 LCD_R0 SDRAM_CKE0 UART15_RX	ADC3_INP13
F5	VDD	S	-	-	-	-
C16	VSS	S	-	-	-	-
P2	PH3	IO	TT	Yes	xSPI2_IO5 ETH1_MII_COL/ETH1_GMII_COL	ADC3_INN13 ADC3_INP14

					SHRTIM2_CHD2 GTIMB3_CH3 LCD_R1 SDRAM_NCE0 USART7_CK UART15_TX	
P3	PH4	IO	FT	Yes	ETH2_MII_TXD0/ETH2_RMII_TXD0 SHRTIM2_CHE1 GTIMB3_CH4 DVP2_HSYNC LCD_G4 LCD_G5 USART7_RX UART15_DE/UART15_RTS FDCAN5_TX I2C2_SCL	ADC3_INN14 ADC3_INP15
P4	PH5	IO	TT	Yes	SPI5_NSS ETH2_MII_TXD1/ETH2_RMII_TXD1 SHRTIM2_CHE2 GTIMB3_ETR DVP2_PIXCLK SDRAM_NWE USART7_TX UART15_CTS FDCAN5_RX I2C2_SDA	ADC3_INN15 ADC3_INP16
U2	PA3	IO	TT	Yes	I2S4_MCK ETH1_MII_COL/ETH1_GMII_COL GTIMA1_CH4 GTIMA4_CH4 GTIMB1_CH2 LPTIM5_OUT LCD_B2 LCD_B5 USART2_RX FEMC_A10	ADC1_INP15 ADC2_INP15
G5	VDD	S	-	-	-	-
U3	PA4	IO	TT	No	SPI1_NSS SPI3_NSS SPI4_NSS I2S1_WS I2S3_WS I2S4_WS GTIMA4_ETR DVP1_HSYNC LCD_VSYNC FEMC_D8/FEMC_DA8 SDRAM_D8 USART2_CK USB2_SOF	ADC1_INP18 ADC2_INP18 DAC1_OUT
T3	PA5	IO	TT	Yes	SPI1_SCK SPI4_SCK I2S1_CK I2S4_CK ATIM2_CH1N GTIMA1_CH1 GTIMA1_ETR LCD_R4 FEMC_D9/FEMC_DA9 SDRAM_D9 SDRAM_DQM0	ADC1_INN18 ADC1_INP19 ADC2_INN18 ADC2_INP19 DAC2_OUT

R3	PA6	IO	TT	Yes	SPI1_MISO SPI4_MISO I2S1_SD I2S4_SD xSPI2_IO3 ATIM1_BKIN1 ATIM2_BKIN1 ATIM3_CH1 GTIMA2_CH1 DVP1_PIXCLK LCD_G2	ADC1_INP3 ADC2_INP3
R5	PA7	IO	TT	Yes	SPI1_MOSI SPI4_MOSI I2S1_SD_EXT I2S4_SD_EXT xSPI2_IO2 ETH1_MII_RX_DV/ETH1_RMII_CRS_DV/ETH1_GMII_RX_DV ATIM1_CH1N ATIM2_CH1N ATIM4_CH1 GTIMA2_CH2 LCD_VSYNC SDRAM_NWE	ADC1_INN3 ADC1_INP7 ADC2_INN3 ADC2_INP7
T4	PC4	IO	TT	Yes	I2S1_MCK ETH1_MII_RXD0/ETH1_RMII_RXD0/ETH1_GMII_RXD0 SHRTIM2_EEV LCD_R7 SDMMC2_CKIN FEMC_A22 SDRAM_NCE0 DSMU_CKIN2	ADC1_INP4 ADC2_INP4 COMP1_INM
U4	PC5	IO	TT	Yes	ETH1_MII_RXD1/ETH1_RMII_RXD1/ETH1_GMII_RXD1 SHRTIM2_FLT LCD_DE SDMMC2_SEL SDRAM_CKE0 DSMU_DATIN2 FEMC_A1 SDRAM_NCAS	ADC1_INN4 ADC1_INP8 ADC2_INN4 ADC2_INP8 COMP1_OUT
G13	VDD	S	-	-	-	-
R4	VSS	S	-	-	-	-
U5	PB0	IO	TT	Yes	xSPI2_IO1 ETH1_MII_RXD2/ETH1_GMII_RXD2 ATIM1_CH2N ATIM2_CH2N GTIMA2_CH3 LCD_G1 LCD_R3 UART9_CTS DSMU_CKOUT	ADC1_INN5 ADC1_INP9 ADC2_INN5 ADC2_INP9 COMP1_INP
T5	PB1	IO	TT	Yes	SPI3_MISO xSPI2_IO0 ETH1_MII_RXD3/ETH1_GMII_RXD3 ATIM1_CH3N ATIM2_CH3N GTIMA2_CH4 DVP1_MCLK LCD_G0	ADC1_INP5 ADC2_INP5 COMP1_INM

					LCD_R6 DSMU_DATIN1	
R6	PB2	IO	TT	Yes	RTC_OUT2 SPI3_MOSI I2S3_SD_EXT xSPI2_CLK/xSPI2_CLKIN ETH1_MII_TX_ER/ETH1_GMII_TX_ER ATIM1_CH4N ATIM2_CH4N GTIMA5_ETR DVP1_HSYNC DVP2_D12 DSMU_CKIN1	COMP1_INP
P5	PI15	IO	FT	Yes	ETH2_PPS_OUT SHRTIM1_FLT ATIM3_BKIN2 GTIMB3_ETR DVP2_D13 LCD_G2 LCD_R0	ADC2_INP17 ADC3_INP17
N6	PJ0	IO	FT	Yes	ETH2_MII_TXD2 SHRTIM2_FLT ATIM4_ETR GTIMB3_CH1N LCD_R1 LCD_R7 UART15_RX FDCAN8_TX I2C9_SDA	ADC2_INP16
P6	PJ1	IO	TT	Yes	SPI7_SCK xSPI2_IO4 ETH2_MII_TXD3 ATIM4_CH1 GTIMB3_CH1P DVP2_VSYNC LCD_R2 UART15_TX FDCAN8_RX I2C9_SCL	-
T6	PJ2	IO	TT	Yes	SPI7_NSS xSPI2_IO5 SHRTIM2_EEV ATIM4_CH1N GTIMB3_CH2 DVP1_D15 LCD_R3 UART15_DE/UART15_RTS I2C9_SMBA	-
U6	PJ3	IO	FT	Yes	SPI7_MISO ETH2_MII_RX_DV/ETH2_RMII_CRS_DV ATIM4_CH2 GTIMB3_CH3 DVP1_D14 LCD_R4 UART13_RTS UART15_CTS FDCAN7_TX I2C9_SDA	ADC3_INP18
U7	PJ4	IO	FT	Yes	SPI7_MOSI ETH2_MII_RX_CLK/ETH2_RMII_REF_CLK ATIM4_CH2N	ADC3_INP19

					GTIMB3_CH4 DVP1_D13 LCD_R5 UART13_CTS FDCAN7_RX I2C9_SCL	
T7	PF11	IO	TT	Yes	SPI5_MOSI ETH2_MII_TX_EN/ETH2_RMII_TX_EN GTIMA6_CH1 DVP1_D12 SDRAM_NRAS I2C6_SDA SDRAM_NRAS	ADC1_INP2
R7	PF12	IO	TT	Yes	xSPI2_DQS ETH2_MII_TXD0/ETH2_RMII_TXD0 GTIMA6_CH2 DVP2_D6 FEMC_A6 SDRAM_A6 FDCAN6_TX I2C6_SCL	ADC1_INN2 ADC1_INP6
J3	VSS	S	-	-	-	-
H5	VDD	S	-	-	-	-
P7	PF13	IO	TT	Yes	ETH2_MII_TXD1/ETH2_RMII_TXD1 SHRTIM2_FLT GTIMA6_CH3 DVP2_D7 FEMC_A7 SDRAM_A7 USART7_CK FDCAN6_RX I2C4_SMBA I2C6_SMBA DSMU_DATIN6 SDRAM_NCE0	ADC2_INP2 COMP3_OUT
P8	PF14	IO	TT	Yes	ETH2_MII_TXD2 SHRTIM2_CHF1 GTIMA6_CH4 DVP2_D8 FEMC_A8 SDRAM_A8 USART7_RX FDCAN3_RX I2C4_SCL DSMU_CKIN6	ADC2_INN2 ADC2_INP6 COMP3_INM
R9	PF15	IO	TT	Yes	ETH2_MII_TXD3 SHRTIM2_CHF2 LPTIM4_ETR DVP2_D9 FEMC_A9 SDRAM_A9 USART7_TX FDCAN3_TX I2C4_SDA SDRAM_BA0	COMP3_INP
T8	PG0	IO	TT	Yes	xSPI2_IO4 xSPI2_NCS2 ETH2_MII_TX_CLK SHRTIM1_EEV ATIM4_BKIN1 LPTIM4_IN1	-

					DVP2_D10 FEMC_A10 SDRAM_A10 UART13_RX SDRAM_BA1	
J16	VSSDSI	S	-	-	-	-
H13	VDD	S	-	-	-	-
U8	PG1	IO	TT	Yes	xSPI2_IO5 xSPI2_NCS3 ETH2_MII_TX_ER SHRTIM2_FLT GTIMB1_ETR LPTIM4_IN2 DVP2_D11 FEMC_A11 SDRAM_A11 UART13_TX SDRAM_A10	-
U9	PE7	IO	TT	Yes	xSPI2_NCS2 ETH2_PHY_INTN ATIM1_ETR FEMC_D4/FEMC_DA4 SDRAM_D4 UART11_RX I2C7_SDA DSMU_DATIN2	COMP2_INM
T9	PE8	IO	TT	Yes	ATIM1_CH1N SDMMC1_LEDCTRL FEMC_D5/FEMC_DA5 SDRAM_D5 UART11_TX FDCAN5_TX I2C7_SCL DSMU_CKIN2 SDRAM_A0	COMP2_OUT
P9	PE9	IO	TT	Yes	ATIM1_CH1 SDMMC2_LEDCTRL FEMC_D6/FEMC_DA6 SDRAM_D6 UART11_DE/UART11_RTS FDCAN5_RX I2C7_SMBA DSMU_CKOUT SDRAM_A1	COMP2_INP
J17	VSSDSI	S	-	-	-	-
J13	VDD	S	-	-	-	-
N9	PE10	IO	TT	Yes	ATIM1_CH2N FEMC_D7/FEMC_DA7 SDRAM_D7 UART11_CTS DSMU_DATIN4 SDRAM_A2	COMP2_INM
P10	PE11	IO	TT	Yes	SPI6_NSS ATIM1_CH2 LCD_G3 FEMC_D8/FEMC_DA8 SDRAM_D8 DSMU_CKIN4 SDRAM_A3	COMP2_INP
R10	PE12	IO	TT	Yes	SPI6_SCK ETH1_GMII_RXD4	COMP1_OUT

					ATIM1_CH3N LCD_B4 FEMC_D9/FEMC_DA9 SDRAM_D9 UART13_RX DSMU_DATIN5	
T10	PE13	IO	TT	Yes	SPI6_MISO ETH1_GMII_RXD5 ATIM1_CH3 LCD_DE FEMC_D10/FEMC_DA10 SDRAM_D10 UART13_TX FDCAN6_TX I2C6_SDA DSMU_CKIN5	COMP2_OUT
T12	VSS	S	-	-	-	-
K13	VDD	S	-	-	-	-
U10	PE14	IO	TT	Yes	SPI6_MOSI ETH1_GMII_RXD6 SHRTIM2_EEV ATIM1_CH4 LCD_CLK FEMC_D11/FEMC_DA11 SDRAM_D11 USART6_CK UART13_CTS FDCAN6_RX I2C6_SCL	-
R11	PE15	IO	TT	Yes	ETH1_GMII_RXD7 ATIM1_BKIN1 LCD_R7 FEMC_D12/FEMC_DA12 SDRAM_D12 USART5_CK UART13_DE/UART13_RTS I2C6_SMBA	-
P11	PB10	IO	TT	Yes	SPI2_SCK I2S2_CK ETH1_MII_RX_ER/ETH1_GMII_RX_ER SHRTIM1_SCOUT GTIMA1_CH3 LPTIM2_IN1 LCD_G4 USART3_TX I2C2_SCL DSMU_DATIN7 FEMC_D13/FEMC_DA13	-
P12	PB11	IO	TT	Yes	ETH1_MII_TX_EN/ETH1_RMII_TX_EN/ETH1_GMII_TX_EN SHRTIM1_SCIN GTIMA1_CH4 LPTIM2_ETR LCD_G5 USART3_RX I2C2_SDA DSMU_CKIN7 FEMC_D15/FEMC_DA15	-
U11	VCAP	S	-	-	-	-
U12	NC	S	-	-	-	-
L13	VDD	S	-	-	-	-

R12	PJ5	IO	FT	Yes	ETH2_MII_TX_ER SHRTIM1_EEV ATIM4_BKIN2 LPTIM5_ETR DVP1_D9 LCD_R6	ADC2_INP16
T11	PH6	IO	TT	Yes	SPI5_SCK ETH1_MII_RXD2/ETH1_GMII_RXD2 ATIM1_CH4N GTIMA7_CH1 LPTIM5_IN1 DVP1_D8 FEMC_BAA SDRAM_NCE1 UART14_RX FDCAN7_TX I2C2_SMBA SDRAM_A4	COMP4_INM
U13	PH7	IO	TT	Yes	SPI5_MISO ETH1_MII_RXD3/ETH1_GMII_RXD3 SHRTIM2_EEV ATIM3_BKIN1 LPTIM5_IN2 DVP1_D9 FEMC_CRE SDRAM_CKE1 UART14_TX FDCAN7_RX I2C3_SCL SDRAM_A5	COMP4_INP
T13	PH8	IO	TT	Yes	ETH1_GMII_RXD4 SHRTIM2_EEV ATIM3_CH1 GTIMA4_ETR DVP1_HSYNC LCD_R2 FEMC_D16 SDRAM_D16 UART10_DE/UART10_RTS UART14_DE/UART14_RTS FDCAN2_RX I2C3_SDA SDRAM_A6	COMP4_OUT
R13	PH9	IO	TT	Yes	ETH1_GMII_RXD5 ATIM3_CH1N GTIMA7_CH2 DVP1_D0 LCD_R3 FEMC_D17 SDRAM_D17 UART10_CTS UART14_CTS FDCAN2_TX I2C3_SMBA SDRAM_A7	COMP4_INM
P13	PH10	IO	TT	Yes	ETH1_GMII_RXD6 SHRTIM2_EEV ATIM3_CH2 GTIMA4_CH1 DVP1_D1 LCD_R4	COMP4_INP

					FEMC_D18 SDRAM_D18 I2C4_SMBA SDRAM_A8	
P14	PH11	IO	TT	Yes	ETH1_GMII_RXD7 SHRTIM2_EEV ATIM3_CH2N GTIMA4_CH2 DVP1_D2 LCD_R5 FEMC_D19 SDRAM_D19 UART10_RX I2C4_SCL SDRAM_A9	-
R14	PH12	IO	TT	Yes	ETH2_MII_RX_DV/ETH2_RMII_CRS_DV SHRTIM2_EEV ATIM3_ETR GTIMA4_CH3 DVP1_D3 LCD_R6 FEMC_D20 SDRAM_D20 UART10_TX I2C4_SDA SDRAM_A11	COMP4_OUT
N16	VSS	S	-	-	-	-
M13	VDD	S	-	-	-	-
T14	PB12	IO	TT	No	SPI2_NSS/I2S2_WS ETH1_MII_TXD0/ETH1_RMII_TXD0/ETH1_GMII_TXD0 ATIM1_BKIN1 LPTIM2_IN2 DVP2_D14 USART3_CK UART10_RX FDCAN2_RX USB2_ID I2C2_SMBA DSMU_DATIN1	-
U14	PB13	IO	TT	No	SPI2_SCK I2S2_CK ETH1_MII_TXD1/ETH1_RMII_TXD1/ETH1_GMII_TXD1 ATIM1_CH1N LPTIM2_OUT DVP1_D2 SDMMC1_D0 USART3_CTS/USART3_NSS UART10_TX FDCAN2_TX USB2_VBUS DSMU_CKIN1	-
U15	PB14	IO	TT	No	SPI2_MISO I2S2_SD ATIM1_CH2N ATIM2_CH2N GTIMA7_CH1 LCD_CLK SDMMC2_D0	-

					FEMC_D10/FEMC_DA10 SDRAM_D10 USART1_TX USART3_DE/USART3_RTS UART9_DE/UART9_RTS USB2_DM DSMU_DATIN2	
T15	PB15	IO	TT	No	RTC_REFIN SPI2_MOSI I2S2_SD_EXT ATIM1_CH3N ATIM2_CH3N GTIMA7_CH2 LCD_G7 SDMMC2_D1 FEMC_D11/FEMC_DA11 SDRAM_D11 USART1_RX UART9_CTS USB2_DP DSMU_CKIN2	-
U16	PD8	IO	TT	Yes	SHRTIM1_EEV SHRTIM2_SCIN ATIM3_CH3 DVP2_HSYNC FEMC_D13/FEMC_DA13 SDRAM_D13 USART3_TX I2C7_SDA DSMU_CKIN3	-
T17	PD9	IO	TT	Yes	SHRTIM1_EEV SHRTIM2_SCOUT ATIM3_CH3N DVP2_VSYNC FEMC_D14/FEMC_DA14 SDRAM_D14 USART3_RX I2C7_SCL DSMU_DATIN3	-
T16	PD10	IO	TT	Yes	ETH1_CLK125 ETH2_PPS_OUT ATIM1_CH4N LPTIM2_OUT LCD_B3 FEMC_D15/FEMC_DA15 SDRAM_D15 USART3_CK I2C7_SMBA DSMU_CKOUT	-
N12	VDD	S	-	-	-	-
U17	VSS	S	-	-	-	-
R15	PD11	IO	TT	Yes	SHRTIM2_EEV GTIMA3_ETR LPTIM2_IN2 DVP2_D15 FEMC_A16/FEMC_CLE USART3_CTS/USART3_NSS I2C4_SMBA	-
R16	PD12	IO	TT	Yes	GTIMA3_CH1 LPTIM1_IN1 LPTIM2_IN1	-

					DVP1_D12 FEMC_A17/FEMC_ALE USART3_DE/USART3_RTS UART12_TX UART13_CTS FDCAN3_RX I2C4_SCL	
R17	PD13	IO	TT	Yes	GTIMA3_CH2 LPTIM1_OUT DVP1_D13 FEMC_A18 UART12_RX USART13_DE/USART13_RTS FDCAN3_TX I2C4_SDA I2C8_SMBA	-
N11	VDD	S	-	-	-	-
P16	PD14	IO	TT	Yes	ETH1_PPS_OUT ATIM3_CH4 GTIMA3_CH3 SDMMC1_D4 FEMC_D0/FEMC_DA0 SDRAM_D0 UART12_CTS UART13_RX I2C8_SDA SDRAM_CKE0	-
P15	PD15	IO	TT	Yes	ETH1_PHY_INTN ETH2_PHY_INTN SHRTIM2_FLT ATIM3_CH4N GTIMA3_CH4 SDMMC1_D5 FEMC_D1/FEMC_DA1 SDRAM_D1 UART12_DE/UART12_RTS UART13_TX I2C8_SCL	-
N15	PJ6	IO	FT	Yes	ATIM2_CH2 DVP2_D8 LCD_R7 FDCAN7_TX FEMC_D2/FEMC_DA2	ADC3_INP18
N14	PJ7	IO	FT	Yes	TRGIN ATIM2_CH2N DVP2_D9 LCD_G0 FDCAN7_RX FEMC_D3/FEMC_DA3	ADC3_INP19
N10	VDD	S	-	-	-	-
R8	VSS	S	-	-	-	-
N13	PJ8	IO	FT	Yes	ETH2_MII_RXD2 ATIM1_CH3N ATIM2_CH1 DVP2_D10 LCD_G1 USART8_CTS/USART8_NSS UART12_TX UART14_DE/UART14_RTS FDCAN8_TX I2C8_SDA	-

M14	PJ9	IO	FT	Yes	ETH2_MII_RXD3 ATIM1_CH3 ATIM2_CH1N DVP2_D11 LCD_G2 USART8_DE/USART8_RTS UART12_RX UART14_CTS FDCAN8_RX I2C8_SCL	-
L14	PJ10	IO	FT	Yes	SPI5_MOSI ATIM1_CH2N ATIM2_CH2 DVP2_D12 LCD_G3 UART12_CTS UART14_RX I2C8_SMBA FEMC_D5/FEMC_DA5	-
K14	PJ11	IO	FT	Yes	SPI5_MISO ATIM1_CH2 ATIM2_CH2N DVP2_D13 LCD_G4 UART12_DE/UART12_RTS UART14_TX FEMC_D6/FEMC_DA6	-
N8	VDD	S	-	-	-	-
P17	VDDDSI	S	-	-	-	-
U1	VSS	S	-	-	-	-
N17	NC	S	-	-	-	-
M16	DSI_D0P	DSI	TT	-	DSI_L0P	-
M17	DSI_D0N	DSI	TT	-	DSI_L0N	-
K15	VSSDSI	S	-	-	-	-
L16	DSI_CKP	DSI	TT	-	DSI_CKP	-
L17	DSI_CKN	DSI	TT	-	DSI_CKN	-
K16	DSI_D1P	DSI	TT	-	DSI_L1P	-
K17	DSI_D1N	DSI	TT	-	DSI_L1N	-
L15	VSSDSI	S	-	-	-	-
M15	VSSDSI	S	-	-	-	-
J14	PK0	IO	FT	Yes	SPI5_SCK ETH2_MII_COL SHRTIM2_EEV ATIM1_CH1N ATIM2_CH3 DVP2_D7 LCD_G5 I2C3_SCL	-
J15	PK1	IO	FT	Yes	SPI5_NSS ETH2_MII_CRS SHRTIM2_FLT ATIM1_CH1 ATIM2_CH3N DVP2_D6 LCD_G6 I2C3_SDA	-
H17	PK2	IO	FT	Yes	SHRTIM1_FLT ATIM1_BKIN1 ATIM2_BKIN1 DVP2_D5 LCD_G7	-

					I2C3_SMBA FEMC_A11	
H16	PG2	IO	TT	Yes	ETH2_MII_RXD0/ETH2_RMII_RXD0 SHRTIM2_SCIN ATIM2_BKIN1 GTIMA6_ETR DVP2_D12 FEMC_A12 SDRAM_A12 USART7_CTS/USART7_NSS FDCAN8_TX SDRAM_DQM1	-
H15	PG3	IO	FT	Yes	ETH2_MII_RXD1/ETH2_RMII_RXD1 SHRTIM2_SCOUT ATIM2_BKIN2 GTIMA5_ETR DVP2_D13 FEMC_A13 USART7_DE/USART7_RTS FDCAN8_RX	-
N7	VDD	S	-	-	-	-
H14	PG4	IO	TT	Yes	ETH2_MII_RXD2 SHRTIM1_CHF1 ATIM1_BKIN2 DVP2_D14 SDMMC2_CKIN SDMMC2_D4 FEMC_A14 SDRAM_BA0 USART6_CTS/USART6_NSS I2C1_SDA I2C8_SDA	-
G14	PG5	IO	TT	Yes	ETH2_MII_RXD3 SHRTIM1_CHF2 ATIM1_ETR DVP2_D15 SDMMC2_CDIN SDMMC2_D5 FEMC_A15 SDRAM_BA1 USART6_DE/USART6_RTS I2C1_SCL I2C8_SCL	-
G15	PG6	IO	TT	Yes	ETH2_MII_RX_ER SHRTIM1_CHE1 GTIMB3_BRK DVP1_D12 LCD_R7 FEMC_NE3 I2C1_SMBA I2C8_SMBA	-
F16	PG7	IO	TT	Yes	xSPI2_DQS ETH1_PHY_INTN SHRTIM1_CHE2 DVP1_D13 LCD_CLK FEMC_INT/FEMC_BUSY USART4_CK FDCAN7_TX	-
F15	PG8	IO	TT	Yes	SPI4_NSS I2S4_WS	-

					ETH1_PPS_OUT SHRTIM2_EEV ATIM2_ETR LCD_G7 SDRAM_CLK USART4_DE/USART4_RTS FDCAN7_RX SDRAM_CLK	
G16	VSS	S	-	-	-	-
G17	NC	S	-	-	-	-
F17	VDD33_USB	S	-	-	-	-
M5	VDD	S	-	-	-	-
F14	PC6	IO	FT	Yes	I2S2_MCK SHRTIM1_CHA1 ATIM2_CH1 GTIMA2_CH1 DVP1_D0 LCD_HSYNC SDMMC1_D0DIR SDMMC1_D6 SDMMC2_D6 FEMC_NWAIT USART4_TX DSMU_CKIN3	-
F13	PC7	IO	FT	Yes	TRGIO I2S3_MCK SHRTIM1_CHA2 ATIM2_CH2 GTIMA2_CH2 DVP1_D1 LCD_G6 SDMMC1_D123DIR SDMMC1_D7 SDMMC2_D7 FEMC_NE1/FEMC_NCE2 USART4_RX DSMU_DATIN3	-
E13	PC8	IO	FT	Yes	TRACED1 SHRTIM1_CHB1 ATIM2_CH3 GTIMA2_CH3 DVP1_D2 SDMMC1_D0 FEMC_NCE1/FEMC_NE2 FEMC_INT/FEMC_BUSY USART4_CK UART10_DE/UART10_RTS	-
E14	PC9	IO	TT	Yes	MCO2 I2S1_CKIN I2S2_CKIN I2S3_CKIN I2S4_CKIN GTIMA2_CH4 DVP1_D3 LCD_B2 LCD_G3 SDMMC1_D1 UART10_CTS I2C3_SDA I2C5_SDA	-
L5	VDD	S	-	-	-	-

E15	PA8	IO	FT	No	MCO1 ETH2_MII_RX_CLK/ETH2_RMII_REF_CLK SHRTIM1_CHB2 ATIM1_CH1 ATIM2_BKIN2 LCD_B3 LCD_R6 USART1_CK UART11_RX USB1_SOF I2C3_SCL I2C5_SCL	-
D15	PA9	IO	TT	No	SPI2_SCK I2S2_CK ETH1_MII_TX_ER/ETH1_GMII_TX_ER SHRTIM1_CHC1 ATIM1_CH2 DVP1_D0 LCD_R5 USART1_TX LPUART1_TX USB1_VBUS I2C3_SMBA I2C5_SMBA	-
D14	PA10	IO	FT	No	SHRTIM1_CHC2 ATIM1_CH3 DVP1_D1 LCD_B1 LCD_B4 USART1_RX LPUART1_RX USB1_ID	-
E17	PA11	IO	FT	No	SPI2_NSS I2S2_WS SHRTIM1_CHD1 ATIM1_CH4 LCD_R4 SDMMC1_SEL USART1_CTS/USART1_NSS UART9_RX LPUART1_CTS FDCAN1_RX USB1_DM	-
E16	PA12	IO	FT	No	SPI2_SCK I2S2_CK SHRTIM1_CHD2 ATIM1_BKIN2 ATIM1_ETR LCD_R5 USART1_DE/USART1_RTS UART9_TX LPUART1_RTS FDCAN1_TX USB1_DP	-
C15	PA13	IO	FT	Yes	JTMS-SWDIO	-
D17	VCAP	S	-	-	-	-
C17	NC	S	-	-	-	-
K5	VDD	S	-	-	-	-
D16	PH13	IO	TT	Yes	SPI7_NSS ETH2_MII_TX_EN/ETH2_RMII_TX_EN ATIM2_CH1N	-

					LCD_G2 FEMC_D21 SDRAM_D21 UART9_TX FDCAN1_TX I2C9_SMBA	
B17	PH14	IO	TT	Yes	SPI7_MISO ETH2_MII_TXD0/ETH2_RMII_TXD0 ATIM2_CH2N DVP1_D4 LCD_G3 FEMC_D22 SDRAM_D22 USART6_RX UART9_RX FDCAN1_RX I2C9_SDA	-
B16	PH15	IO	TT	Yes	SPI7_MOSI ETH2_MII_TXD1/ETH2_RMII_TXD1 ATIM2_CH3N DVP1_D11 LCD_G4 FEMC_D23 SDRAM_D23 USART6_TX I2C9_SCL	-
A16	PI0	IO	TT	Yes	SPI2_NSS I2S2_WS SHRTIM2_FLT ATIM2_CH4N GTIMA4_CH4 DVP1_D13 LCD_G5 FEMC_D24 SDRAM_D24 I2C10_SDA	-
A15	PI1	IO	TT	Yes	SPI2_SCK I2S2_CK ETH2_MII_RXD0/ETH2_RMII_RXD0 ATIM2_BKIN2 DVP1_D8 LCD_G6 FEMC_D25 SDRAM_D25 USART8_CK I2C8_SMBA I2C10_SCL SDRAM_D8	-
B15	PI2	IO	TT	Yes	SPI2_MISO I2S2_SD ETH2_MII_RXD1/ETH2_RMII_RXD1 ATIM2_CH4 DVP1_D9 LCD_G7 FEMC_D26 SDRAM_D26 USART8_RX LPUART2_TX I2C8_SDA SDRAM_D9	-

C14	PI3	IO	TT	Yes	SPI2_MOSI I2S2_SD_EXT ETH2_MII_RX_ER ATIM2_ETR DVP1_D10 FEMC_D27 SDRAM_D27 USART8_TX LPUART2_RX I2C8_SCL I2C10_SMBA SDRAM_D10	-
B14	PA14	IO	FT	Yes	JTCK-SWCLK	-
A14	PA15	IO	FT	Yes	JTDI SPI1_NSS SPI3_NSS SPI4_NSS I2S1_WS I2S3_WS I2S4_WS SHRTIM1_FLT GTIMA1_CH1 GTIMA1_ETR LCD_B6 LCD_R3 UART9_DE/UART9_RTS UART11_TX	-
A13	PC10	IO	TT	Yes	SPI3_SCK I2S3_CK SHRTIM1_EEV DVP1_D8 LCD_R2 LCD_B1 SDMMC1_D2 USART3_TX UART9_TX I2C5_SDA DSMU_CKIN5	-
B13	PC11	IO	TT	Yes	SPI3_MISO I2S3_SD SHRTIM1_FLT DVP1_D4 LCD_B4 SDMMC1_D3 USART3_RX UART9_RX I2C5_SCL DSMU_DATIN5	-
C12	PC12	IO	TT	Yes	TRACED3 SPI3_MOSI SPI4_SCK I2S3_SD_EXT I2S4_CK SHRTIM1_EEV GTIMB1_CH1P DVP1_D9 LCD_R6 SDMMC1_CK FEMC_D6/FEMC_DA6 SDRAM_D6 USART3_CK	-

					UART10_TX I2C5_SMBA	
D13	PD0	IO	TT	Yes	SHRTIM2_EEV GTIMB2_CH1N LCD_B1 SDMMC1_WP FEMC_D2/FEMC_DA2 SDRAM_D2 UART9_RX UART13_CTS FDCAN1_RX DSMU_CKIN6 SDRAM_D11	-
E12	PD1	IO	TT	Yes	SHRTIM2_FLT GTIMB2_CH1P SDMMC1_CD FEMC_D3/FEMC_DA3 SDRAM_D3 UART9_TX FDCAN1_TX I2C1_SMBA DSMU_DATIN6 SDRAM_D12	-
D12	PD2	IO	TT	Yes	TRACED2 GTIMA2_ETR GTIMB1_BRK GTIMB2_CH2 DVP1_D11 LCD_B2 LCD_B7 SDMMC1_CMD FEMC_D7/FEMC_DA7 SDRAM_D7 UART10_RX LPUART2_CTS SDRAM_D13	-
B12	PD3	IO	FT	Yes	SPI2_SCK I2S2_CK GTIMB2_CH3 DVP1_D5 LCD_G7 SDMMC1_RST FEMC_CLK USART2_CTS/USART2_NSS LPUART2_RTS DSMU_CKOUT	-
A12	PD4	IO	TT	Yes	SPI3_NSS SHRTIM1_FLT GTIMB2_CH4 DVP1_D14 SDMMC2_WP FEMC_NOE USART2_DE/USART2_RTS LPUART2_TX I2C1_SCL	-
A11	PD5	IO	TT	Yes	SPI3_MISO SHRTIM1_EEV GTIMB2_ETR DVP1_D15 SDMMC2_CD FEMC_NWE	-

					USART2_TX LPUART2_RX I2C1_SDA	
B11	PD6	IO	TT	Yes	SPI3_MOSI I2S3_SD_EXT DVP1_D10 LCD_B2 SDMMC2_CK FEMC_NWAIT USART2_RX DSMU_CKIN4 DSMU_DATIN1	-
C11	PD7	IO	TT	Yes	SPI1_MOSI SPI3_SCK I2S1_SD_EXT ATIM4_BKIN1 SDMMC2_CMD FEMC_NE1/FEMC_NCE2 USART2_CK DSMU_CKIN1 DSMU_DATIN4	-
D11	PJ12	IO	FT	Yes	TRGOUT ATIM4_CH3 DVP2_D15 LCD_B0 LCD_G3 SDMMC1_SEL I2C10_SMBA FEMC_BAA	-
E10	PJ13	IO	FT	Yes	ATIM4_CH3N DVP2_D14 LCD_B1 LCD_B4 SDMMC2_SEL I2C10_SDA FEMC_NBL0	-
D10	PJ14	IO	FT	Yes	SHRTIM2_EEV ATIM4_CH4 DVP2_D13 LCD_B2 FEMC_CRE I2C10_SCL	-
B10	PJ15	IO	FT	Yes	ATIM4_CH4N DVP2_D12 LCD_B3 FEMC_BAA	-
A10	PG9	IO	TT	Yes	SPI1_MISO I2S1_SD ETH2_MII_RXD0/ETH2_RMII_RXD0 SHRTIM1_FLT DVP1_VSYNC SDMMC2_D0 FEMC_NCE1/FEMC_NE2 USART4_RX FDCAN3_TX	-
A9	PG10	IO	TT	Yes	SPI1_NSS I2S1_WS xSPI2_IO6 xSPI2_NCS4 ETH2_MII_RXD1/ETH2_RMII_RXD1 SHRTIM1_FLT	-

					DVP1_D2 LCD_B2 LCD_G3 SDMMC2_D1 FEMC_NE3 FDCAN3_RX	
B9	PG11	IO	TT	Yes	SPI1_SCK I2S1_CK xSPI2_IO7 xSPI2_NCSIN ETH1_MII_TX_EN/ETH1_RMII_TX_EN/ETH1_GMII_TX_EN SHRTIM1_EEV LPTIM1_IN2 DVP1_D3 LCD_B3 SDMMC2_D2 USART5_RX	-
C9	PG12	IO	TT	Yes	SPI4_MISO I2S4_SD xSPI2_NCS1 ETH1_MII_TXD1/ETH1_RMII_TXD1/ETH1_GMII_TXD1 SHRTIM1_EEV GTIMA5_CH1 LPTIM1_IN1 DVP2_MCLK LCD_B1 LCD_B4 SDMMC2_D3 FEMC_NE4 USART4_DE/USART4_RTS USART5_TX	-
D9	PG13	IO	TT	Yes	TRACED0 SPI4_SCK I2S4_CK ETH1_MII_TXD0/ETH1_RMII_TXD0/ETH1_GMII_TXD0 SHRTIM1_EEV GTIMA5_CH2 LPTIM1_OUT LCD_R0 SDMMC2_D0DIR SDMMC2_D6 FEMC_A24 USART4_CTS/USART4_NSS USART5_CTS/USART5_NSS	-
D8	PG14	IO	TT	Yes	TRACED1 SPI4_MOSI I2S4_SD_EXT ETH1_MII_TXD1/ETH1_RMII_TXD1/ETH1_GMII_TXD1 GTIMA5_CH3 LPTIM1_ETR LCD_B0 SDMMC2_D123DIR SDMMC2_D7 FEMC_A25 USART4_TX USART5_DE/USART5_RTS	-

C8	PK3	IO	TT	Yes	xSPI2_IO6 SHRTIM1_EEV ATIM4_BKIN2 DVP2_D0 LCD_B4 I2C10_SDA FEMC_D7/FEMC_DA7	-
B8	PK4	IO	TT	Yes	xSPI2_IO7 SHRTIM1_EEV GTIMA6_CH1 DVP2_D1 LCD_B5 I2C10_SCL FEMC_D9/FEMC_DA9	-
A8	PK5	IO	TT	Yes	xSPI2_NCS1 GTIMA6_CH2 DVP2_D2 LCD_B6 I2C10_SMBA FEMC_D11/FEMC_DA11	-
C7	PK6	IO	TT	Yes	xSPI2_DQS SHRTIM2_FLT GTIMA6_CH3 DVP2_D3 LCD_B7 I2C10_SDA FEMC_A12	-
D7	PK7	IO	TT	Yes	GTIMA6_CH4 DVP2_D4 LCD_DE I2C10_SCL FEMC_A15	-
D6	PG15	IO	TT	Yes	xSPI2_DQS ETH1_PHY_INTN SHRTIM2_EEV DVP1_D13 SDMMC2_RST SDRAM_NCAS USART4_CTS/USART4_NSS USART5_CK SDRAM_D14	-
C6	PB3	IO	FT	Yes	TRACESWO/JTDO SPI1_SCK SPI3_SCK SPI4_SCK I2S1_CK I2S3_CK I2S4_CK SHRTIM1_FLT GTIMA1_CH2 GTIMA6_ETR SDMMC2_D2 UART11_RX	-
B7	PB4	IO	FT	Yes	JTRST SPI1_MISO SPI2_NSS SPI3_MISO SPI4_MISO I2S1_SD I2S2_WS I2S3_SD	-

					I2S4_SD ETH1_PHY_INTN SHRTIM1_EEV GTIMA2_CH1 GTIMB2_BRK SDMMC2_D3 UART11_TX	
A5	PB5	IO	TT	Yes	SPI1_MOSI/I2S1_SD_EXT SPI3_MOSI/I2S3_SD_EXT SPI4_MOSI/I2S4_SD_EXT ETH1_PPS_OUT SHRTIM1_EEV GTIMA2_CH2 GTIMB3_BRK DVP1_D10 LCD_B5 SDRAM_CKE1 UART10_RX FDCAN2_RX I2C1_SMBA I2C4_SMBA	-
B5	PB6	IO	TT	Yes	SHRTIM1_EEV GTIMA2_CH3 GTIMA3_CH1 GTIMB2_CH1N DVP1_D5 SDMMC1_D6 SDRAM_NCE1 USART1_TX UART10_TX LPUART1_TX FDCAN2_TX I2C1_SCL I2C4_SCL DSMU_DATIN5	-
C5	PB7	IO	TT	Yes	ETH1_MII_TXD2/ETH1_GMII_TXD2 SHRTIM1_EEV GTIMA2_CH4 GTIMA3_CH2 GTIMB3_CH1N DVP1_VSYNC SDMMC1_D7 FEMC_NL/FEMC_NADV USART1_RX LPUART1_RX I2C1_SDA I2C4_SDA DSMU_CKIN5	-
E8	BOOT0	I	BO OT	Yes	BOOT0	-
D5	PB8	IO	TT	Yes	ETH1_MII_TXD3/ETH1_GMII_TXD3 GTIMA2_ETR GTIMA3_CH3 GTIMB2_CH1P DVP1_D6 LCD_B6 SDMMC1_CKIN SDMMC1_D4 SDMMC2_D4 UART9_RX FDCAN1_RX	-

					I2C1_SCL I2C4_SCL DSMU_CKIN7	
D4	PB9	IO	FT	Yes	SPI2_NSS/I2S2_WS GTIMA3_CH4 GTIMB3_CH1P DVP1_D7 LCD_B7 SDMMC1_CDIRE SDMMC1_D5 SDMMC2_D5 UART9_TX FDCAN1_TX I2C1_SDA I2C4_SDA I2C4_SMBA DSMU_DATIN7	-
C4	PE0	IO	TT	Yes	SHRTIM1_SCIN GTIMA3_ETR GTIMB1_CH3 LPTIM1_ETR LPTIM2_ETR DVP1_D2 LCD_R0 FEMC_NBL0 SDRAM_DQM0 UART12_RX	-
B4	PE1	IO	TT	Yes	SHRTIM1_SCOUT GTIMB1_CH4 LPTIM1_IN2 DVP1_D3 LCD_R6 FEMC_NBL1 SDRAM_DQM1 UART12_TX SDRAM_D15	-
A7	VCAP	S	-	-	-	-
B6	VSS	S	-	-	-	-
E7	NC	S	-	-	-	-
A6	NC	S	-	-	-	-
A4	PI4	IO	TT	Yes	xSPI2_NCS2 ETH1_GMII_TXD4 ATIM2_BKIN1 DVP1_D5 DVP2_D8 LCD_B4 FEMC_NBL2 SDRAM_DQM2 USART8_RX I2C10_SMBA SDRAM_D0	-
A3	PI5	IO	TT	Yes	xSPI2_NCS3 ETH1_GMII_TXD5 ATIM2_CH1 DVP1_VSYNC DVP2_D9 LCD_B5 FEMC_NBL3 SDRAM_DQM3 USART8_TX	-

					I2C10_SDA SDRAM_D1	
A2	PI6	IO	TT	Yes	xSPI2_NCS4 ETH1_GMII_TXD6 SHRTIM1_FLT ATIM2_CH2 DVP1_D6 DVP2_D10 LCD_B6 FEMC_D28 SDRAM_D28 USART8_CK I2C10_SCL SDRAM_D2	-
B3	PI7	IO	TT	Yes	xSPI2_NCSIN ETH1_GMII_TXD7 ATIM2_CH3 DVP1_D7 DVP2_D11 LCD_B7 FEMC_D29 SDRAM_D29 SDRAM_D3	-
G7/ G8/ G9/ G10/ G11/ H7/ H8/ H9/ H10/ H11/ J7/ J8/ J9/ J10/ J11/ K7/ K8/ K9/ K10/ K11/ L7/ L8/ L9/ L10/ L11	VSS	S	-	-	-	-

Notes:

(1) I = input, O = output, S = power supply.

(2) FT: 5V toleran; TT: 3.3V IO.

(3) Fail-safe indicates that when the chip has no power input, a high input level is added to the IO. The high input level does not flood into the chip, resulting in a certain voltage on the power supply and current consumption.

3.3 GPIO Alternate Function

3.3.1 GPIOA Alternate Function

Table 3-2 GPIOA Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PA0	ETH1_MII_CRS/ETH1_GMII_CRS	SDMMC2_CMD	FEMC_A19	SPI4_NSS	I2S4_WS	ATIM2_ETR	GTIMA1_C H1	GTIMA1_E TR	GTIMA4_C H1	GTIMB1_B RK	USART2_C TS/USART2_NSS	UART9_TX	-	-	EVENTOUT	-
PA1	-	-	ETH1_MII_RX_CLK/E TH1_RMII_REF_CLK/E TH1_GMII_RX_CLK	LCD_R2	GTIMA1_C H2	GTIMA4_C H2	GTIMB1_C H1N	LPTIM3_O UT	USART2_D E/USART2_RTS	UART9_RX	-	-	-	-	EVENTOUT	-
PA2	-	ETH1_MDI_O	LCD_R1	GTIMA1_C H3	GTIMA4_C H3	GTIMB1_C H1P	LPTIM4_O UT	USART2_T X	-	-	-	-	-	-	EVENTOUT	-
PA3	-	-	ETH1_MII_COL/ETH1_GMII_COL	FEMC_A10	LCD_B2	LCD_B5	I2S4_MCK	GTIMA1_C H4	GTIMA4_C H4	GTIMB1_C H2	LPTIM5_O UT	USART2_R X	-	-	EVENTOUT	-
PA4	SDRAM_D8	FEMC_D8/F EMC_DA8	LCD_VSYN_C	DVP1_HSY NC	SPI1_NSS	SPI3_NSS	SPI4_NSS	I2S1_WS	I2S3_WS	I2S4_WS	GTIMA4_E TR	USART2_C K	USB2_SOF	-	EVENTOUT	-
PA5	SDRAM_D9	SDRAM_D_QM0	FEMC_D9/F EMC_DA9	LCD_R4	SPI1_SCK	SPI4_SCK	I2S1_CK	I2S4_CK	ATIM2_CH1_N	GTIMA1_C H1	GTIMA1_E TR	-	-	-	EVENTOUT	-
PA6	-	xSPI2_IO3	LCD_G2	DVP1_PIXC LK	SPI1_MISO	SPI4_MISO	I2S1_SD	I2S4_SD	ATIM1_BK1_N1	ATIM2_BK1_N1	ATIM3_CH1	GTIMA2_C H1	-	-	EVENTOUT	-
PA7	SDRAM_N WE	-	xSPI2_IO2	ETH1_MII_RX_DV/ETH1_RMII_CRS_DV/ETH1_GMII_RX_DV	LCD_VSYN_C	SPI1_MOSI	SPI4_MOSI	I2S1_SD_E XT	I2S4_SD_E XT	ATIM1_CH1_N	ATIM2_CH1_N	ATIM4_CH1	GTIMA2_C H2	-	EVENTOUT	-
PA8	ETH2_MII_RX_CLK/E TH2_RMII_REF_CLK	LCD_B3	LCD_R6	SHRTIM1_CHB2	ATIM1_CH1	ATIM2_BK1_N2	USART1_C K	UART11_R X	USB1_SOF	I2C3_SCL	I2C5_SCL	-	-	-	EVENTOUT	MCO1
PA9	ETH1_MII_TX_ER/ETH1_GMII_TX_ER	LCD_R5	DVP1_D0	SPI2_SCK	I2S2_CK	SHRTIM1_CHC1	ATIM1_CH2	USART1_T X	LPUART1_TX	USB1_VBUS	I2C3_SMBA	I2C5_SMBA	-	-	EVENTOUT	-
PA10	LCD_B1	LCD_B4	DVP1_D1	SHRTIM1_CHC2	ATIM1_CH3	USART1_R X	LPUART1_RX	USB1_ID	-	-	-	-	-	-	EVENTOUT	-
PA11	SDMMC1_SEL	LCD_R4	SPI2_NSS	I2S2_WS	SHRTIM1_CHD1	ATIM1_CH4	USART1_C TS	UART9_RX	LPUART1_CTS	FDCAN1_RX	USB1_DM	-	-	-	EVENTOUT	-
PA12	LCD_R5	SPI2_SCK	I2S2_CK	SHRTIM1_CHD2	ATIM1_BK1_N2	ATIM1_ETR	USART1_R TS	UART9_TX	LPUART1_RTS	FDCAN1_TX	USB1_DP	-	-	-	EVENTOUT	-
PA13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENTOUT	JTMS/SWDIO
PA14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENTOUT	JTCK/SWCLK
PA15	LCD_B6	LCD_R3	SPI1_NSS	SPI3_NSS	SPI4_NSS	I2S1_WS	I2S3_WS	I2S4_WS	-	GTIMA1_C H1	GTIMA1_E TR	UART9_DE/UART9_RTS	UART11_TX	-	EVENTOUT	JTDI

3.3.2 GPIOB Alternate Function

Table 3-3 GPIOB Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PB0	-	xSPI2_IO1	ETH1_MII_RXD2/ETH1_GMII_RXD2	LCD_G1	LCD_R3	ATIM1_CH2_N	ATIM2_CH2_N	GTIMA2_C_H3	UART9_CTS	DSMU_CKOUT	-	-	-	-	EVENTOUT	-
PB1	-	xSPI2_IO0	ETH1_MII_RXD3/ETH1_GMII_RXD3	LCD_G0	LCD_R6	DVP1_MCLK	SPI3_MISO	ATIM1_CH3_N	ATIM2_CH3_N	GTIMA2_C_H4	DSMU_DATIN1	-	-	-	EVENTOUT	-
PB2	-	-	xSPI2_CLK/xSPI2_CLKIN	ETH1_MII_TX_ER/ETH1_GMII_TX_ER	DVP1_HSYNC	DVP2_D12	SPI3_MOSI	I2S3_SD_EXT	ATIM1_CH4_N	ATIM2_CH4_N	GTIMA5_ETR	DSMU_CKIN1	-	-	EVENTOUT	RTC_OUT2
PB3	SDMMC2_D2	SPI1_SCK	SPI3_SCK	SPI4_SCK	I2S1_CK	I2S3_CK	I2S4_CK	-	GTIMA1_C_H2	GTIMA6_ETR	UART11_RX	-	-	-	EVENTOUT	JTDO/TRACESWO
PB4	ETH1_PHY_INTN	SDMMC2_D3	SPI1_MISO	SPI2_NSS	SPI3_MISO	SPI4_MISO	I2S1_SD	I2S2_WS	I2S3_SD	I2S4_SD	GTIMA2_C_H1	GTIMB2_BRK	UART11_TX	-	EVENTOUT	JTRST
PB5	SDRAM_CK_E1	-	ETH1_PPS_OUT	LCD_B5	DVP1_D10	SPI1_MOSI/I2S1_SD_EXT	SPI3_MOSI/I2S3_SD_EXT	SPI4_MOSI/I2S4_SD_EXT	GTIMA2_C_H2	GTIMB3_BRK	UART10_RX	FDCAN2_RX	I2C1_SMBA	I2C4_SMBA	EVENTOUT	-
PB6	SDRAM_NC_E1	-	SDMMC1_D6	DVP1_D5	GTIMA2_C_H3	GTIMA3_C_H1	GTIMB2_C_H1N	USART1_TX	UART10_TX	LPUART1_TX	FDCAN2_TX	I2C1_SCL	I2C4_SCL	DSMU_DATIN5	EVENTOUT	-
PB7	ETH1_MII_TXD2/ETH1_GMII_TXD2	SDMMC1_D7	FEMC_NL/FEMC_NADV	DVP1_VSYNC	-	GTIMA2_C_H4	GTIMA3_C_H2	GTIMB3_C_H1N	USART1_RX	LPUART1_RX	I2C1_SDA	I2C4_SDA	DSMU_CKIN5	-	EVENTOUT	-
PB8	ETH1_MII_TXD3	SDMMC1_CKIN	SDMMC1_D4	SDMMC2_D4	LCD_B6	DVP1_D6	GTIMA2_ETR	GTIMA3_C_H3	GTIMB2_C_H1P	UART9_RX	FDCAN1_RX	I2C1_SCL	I2C4_SCL	DSMU_CKIN7	EVENTOUT	-
PB9	SDMMC1_CDIR	SDMMC1_D5	SDMMC2_D5	LCD_B7	DVP1_D7	SPI2_NSS/I2S2_WS	GTIMA3_C_H4	GTIMB3_C_H1P	UART9_TX	FDCAN1_TX	I2C1_SDA	I2C4_SDA	I2C4_SMBA	DSMU_DATIN7	EVENTOUT	-
PB10	-	ETH1_MII_RX_ER/ETH1_GMII_RX_ER	FEMC_D13/FEMC_DAI3	LCD_G4	SPI2_SCK	I2S2_CK	SHRTIM1_SCOUT	GTIMA1_C_H3	LPTIM2_IN1	USART3_TX	I2C2_SCL	DSMU_DATIN7	-	-	EVENTOUT	-
PB11	ETH1_MII_TX_EN/ETH1_RMII_TX_EN/ETH1_GMII_TX_EN	FEMC_D15/FEMC_DAI5	LCD_G5	SHRTIM1_SCKIN	GTIMA1_C_H4	LPTIM2_ETR	USART3_RX	I2C2_SDA	DSMU_CKIN7	-	-	-	-	-	EVENTOUT	-
PB12	-	-	ETH1_MII_TXD0/ETH1_RMII_TXD0/ETH1_GMII_TXD0	-	DVP2_D14	SPI2_NSS/I2S2_WS	ATIM1_BKIN1	LPTIM2_IN2	USART3_CK	UART10_RX	FDCAN2_RX	USB2_ID	I2C2_SMBA	DSMU_DATIN1	EVENTOUT	-
PB13	-	ETH1_MII_TXD1/ETH1_RMII_TXD1/ETH1_GMII_TXD1	SDMMC1_D0	DVP1_D2	SPI2_SCK	I2S2_CK	ATIM1_CH1N	LPTIM2_OUT	USART3_CTS/USART3_NSS	UART10_TX	FDCAN2_TX	USB2_VBUS	DSMU_CKIN1	-	EVENTOUT	-
PB14	SDRAM_D10	SDMMC2_D0	FEMC_D10/FEMC_DAI0	LCD_CLK	SPI2_MISO	I2S2_SD	ATIM1_CH2N	ATIM2_CH2N	GTIMA7_C_H1	USART1_TX	USART3_DE/USART3_RTS	UART9_DE/UART9_RTS	USB2_DM	DSMU_DATIN2	EVENTOUT	-
PB15	SDRAM_D11	SDMMC2_D1	FEMC_D11/FEMC_DAI1	LCD_G7	SPI2_MOSI	I2S2_SD_EXT	ATIM1_CH3N	ATIM2_CH3N	GTIMA7_C_H2	USART1_RX	UART9_CTS	USB2_DP	DSMU_CKIN2	-	EVENTOUT	RTC_REFIN

3.3.3 GPIOC Alternate Function

Table 3-4 GPIOC Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PC0	SDRAM_NWE	SDRAM_D12	ETH2_MII_RX_DV/ETH2_RMII_CRS_DV	FEMC_A25	FEMC_D12/FEMC_DA12	LCD_G2	LCD_R5	DSMU_CK1N0	DSMU_DATIN4	-	-	-	-	-	EVENTOUT	-
PC1	-	ETH1_MDC	SDMMC2_CK	LCD_G5	SPI2_MOSI	I2S2_SD_EXT	DSMU_CK1N4	DSMU_DATIN0	FEMC_D0/FEMC_DA0	-	-	-	-	-	EVENTOUT	TRACED0
PC2	SDRAM_CE0	-	-	-	ETH1_MII_TXD2/ETH1_GMII_TXD2	DVP2_D6	SPI2_MISO	I2S2_SD	DSMU_CK1N1	DSMU_CKOUT	-	-	-	-	EVENTOUT	-
PC3	SDRAM_CKE0	-	-	-	ETH1_MII_TX_CLK/ETH1_GMII_TX_CLK	DVP2_D7	SPI2_MOSI	I2S2_SD_EXT	DSMU_DATIN1	-	-	-	-	-	EVENTOUT	-
PC4	SDRAM_NCE0	ETH1_MII_RXD0/ETH1_RMII_RXD0/ETH1_GMII_RXD0	SDMMC2_CKIN	FEMC_A22	LCD_R7	I2S1_MCK	DSMU_CK1N2	-	-	-	-	-	-	-	EVENTOUT	-
PC5	SDRAM_CKE0	-	ETH1_MII_RXD1/ETH1_RMII_RXD1/ETH1_GMII_RXD1	FEMC_A1	LCD_DE	DSMU_DATIN2	COMP1_OUT	SDRAM_NCAS	SDMMC2_SEL	-	-	-	-	-	EVENTOUT	-
PC6	SDMMC1_D0DIR	SDMMC1_D6	SDMMC2_D6	FEMC_NWAIT	LCD_HSYN_C	DVP1_D0	I2S2_MCK	SHRTIM1_CHA1	ATIM2_CH1	GTIMA2_CH1	USART4_TX	DSMU_CK1N3	-	-	EVENTOUT	-
PC7	SDMMC1_D123DIR	SDMMC1_D7	SDMMC2_D7	FEMC_NE1/FEMC_NCE2	LCD_G6	DVP1_D1	I2S3_MCK	SHRTIM1_CHA2	ATIM2_CH2	GTIMA2_CH2	USART4_RX	DSMU_DATIN3	-	-	EVENTOUT	TRGIO
PC8	SDMMC1_D0	FEMC_NCE1/FEMC_NE2	FEMC_INT/FEMC_BUSY	DVP1_D2	SHRTIM1_CHB1	ATIM2_CH3	GTIMA2_CH3	USART4_CK	UART10_DE/UART10_RTS	-	-	-	-	-	EVENTOUT	TRACED1
PC9	-	SDMMC1_D1	LCD_B2	LCD_G3	DVP1_D3	I2S1_CKIN	I2S2_CKIN	I2S3_CKIN	I2S4_CKIN	ATIM2_CH4	GTIMA2_CH4	UART10_CTS	I2C3_SDA	I2C5_SDA	EVENTOUT	MCO2
PC10	-	SDMMC1_D2	LCD_R2	LCD_B1	DVP1_D8	SPI3_SCK	I2S3_CK	USART3_TX	UART9_TX	I2C5_SDA	DSMU_CK1N5	-	-	-	EVENTOUT	-
PC11	-	SDMMC1_D3	LCD_B4	DVP1_D4	SPI3_MISO	I2S3_SD	-	USART3_RX	UART9_RX	I2C5_SCL	DSMU_DATIN5	-	-	-	EVENTOUT	-
PC12	SDRAM_D6	SDMMC1_CK	FEMC_D6/FEMC_DA6	LCD_R6	DVP1_D9	SPI3_MOSI	SPI4_SCK	I2S3_SD_EXT	I2S4_CK	GTIMB1_CHIP	USART3_CK	UART10_TX	I2C5_SMB_A	-	EVENTOUT	TRACED3
PC13	-	-	-	-	-	-	-	-	-	RTC_TAMP1/RTC_TS	-	-	-	-	EVENTOUT	RTC_OUT1
PC14	-	-	-	-	-	-	-	-	-	TIMESTAMP	-	-	-	-	EVENTOUT	-
PC15	-	-	-	-	-	-	-	-	-	TIMESTAMP	-	-	-	-	EVENTOUT	-

3.3.4 GPIOD Alternate Function

Table 3-5 GPIOD Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PD0	SDRAM_D2	SDRAM_D1_1	SDMMC1_WP	FEMC_D2/FEMC_DA2	LCD_B1	GTIMB2_C_H1N	UART9_RX	UART13_CTS	FDCAN1_RX	DSMU_CK1_N6	-	-	-	-	EVENTOUT	-
PD1	SDRAM_D3	SDRAM_D1_2	SDMMC1_CD	FEMC_D3/FEMC_DA3	GTIMB2_C_H1P	UART9_TX	FDCAN1_TX	I2C1_SMB_A	DSMU_DATIN6	-	-	-	-	-	EVENTOUT	-
PD2	SDRAM_D7	SDRAM_D1_3	SDMMC1_CMD	FEMC_D7/FEMC_DA7	LCD_B2	LCD_B7	DVP1_D11	GTIMA2_ETR	GTIMB1_B_RK	GTIMB2_C_H2	UART10_RX	LPUART2_CTS	-	-	EVENTOUT	TRACED2
PD3	SDMMC1_RST	FEMC_CLK	LCD_G7	DVP1_D5	SPI2_SCK	I2S2_CK	GTIMB2_C_H3	USART2_CTS/USART2_NSS	LPUART2_RTS	DSMU_CK_OUT	-	-	-	-	EVENTOUT	-
PD4	-	SDMMC2_WP	FEMC_NOE	DVP1_D14	SPI3_NSS	-	GTIMB2_C_H4	USART2_DE/USART2_RTS	LPUART2_TX	I2C1_SCL	-	-	-	-	EVENTOUT	-
PD5	-	SDMMC2_CD	FEMC_NWE	DVP1_D15	SPI3_MISO	GTIMB2_ETR	USART2_TX	LPUART2_RX	I2C1_SDA	-	-	-	-	-	EVENTOUT	-
PD6	-	SDMMC2_CK	FEMC_NW_AIT	LCD_B2	DVP1_D10	SPI3_MOSI	I2S3_SD_EX	USART2_RX	DSMU_CK1_N4	DSMU_DATIN1	-	-	-	-	EVENTOUT	-
PD7	-	SDMMC2_CMD	FEMC_NE1/FEMC_NC_E2	SPI1_MOSI	SPI3_SCK	I2S1_SD_EX	ATIM4_BK1_N1	USART2_CK	DSMU_CK1_N1	DSMU_DATIN4	-	-	-	-	EVENTOUT	-
PD8	SDRAM_D1_3	-	FEMC_D13/FEMC_DA1_3	DVP2_HSY_NC	SHRTIM2_SCIN	ATIM3_CH3	USART3_TX	I2C7_SDA	DSMU_CK1_N3	-	-	-	-	-	EVENTOUT	-
PD9	SDRAM_D1_4	FEMC_D14/FEMC_DA1_4	DVP2_VSY_NC	SHRTIM2_S_COUT	ATIM3_CH3N	USART3_RX	I2C7_SCL	DSMU_DATIN3	-	-	-	-	-	-	EVENTOUT	-
PD10	SDRAM_D1_5	ETH1_CLK_125	ETH2_PPS_OUT	FEMC_D15/FEMC_DA1_5	LCD_B3	ATIM1_CH4N	LPTIM2_OUT	USART3_CK	I2C7_SMB_A	DSMU_CK_OUT	-	-	-	-	EVENTOUT	-
PD11	-	FEMC_A16/FEMC_CLE	DVP2_D15	GTIMA3_ETR	LPTIM2_IN2	USART3_CTS/USART3_NSS	I2C4_SMB_A	-	-	-	-	-	-	-	EVENTOUT	-
PD12	-	FEMC_A17/FEMC_ALE	DVP1_D12	GTIMA3_CH1	LPTIM1_IN1	LPTIM2_IN1	USART3_DE/USART3_RTS	UART12_TX	UART13_CTS	FDCAN3_RX	I2C4_SCL	-	-	-	EVENTOUT	-
PD13	-	FEMC_A18	DVP1_D13	GTIMA3_CH2	LPTIM1_OUT	UART12_RX	UART13_DE/UART13_RTS	FDCAN3_TX	I2C4_SDA	I2C8_SMB_A	-	-	-	-	EVENTOUT	-
PD14	SDRAM_D0	SDRAM_CKE0	ETH1_PPS_OUT	SDMMC1_D4	FEMC_D0/FEMC_DA0	ATIM3_CH4	GTIMA3_CH3	UART12_CTS	UART13_RX	I2C8_SDA	-	-	-	-	EVENTOUT	-
PD15	SDRAM_D1	ETH1_PHY_INTN	ETH2_PHY_INTN	SDMMC1_D5	FEMC_D1/FEMC_DA1	ATIM3_CH4N	GTIMA3_CH4	UART12_DE/UART12_RTS	UART13_TX	I2C8_SCL	-	-	-	-	EVENTOUT	-

3.3.5 GPIOE Alternate Function

Table 3-6 GPIOE Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PE0	SDRAM_D_QM0	-	FEMC_NBL_0	LCD_R0	DVP1_D2	SHRTIM1_S_CIN	GTIMA3_ETR	GTIMB1_C_H3	LPTIM1_ETR	LPTIM2_ETR	UART12_RX	-	-	-	EVENTOUT	-
PE1	SDRAM_D_QM1	-	FEMC_NBL_1	LCD_R6	DVP1_D3	SHRTIM1_S_COUT	GTIMB1_C_H4	LPTIM1_IN2	UART12_TX	SDRAM_D1_5	-	-	-	-	EVENTOUT	-
PE2	-	ETH1_MII_TXD3/ETH1_GMII_TX_D3	FEMC_A23	DVP2_D0	SPI6_SCK	GTIMB1_ETR	USART5_RX	FDCAN4_TX	-	-	-	-	-	-	EVENTOUT	TRACECLK
PE3	ETH1_MII_TXD2/ETH1_GMII_TX_D2	FEMC_A19	DVP2_D1	GTIMB1_B_RK	USART5_TX	FDCAN4_RX	-	-	-	-	-	-	-	-	EVENTOUT	TRACED0
PE4	ETH2_PHY_INTN	FEMC_A20	LCD_B0	DVP1_D4	SPI6_NSS	GTIMB1_C_H1N	USART6_RX	DSMU_DATIN3	-	-	-	-	-	-	EVENTOUT	TRACED1
PE5	xSPI2_NCS_1	FEMC_A21	LCD_G0	DVP1_D6	SPI6_MISO	GTIMB1_C_H1P	USART6_TX	DSMU_CKIN3	-	-	-	-	-	-	EVENTOUT	TRACED2
PE6	FEMC_A22	LCD_G1	DVP1_D7	SPI6_MOSI	ATIM1_BKIN2	GTIMB1_C_H2	-	-	-	-	-	-	-	-	EVENTOUT	TRACED3
PE7	SDRAM_D4	-	-	xSPI2_NCS_2	ETH2_PHY_INTN	FEMC_D4/FEMC_DA4	ATIM1_ETR	UART11_RX	I2C7_SDA	DSMU_DATIN2	-	-	-	-	EVENTOUT	-
PE8	SDRAM_D5	SDRAM_A0	-	-	SDMMC1_LEDCTRL	FEMC_D5/FEMC_DA5	ATIM1_CH1N	UART11_TX	FDCAN5_TX	I2C7_SCL	DSMU_CKIN2	COMP2_OUT	-	-	EVENTOUT	-
PE9	SDRAM_D6	SDRAM_A1	-	-	SDMMC2_LEDCTRL	FEMC_D6/FEMC_DA6	ATIM1_CH1	UART11_DE/UART11_RTS	FDCAN5_RX	I2C7_SMB_A	DSMU_CKOUT	-	-	-	EVENTOUT	-
PE10	SDRAM_D7	SDRAM_A2	-	-	FEMC_D7/FEMC_DA7	ATIM1_CH2N	UART11_CTS	DSMU_DATIN4	-	-	-	-	-	-	EVENTOUT	-
PE11	SDRAM_D8	-	FEMC_D8/FEMC_DA8	LCD_G3	SPI6_NSS	ATIM1_CH2	DSMU_CKIN4	SDRAM_A3	-	-	-	-	-	-	EVENTOUT	-
PE12	SDRAM_D9	-	ETH1_GMII_RXD4	FEMC_D9/FEMC_DA9	LCD_B4	SPI6_SCK	ATIM1_CH3N	UART13_RX	DSMU_DATIN5	COMP1_OUT	-	-	-	-	EVENTOUT	-
PE13	SDRAM_D1_0	ETH1_GMII_RXD5	FEMC_D10/FEMC_DA1_0	LCD_DE	SPI6_MISO	ATIM1_CH3	UART13_TX	FDCAN6_TX	I2C6_SDA	DSMU_CKIN5	COMP2_OUT	-	-	-	EVENTOUT	-
PE14	SDRAM_D1_1	-	ETH1_GMII_RXD6	FEMC_D11	LCD_CLK	SPI6_MOSI	ATIM1_CH4	USART6_CK	UART13_CTS	FDCAN6_RX	I2C6_SCL	-	-	-	EVENTOUT	-
PE15	SDRAM_D1_2	ETH1_GMII_RXD7	FEMC_D12/FEMC_DA1_2	LCD_R7	ATIM1_BKIN1	USART5_CK	UART13_DE/UART13_RTS	I2C6_SMB_A	-	-	-	-	-	-	EVENTOUT	-

3.3.6 GPIOF Alternate Function

Table 3-7 GPIOF Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PF0	SDRAM_A0	xSPI2_IO0	ETH1_GMII_TXD4	FEMC_A0	DVP2_D0	SHRTIM2_CHA1	GTIMA1_C_H1	GTIMA5_C_H1	USART1_TX	FDCAN4_TX	I2C2_SDA	I2C5_SDA	COMP3_OUT	-	EVENTOUT	-
PF1	SDRAM_A1	SDRAM_D5	xSPI2_IO1	ETH1_GMII_TXD5	FEMC_A1	DVP2_D1	SHRTIM2_CHA2	GTIMA1_C_H2	GTIMA5_C_H2	USART1_RX	FDCAN4_RX	I2C2_SCL	I2C5_SCL	-	EVENTOUT	-
PF2	SDRAM_A2	xSPI2_IO2	ETH1_GMII_TXD6	FEMC_A2	DVP2_D2	SPI6_NSS	SHRTIM2_CHB1	GTIMA1_C_H3	GTIMA5_C_H3	GTIMB2_ETR	USART1_CK	I2C2_SMB_A	I2C5_SMB_A	-	EVENTOUT	-
PF3	SDRAM_A3	xSPI2_IO3	ETH1_GMII_TXD7	FEMC_A3	DVP2_D3	SPI6_SCK	SHRTIM2_CHB2	GTIMA1_C_H4	GTIMA5_C_H4	GTIMB2_C_H4	USART1_CTS/USART1_NSS	I2C6_SDA	-	-	EVENTOUT	-
PF4	SDRAM_A4	SDRAM_D4	xSPI2_CLK/xSPI2_CLKIN	ETH2_MII_RX_CLK/ETH2_RMII_REF_CLK	FEMC_A4	DVP2_D4	SPI6_MISO	SHRTIM2_CHC1	GTIMA1_ETR	GTIMB2_C_H3	USART1_DE/USART1_RTS	FDCAN5_TX	I2C6_SCL	-	EVENTOUT	-
PF5	SDRAM_A5	xSPI2_NCLK	ETH1_GMII_GTX_CLK	FEMC_A5	DVP2_D5	SPI6_MOSI	SHRTIM2_CHC2	ATIM3_BKIN1	GTIMB2_C_H2	FDCAN5_RX	I2C6_SMB_A	-	-	-	EVENTOUT	-
PF6	-	xSPI2_IO3	ETH2_MDI0	DVP1_PIXCLK	DVP2_D5	SPI5_NSS	ATIM3_ETR	ATIM4_ETR	GTIMA5_C_H1	GTIMB2_C_H1P	UART11_RX	FDCAN3_RX	-	-	EVENTOUT	-
PF7	-	xSPI2_IO2	ETH2_MDC	DVP2_PIXCLK	SPI5_SCK	ATIM3_CH4	ATIM4_CH3	GTIMA5_C_H2	GTIMB3_C_H1P	UART11_TX	FDCAN3_TX	-	-	-	EVENTOUT	-
PF8	-	xSPI2_IO0	ETH2_MII_COL	SDMMC2_LEDCTRL	DVP2_HSYNC	SPI5_MISO	ATIM3_CH1	ATIM4_CH4	GTIMA5_C_H3	GTIMB2_C_H1N	UART11_DE/UART11_RTS	-	-	-	EVENTOUT	-
PF9	-	xSPI2_IO1	ETH2_MII_CRS	SDMMC1_LEDCTRL	DVP2_VSYNC	SPI5_MOSI	-	ATIM3_CH2	ATIM4_CH1	GTIMA5_C_H4	GTIMB3_C_H1N	UART11_CTS	-	-	EVENTOUT	-
PF10	-	xSPI2_CLK/xSPI2_CLKIN	ETH2_PPS_OUT	LCD_DE	DVP1_D11	ATIM3_CH3	ATIM4_CH2	GTIMB2_BRRK	FEMC_A3	-	-	-	-	-	EVENTOUT	-
PF11	SDRAM_N_RAS	-	DVP1_D12	SPI5_MOSI	GTIMA6_C_H1	I2C6_SDA	ETH2_MII_TX_EN/ETH2_RMII_TX_EN	-	-	-	-	-	-	-	EVENTOUT	-
PF12	SDRAM_A6	xSPI2_DQS	ETH2_MII_TXD0/ETH2_RMII_TXD0	FEMC_A6	DVP2_D6	GTIMA6_C_H2	FDCAN6_TX	I2C6_SCL	-	-	-	-	-	-	EVENTOUT	-
PF13	SDRAM_A7	SDRAM_N_CE0	ETH2_MII_TXD1/ETH2_RMII_TXD1	FEMC_A7	DVP2_D7	-	GTIMA6_C_H3	USART7_CK	FDCAN6_RX	I2C4_SMB_A	I2C6_SMB_A	DSMU_DATIN6	COMP3_OUT	-	EVENTOUT	-
PF14	SDRAM_A8	ETH2_MII_TXD2	FEMC_A8	DVP2_D8	SHRTIM2_CHF1	GTIMA6_C_H4	USART7_RX	FDCAN3_RX	I2C4_SCL	DSMU_CKIN6	-	-	-	-	EVENTOUT	-
PF15	SDRAM_A9	SDRAM_B_A0	ETH2_MII_TXD3	FEMC_A9	DVP2_D9	SHRTIM2_CHF2	LPTIM4_ETR	USART7_TX	FDCAN3_TX	I2C4_SDA	-	-	-	-	EVENTOUT	-

3.3.7 GPIOG Alternate Function

Table 3-8 GPIOG Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PG0	SDRAM_A1_0	SDRAM_BA1	xSPI2_IO4	xSPI2_NCS_2	ETH2_MII_TX_CLK	FEMC_A10	DVP2_D10	ATIM4_BK1_N1	LPTIM4_IN1	UART13_RX	-	-	-	-	EVENTOUT	-
PG1	SDRAM_A1_1	SDRAM_A10	xSPI2_IO5	xSPI2_NCS_3	ETH2_MII_TX_ER	FEMC_A11	DVP2_D11	-	GTIMB1_ETR	LPTIM4_IN2	UART13_TX	-	-	-	EVENTOUT	-
PG2	SDRAM_A1_2	SDRAM_DQM1	ETH2_MII_RXD0/ETH2_RMII_RXD0	FEMC_A12	DVP2_D12	SHRTIM2_SCIN	ATIM2_BK1_N1	GTIMA6_ETR	USART7_CTS/USART7_NSS	FDCAN8_TX	-	-	-	-	EVENTOUT	-
PG3	ETH2_MII_RXD1/ETH2_RMII_RXD1	FEMC_A13	DVP2_D13	SHRTIM2_SCOUT	ATIM2_BKIN2	GTIMA5_ETR	USART7_DE/USART7_RTS	FDCAN8_RX	-	-	-	-	-	-	EVENTOUT	-
PG4	SDRAM_BA0	ETH2_MII_RXD2	SDMMC2_CK1N	SDMMC2_D4	FEMC_A14	DVP2_D14	SHRTIM1_CHF1	ATIM1_BK1_N2	USART6_CTS/USART6_NSS	I2C1_SDA	I2C8_SDA	-	-	-	EVENTOUT	-
PG5	SDRAM_BA1	-	ETH2_MII_RXD3	SDMMC2_CD1R	SDMMC2_D5	FEMC_A15	DVP2_D15	SHRTIM1_CHF2	ATIM1_ETR	USART6_DE/USART6_RTS	I2C1_SCL	I2C8_SCL	-	-	EVENTOUT	-
PG6	-	ETH2_MII_RX_ER	FEMC_NE3	LCD_R7	DVP1_D12	SHRTIM1_CHE1	GTIMB3_BK	I2C1_SMB_A	I2C8_SMB_A	-	-	-	-	-	EVENTOUT	-
PG7	xSPI2_DQS	ETH1_PHY_INTN	FEMC_INT/FEMC_BUSY	LCD_CLK	DVP1_D13	SHRTIM1_CHE2	USART4_CK	FDCAN7_TX	-	-	-	-	-	-	EVENTOUT	-
PG8	SDRAM_CLK	-	ETH1_PPS_OUT	LCD_G7	SPI4_NSS	I2S4_WS	ATIM2_ETR	USART4_DE/USART4_RTS	FDCAN7_RX	-	-	-	-	-	EVENTOUT	-
PG9	-	ETH2_MII_RXD0/ETH2_RMII_RXD0	SDMMC2_D0	FEMC_NE1/FEMC_NE2	DVP1_VSYNC	SPI1_MISO	I2S1_SD	USART4_RX	FDCAN3_TX	-	-	-	-	-	EVENTOUT	-
PG10	xSPI2_IO6	xSPI2_NC_S4	ETH2_MII_RXD1/ETH2_RMII_RXD1	SDMMC2_D1	FEMC_NE3	LCD_B2	LCD_G3	DVP1_D2	SPI1_NSS	I2S1_WS	-	FDCAN3_RX	-	-	EVENTOUT	-
PG11	xSPI2_IO7	xSPI2_NC_SIN	ETH1_MII_TXEN/ETH1_RMII_TXEN/ETH1_GMII_TXEN	SDMMC2_D2	LCD_B3	DVP1_D3	SPI1_SCK	I2S1_CK	LPTIM1_IN2	USART5_RX	-	-	-	-	EVENTOUT	-
PG12	xSPI2_NCS_1	ETH1_MII_TXD1/ETH1_RMII_TXD1/ETH1_GMII_TXD1	SDMMC2_D3	FEMC_NE4	LCD_B1	LCD_B4	DVP2_MCLK	SPI4_MISO	I2S4_SD	GTIMA5_CHI	LPTIM1_IN1	USART4_DE/USART4_RTS	USART5_TX	-	EVENTOUT	-
PG13	ETH1_MII_TXD0/ETH1_RMII_TXD0/ETH1_GMII_TXD0	SDMMC2_D0DIR	SDMMC2_D6	FEMC_A24	LCD_R0	SPI4_SCK	I2S4_CK	GTIMA5_CH2	LPTIM1_OUT	USART4_CTS/USART4_NSS	USART5_CTS/USART5_NSS	-	-	-	EVENTOUT	TRACED0
PG14	-	ETH1_MII_TXD1/ETH1_RMII_TXD1/ETH1_GMII_TXD1	SDMMC2_D12_3DIR	SDMMC2_D7	FEMC_A25	LCD_B0	SPI4_MOSI	I2S4_SD_EXT	GTIMA5_CH3	LPTIM1_ETR	USART4_TX	USART5_DE/USART5_RTS	-	-	EVENTOUT	TRACED1
PG15	SDRAM_NCAS	xSPI2_DQS	ETH1_PHY_INTN	SDMMC2_RST	DVP1_D13	USART4_CTS/USART4_NSS	USART5_CK	SDRAM_D14	-	-	-	-	-	-	EVENTOUT	-

3.3.8 GPIOH Alternate Function

Table 3-9 GPIOH Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PH0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENTOUT	-
PH1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENTOUT	-
PH2	SDRAM_CKE0	-	-	xSPI2_IO4	ETH1_MII_CRS/ETH1_GMII_CRS	LCD_R0	SHRTIM2_CHD1	GTIMB3_C H2	LPTIM1_IN2	UART15_RX	-	-	-	-	EVENTOUT	-
PH3	SDRAM_NCE0	-	xSPI2_IO5	ETH1_MII_COL/ETH1_GMII_COL	LCD_R1	SHRTIM2_CHD2	GTIMB3_C H3	USART7_CK	UART15_TX	-	-	-	-	-	EVENTOUT	-
PH4	ETH2_MII_TXD0/ETH2_RMII_TXD0	LCD_G4	LCD_G5	DVP2_HSYNC	SHRTIM2_CHE1	GTIMB3_C H4	USART7_RX	UART15_DE/UART15_RTS	FDCAN5_TX	I2C2_SCL	-	-	-	-	EVENTOUT	-
PH5	SDRAM_NWE	ETH2_MII_TXD1/ETH2_RMII_TXD1	DVP2_PIXCLK	SPI5_NSS	SHRTIM2_CHE2	GTIMB3_ETR	USART7_TX	UART15_CTS	FDCAN5_RX	I2C2_SDA	-	-	-	-	EVENTOUT	-
PH6	SDRAM_NCE1	SDRAM_A4	ETH1_MII_RXD2/ETH1_GMII_RXD2	FEMC_BA A	DVP1_D8	SPI5_SCK	ATIM3_CH4N	GTIMA7_C H1	LPTIM5_IN1	UART14_RX	FDCAN7_TX	I2C2_SMB A	-	-	EVENTOUT	-
PH7	SDRAM_CKE1	ETH1_MII_RXD3/ETH1_GMII_RXD3	FEMC_CRE	DVP1_D9	SPI5_MISO	ATIM3_BK1N1	LPTIM5_IN2	UART14_TX	FDCAN7_RX	I2C3_SCL	SDRAM_A5	-	-	-	EVENTOUT	-
PH8	SDRAM_D16	SDRAM_A6	ETH1_GMII_RXD4	FEMC_D16	LCD_R2	DVP1_HSYNC	ATIM3_CH1	GTIMA4_ETR	UART10_DE/UART10_RTS	UART14_DE/UART14_RTS	FDCAN2_RX	I2C3_SDA	COMP4_OUT	-	EVENTOUT	-
PH9	SDRAM_D17	ETH1_GMII_RXD5	FEMC_D17	LCD_R3	DVP1_D0	ATIM3_CH1N	GTIMA7_C H2	UART10_CTS	UART14_CTS	FDCAN2_TX	I2C3_SMB A	SDRAM_A7	-	-	EVENTOUT	-
PH10	SDRAM_D18	SDRAM_A8	ETH1_GMII_RXD6	FEMC_D18	LCD_R4	DVP1_D1	ATIM3_CH2	GTIMA4_C H1	I2C4_SMB A	-	-	-	-	-	EVENTOUT	-
PH11	SDRAM_D19	ETH1_GMII_RXD7	FEMC_D19	LCD_R5	DVP1_D2	ATIM3_CH2N	GTIMA4_C H2	UART10_RX	I2C4_SCL	SDRAM_A9	-	-	-	-	EVENTOUT	-
PH12	SDRAM_D20	SDRAM_A11	ETH2_MII_RX_DV/ETH2_RMII_CRS_DV	FEMC_D20	LCD_R6	DVP1_D3	SPI7_NSS	ATIM3_ETR	GTIMA4_C H3	UART10_TX	I2C4_SDA	COMP4_OUT	-	-	EVENTOUT	-
PH13	SDRAM_D21	ETH2_MII_TX_EN/ETH2_RMII_TX_EN	FEMC_D21	LCD_G2	SPI7_NSS	ATIM2_CH1N	UART9_TX	FDCAN1_TX	I2C9_SMB A	-	-	-	-	-	EVENTOUT	-
PH14	SDRAM_D22	ETH2_MII_TXD0/ETH2_RMII_TXD0	FEMC_D22	LCD_G3	DVP1_D4	SPI7_MISO	ATIM2_CH2N	USART6_RX	UART9_RX	FDCAN1_RX	I2C9_SDA	-	-	-	EVENTOUT	-
PH15	SDRAM_D23	-	ETH2_MII_TXD1/ETH2_RMII_TXD1	FEMC_D23	LCD_G4	DVP1_D11	SPI7_MOSI	ATIM2_CH3N	USART6_TX	I2C9_SCL	-	-	-	-	EVENTOUT	-

3.3.9 GPIOI Alternate Function

Table 3-10 GPIOI Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PI0	SDRAM_D2_4	FEMC_D24	LCD_G5	DVP1_D13	SPI2_NSS	I2S2_WS	ATIM2_CH4N	GTIMA4_C4H	I2C10_SDA	-	-	-	-	-	EVENTOUT	-
PI1	SDRAM_D2_5	SDRAM_D8	ETH2_MII_RXD0	FEMC_D25	LCD_G6	DVP1_D8	SPI2_SCK	I2S2_CK	ATIM2_BK1N2	USART8_CK	I2C8_SMB_A	I2C10_SCL	-	-	EVENTOUT	-
PI2	SDRAM_D2_6	ETH2_MII_RXD1	FEMC_D26	LCD_G7	DVP1_D9	SPI2_MISO	I2S2_SD	ATIM2_CH4	USART8_RX	LPUART2_TX	I2C8_SDA	SDRAM_D9	-	-	EVENTOUT	-
PI3	SDRAM_D2_7	SDRAM_D10	ETH2_MII_RX_ER	FEMC_D27	DVP1_D10	SPI2_MOSI	I2S2_SD_XT	ATIM2_ETR	USART8_TX	LPUART2_RX	I2C8_SCL	I2C10_SMB_A	-	-	EVENTOUT	-
PI4	SDRAM_DQM2	xSPI2_NCS2	ETH1_GMII_TXD4	FEMC_NBL2	LCD_B4	DVP1_D5	DVP2_D8	ATIM2_BK1N1	USART8_RX	I2C10_SMB_A	SDRAM_D0	-	-	-	EVENTOUT	-
PI5	SDRAM_DQM3	SDRAM_D1	xSPI2_NCS3	ETH1_GMII_TXD5	FEMC_NBL3	LCD_B5	DVP1_VSYN_C	DVP2_D9	ATIM2_CH1	USART8_TX	I2C10_SDA	-	-	-	EVENTOUT	-
PI6	SDRAM_D2_8	xSPI2_NCS4	ETH1_GMII_TXD6	FEMC_D28	LCD_B6	DVP1_D6	DVP2_D10	ATIM2_CH2	USART8_CK	I2C10_SCL	SDRAM_D2	-	-	-	EVENTOUT	-
PI7	SDRAM_D2_9	SDRAM_D3	xSPI2_NCS1N	ETH1_GMII_TXD7	FEMC_D29	LCD_B7	DVP1_D7	DVP2_D11	ATIM2_CH3	-	-	-	-	-	EVENTOUT	-
PI8	ETH2_MII_TX_CLK	SDMMC1_SEL	SDMMC2_SEL	SPI7_SCK	LPTIM3_IN1	FDCAN1_TX	-	-	-	-	-	-	-	-	EVENTOUT	RTC_OUT2
PI9	SDRAM_D3_0	xSPI2_IO0	FEMC_D30	LCD_VSYN_C	-	GTIMA7_C4H3	LPTIM3_IN2	UART9_RX	FDCAN1_RX	I2C9_SMB_A	SDRAM_D6	-	-	-	EVENTOUT	-
PI10	SDRAM_D3_1	SDRAM_D7	xSPI2_IO1	ETH1_MII_RX_ER	FEMC_D31	LCD_HSYN_C	GTIMA7_C4H4	LPTIM3_ETR	FDCAN4_TX	I2C9_SDA	-	-	-	-	EVENTOUT	-
PI11	xSPI2_IO2	SDMMC1_LEDCTRL	SDMMC2_LEDCTRL	FEMC_D0	LCD_G6	GTIMA7_ETR	FDCAN4_RX	I2C9_SCL	-	-	-	-	-	-	EVENTOUT	-
PI12	xSPI2_IO3	FEMC_A4	LCD_HSYN_C	DVP2_D2	SPI7_NSS	GTIMA7_C4H3	FDCAN6_TX	I2C7_SDA	-	-	-	-	-	-	EVENTOUT	-
PI13	xSPI2_CLK	FEMC_A7	LCD_VSYN_C	DVP2_D3	SPI7_MISO	GTIMA7_C4H4	FDCAN6_RX	I2C7_SCL	-	-	-	-	-	-	EVENTOUT	-
PI14	xSPI2_NCLK	FEMC_A9	LCD_CLK	DVP2_D4	SPI7_MOSI	ATIM3_BK1N2	GTIMA7_ETR	I2C7_SMB_A	-	-	-	-	-	-	EVENTOUT	-
PI15	ETH2_PPS_OUT	LCD_G2	LCD_R0	DVP2_D13	ATIM3_BK1N2	GTIMB3_ETR	-	-	-	-	-	-	-	-	EVENTOUT	-

3.3.10 GPIOJ Alternate Function

Table3-11 GPIOJ Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PJ0	ETH2_MII_TXD2	LCD_R1	LCD_R7	-	ATIM4_ETR	GTIMB3_CHIN	UART15_RX	FDCAN8_TX	I2C9_SDA	-	-	-	-	-	EVENTOUT	-
PJ1	xSPI2_IO4	ETH2_MII_TXD3	LCD_R2	DVP2_VSYNC	SPI7_SCK	ATIM4_CH1	GTIMB3_CHIP	UART15_TX	FDCAN8_RX	I2C9_SCL	-	-	-	-	EVENTOUT	-
PJ2	xSPI2_IO5	LCD_R3	DVP1_D15	SPI7_NSS	ATIM4_CH1N	GTIMB3_CH2	UART15_RTS	I2C9_SMB_A	-	-	-	-	-	-	EVENTOUT	-
PJ3	ETH2_MII_RX_DV	LCD_R4	DVP1_D14	SPI7_MISO	ATIM4_CH2	GTIMB3_CH3	UART13_RTS	UART15_CTS	FDCAN7_TX	I2C9_SDA	-	-	-	-	EVENTOUT	-
PJ4	ETH2_MII_RX_CLK	LCD_R5	DVP1_D13	SPI7_MOSI	ATIM4_CH2N	GTIMB3_CH4	UART13_CTS	FDCAN7_RX	I2C9_SCL	-	-	-	-	-	EVENTOUT	-
PJ5	ETH2_MII_TX_ER	LCD_R6	DVP1_D9	-	ATIM4_BKIN2	LPTIM5_ETR	-	-	-	-	-	-	-	-	EVENTOUT	-
PJ6	FEMC_D2	LCD_R7	DVP2_D8	ATIM2_CH2	FDCAN7_TX	-	-	-	-	-	-	-	-	-	EVENTOUT	-
PJ7	FEMC_D3	LCD_G0	DVP2_D9	ATIM2_CH2N	FDCAN7_RX	-	-	-	-	-	-	-	-	-	EVENTOUT	TRGIN
PJ8	ETH2_MII_RXD2	LCD_G1	DVP2_D10	ATIM1_CH3N	ATIM2_CH1	USART8_CTS	UART12_TX	UART14_RTS	FDCAN8_TX	I2C8_SDA	-	-	-	-	EVENTOUT	-
PJ9	ETH2_MII_RXD3	LCD_G2	DVP2_D11	ATIM1_CH3	ATIM2_CH1N	USART8_RTS	UART12_RX	UART14_CTS	FDCAN8_RX	I2C8_SCL	-	-	-	-	EVENTOUT	-
PJ10	FEMC_D5/ FEMC_DA5	LCD_G3	DVP2_D12	SPI5_MOSI	ATIM1_CH2N	ATIM2_CH2	UART12_CTS	UART14_RX	I2C8_SMB_A	-	-	-	-	-	EVENTOUT	-
PJ11	FEMC_D6/ FEMC_DA6	LCD_G4	DVP2_D13	SPI5_MISO	ATIM1_CH2	ATIM2_CH2N	UART12_RTS	UART14_TX	-	-	-	-	-	-	EVENTOUT	-
PJ12	SDMMC1_SEL	FEMC_BA_A	LCD_B0	LCD_G3	DVP2_D15	ATIM4_CH3	I2C10_SMB_A	-	-	-	-	-	-	-	EVENTOUT	TRGOUT
PJ13	SDMMC2_SEL	FEMC_NBL0	LCD_B1	LCD_B4	DVP2_D14	ATIM4_CH3N	I2C10_SDA	-	-	-	-	-	-	-	EVENTOUT	-
PJ14	FEMC_CRE	LCD_B2	DVP2_D13	ATIM4_CH4	I2C10_SCL	-	-	-	-	-	-	-	-	-	EVENTOUT	-
PJ15	FEMC_BA_A	LCD_B3	DVP2_D12	ATIM4_CH4N	-	-	-	-	-	-	-	-	-	-	EVENTOUT	-

3.3.11 GPIOK Alternate Function

Table 3-1 GPIOK Alternate Function

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
PK0	ETH2_MII_COL	LCD_G5	DVP2_D7	SPI5_SCK	ATIM1_CH1N	ATIM2_CH3	I2C3_SCL	-	-	-	-	-	-	-	EVENTOUT	-
PK1	ETH2_MII_CRS	LCD_G6	DVP2_D6	SPI5_NSS	ATIM1_CH1	ATIM2_CH3N	I2C3_SDA	-	-	-	-	-	-	-	EVENTOUT	-
PK2	FEMC_A11	LCD_G7	DVP2_D5	ATIM1_BK1N1	ATIM2_BK1N1	I2C3_SMB_A	-	-	-	-	-	-	-	-	EVENTOUT	-
PK3	xsPI2_IO6	FEMC_D7	LCD_B4	DVP2_D0	ATIM4_BK1N2	I2C10_SDA	-	-	-	-	-	-	-	-	EVENTOUT	-
PK4	xsPI2_IO7	FEMC_D9	LCD_B5	DVP2_D1	GTIMA6_C_H1	I2C10_SCL	-	-	-	-	-	-	-	-	EVENTOUT	-
PK5	xsPI2_NCS1	FEMC_D11	LCD_B6	DVP2_D2	GTIMA6_C_H2	I2C10_SMB_A	-	-	-	-	-	-	-	-	EVENTOUT	-
PK6	xsPI2_DQS	FEMC_A12	LCD_B7	DVP2_D3	GTIMA6_C_H3	I2C10_SDA	-	-	-	-	-	-	-	-	EVENTOUT	-
PK7	-	FEMC_A15	LCD_DE	DVP2_D4	GTIMA6_C_H4	I2C10_SCL	-	-	-	-	-	-	-	-	EVENTOUT	-

4 Electrical Characteristics

4.1 Test Conditions

Unless otherwise specified, all voltages are referenced to VSS.

4.1.1 Minimum and Maximum Values

Notes under each table indicate data obtained through comprehensive evaluation, design simulation, and/or process characteristics, which will not be tested in production lines. Based on comprehensive evaluation, minimum and maximum values are derived by taking the average value from sample testing, plus or minus three times the standard distribution (average $\pm 3\Sigma$).

4.1.2 Typical Values

Unless otherwise specified, typical data is based on $T_A=25^\circ\text{C}$ and $V_{DD}=3.3\text{V}$ (voltage range $2.3\text{V} \leq V_{DD} \leq 3.6\text{V}$). These data are provided only as design guidance and are not tested.

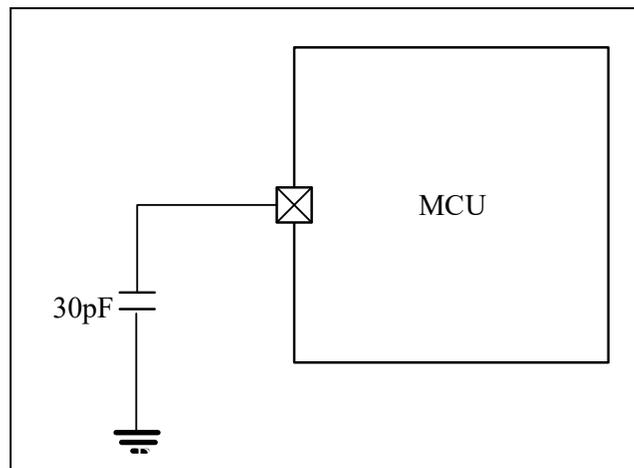
4.1.3 Typical Curves

Unless otherwise specified, typical curves are provided only as design guidance and are not tested.

4.1.4 Load Capacitance

The load conditions for measuring pin parameters are shown in Figure 4-1.

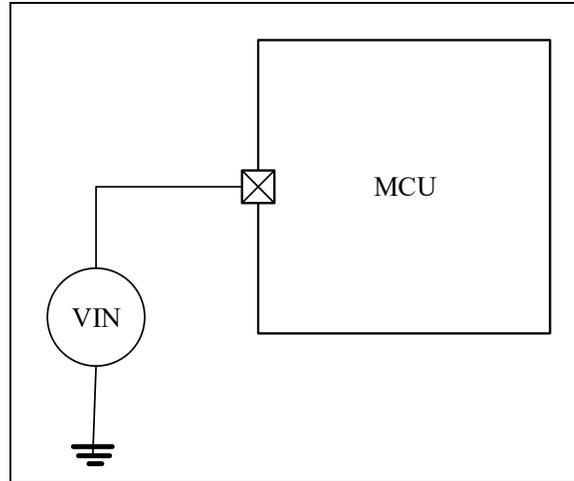
Figure 4-1 Load Conditions for Pins



4.1.5 Pin Input Voltage

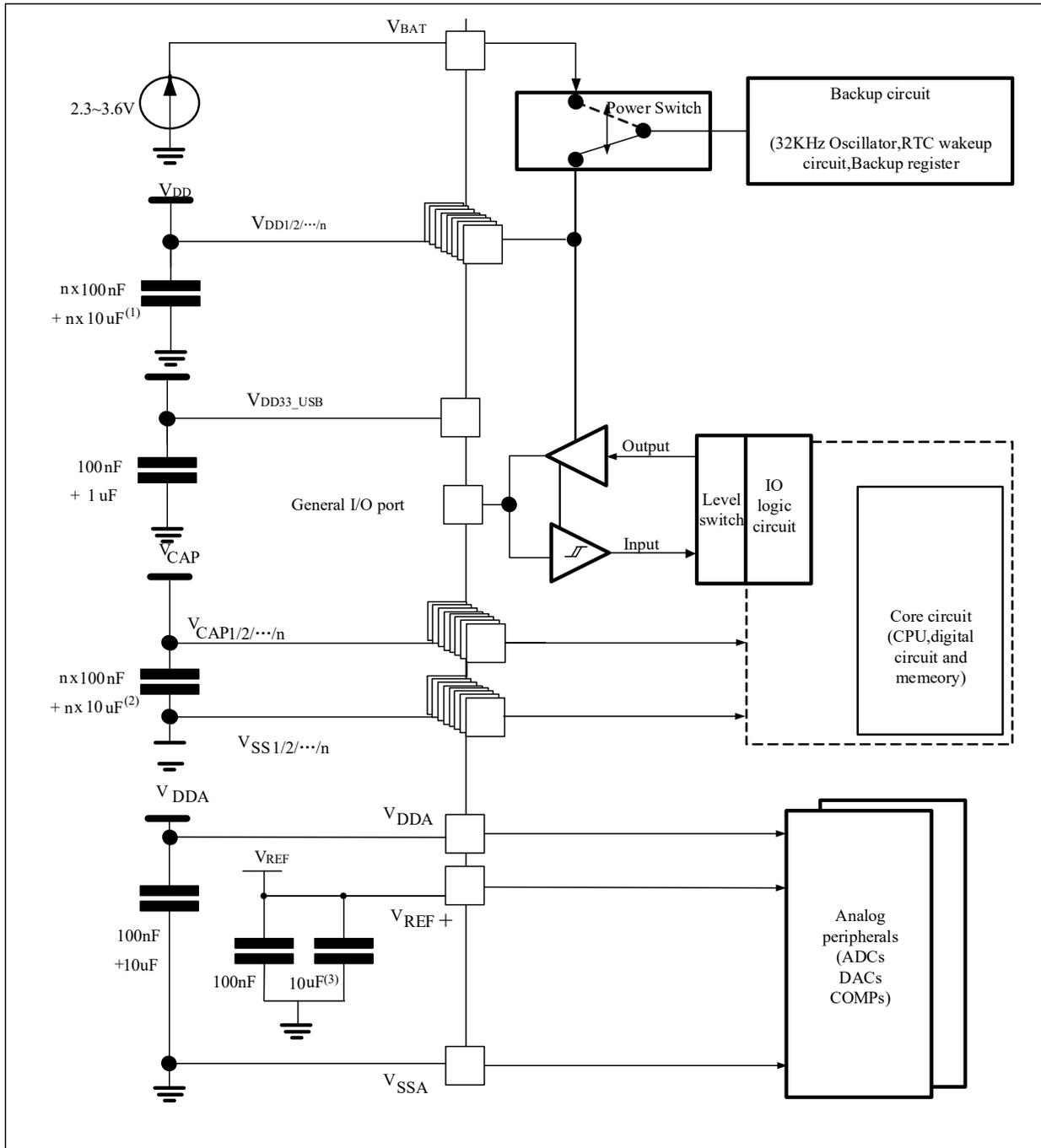
The method for measuring input voltage on pins is shown in Figure 4-2.

Figure 4-2 Pin Input Voltage



4.1.6 Power Supply Scheme

Figure 4-3 Power Supply Scheme

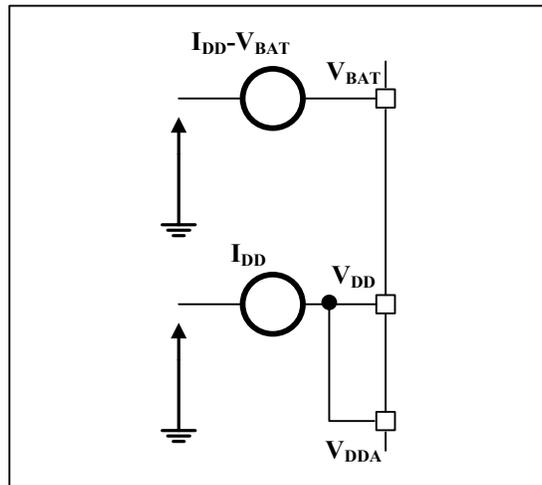


Note:

1. The 10 μ F capacitor in the above figure must be connected to the specified V_{DD} .

4.1.7 Current Consumption Measurement

Figure 4-4 Current Consumption Measurement



4.2 Absolute Maximum Ratings

Loads applied to the device that exceed the values given in the "Absolute Maximum Ratings" tables (Table 4-1, Table 4-2, Table 4-3) may cause permanent damage to the device. These values only indicate the maximum tolerable loads and do not imply that the device will function correctly under these conditions. Long-term operation at maximum values will affect device reliability.

Table 4-1 Voltage Characteristics

Symbol	Description	Minimum	Maximum	Unit
$V_{DD} - V_{SS}$	External main supply voltage (including V_{DDA} and V_{DD}) ⁽¹⁾	-0.3	4.0	V
V_{IN}	Input voltage on 5V-tolerant pins ⁽³⁾	$V_{SS}-0.3$	5.5	
	Input voltage on other pins ⁽²⁾	$V_{SS}-0.3$	$V_{DD} + 0.3$	
$ \Delta V_{DDx} $	Voltage difference between different supply pins	-	50	mV
$ V_{SSx} - V_{SS} $	Voltage difference between different ground pins	-	50	
$V_{ESD(HBM)}$	ESD electrostatic discharge voltage (human body model)	See Section 4.3.12		

- All power supply (V_{DD} , V_{DDA}) and ground (V_{SS} , V_{SSA}) pins must always be connected to an external power system within the allowable range.
- V_{IN} should not exceed its maximum value; for current characteristics, refer to Table 4-2.
- When a 5V-tolerant pin receives 5.5V input, V_{DD} cannot be lower than 2.25V.

Table 4-2 Current Characteristics

Symbol	Description	Maximum ⁽¹⁾	Unit
I_{VDD}	Total current through VDD/VDDA power lines (supply current) ⁽¹⁾⁽⁴⁾	150	mA
$I_{VDDSMPS}$	Total current through VDDSMPS power lines ⁽¹⁾⁽⁴⁾	700	
I_{VCAP}	Total current through VCAP power lines ⁽¹⁾⁽⁴⁾	1000	
I_{VSS}	Total current through VSS ground lines (output current) ⁽¹⁾⁽⁴⁾	1150	
I_{IO}	Output sink current on any I/O and control pin	12	
	Output source current on any I/O and control pin	-12	
$I_{IN(PIN)}^{(2)(3)}$	Injection current for NRST pin	-5/0	

	Injection current for other pins	+/-5
--	----------------------------------	------

1. All power supply (V_{DD} , V_{DDA}) and ground (V_{SS} , V_{SSA}) pins must always be connected to an external power system within the allowable range.
2. When $V_{IN} > V_{DD}$, there is a forward injection current; when $V_{IN} < V_{SS}$, there is a reverse injection current. $I_{INJ}(PIN)$ should not exceed its maximum value; for voltage characteristics, refer to Table 4-1.
3. Reverse injection current will interfere with the device's analog performance. See Section 4.3.33.
4. When maximum current occurs, the maximum allowed V_{DD} voltage drop is $0.1V_{DD}$.

Table 4-3 Temperature Characteristics

Symbol	Description	Value	Unit
T_{STG}	Storage temperature range	-40 ~ + 150	°C
T_J	Maximum junction temperature	125	°C

4.3 Operating Conditions

4.3.1 General Operating Conditions

Table 4-4 General Operating Conditions

Symbol	Parameter	Conditions	Minimum	Maximum	Unit
f_{CPU}	Arm® Cortex®-M7 clock frequency	$V_{CORE} = 0.9V$	-	600	MHz
f_{ACLK}	AXI clock frequency	$V_{CORE} = 0.9V$	-	300	MHz
f_{HCLK}	AHB clock frequency	$V_{CORE} = 0.9V$	-	300	MHz
f_{PCLK}	APB clock frequency	$V_{CORE} = 0.9V$	-	150	
V_{DD}	Standard operating voltage	-	2.3	3.63	V
V_{DDA}	Analog section operating voltage	Must be the same as $V_{DD}^{(1)}$	2.3	3.63	V
V_{BAT}	Backup section operating voltage	-	2.3	3.63	V
T_A	Ambient temperature (temperature grade 7)	Maximum power consumption	-40	105	°C
T_J	Junction temperature range	Temperature ⁷	-40	125	°C
VCAP	VCAP voltage	-	0.9	0.99	V

- It is recommended to use the same power supply for V_{DD} and V_{DDA} . During power-up and normal operation, V_{DDA} must be less than or equal to V_{DD} .

4.3.2 SMPS Step-Down Converter

Characteristics of the externally used SMPS are listed in Table 4-6.

Figure 4-5 External components for SMPS step-down converter

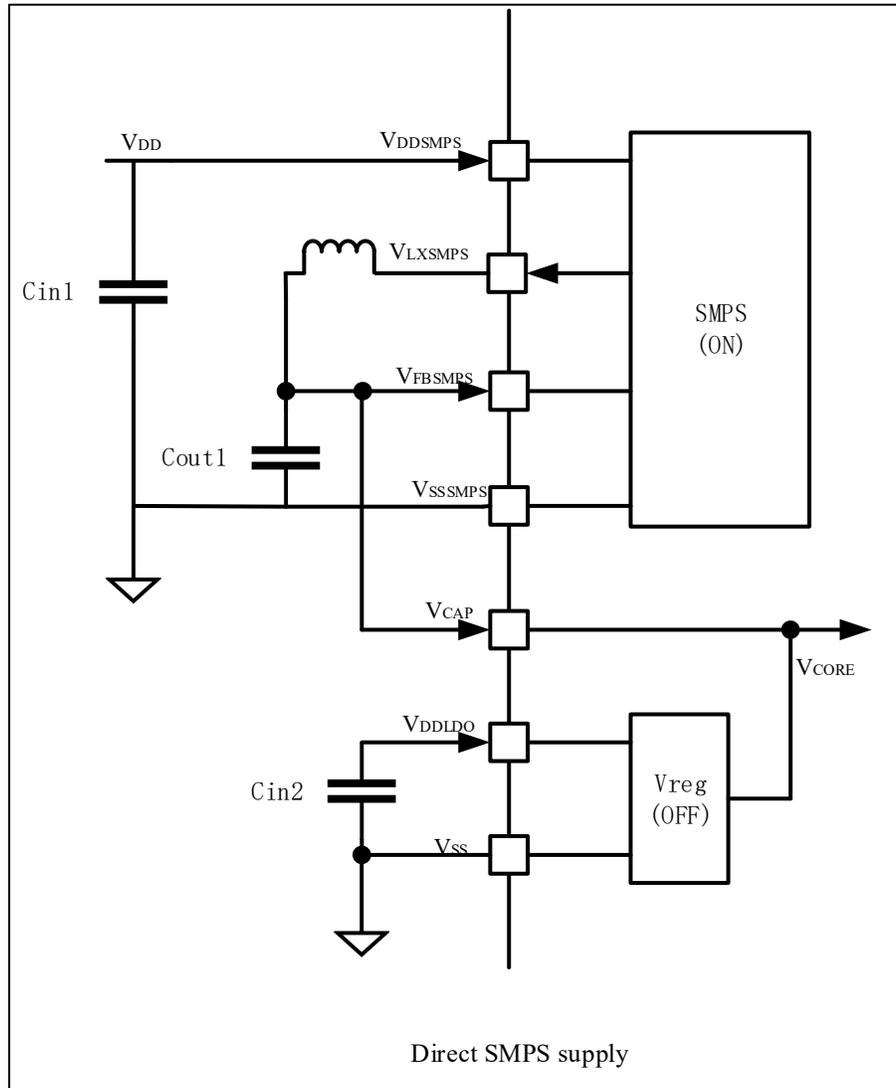


Table 4-5 Characteristics of SMPS Step-Down Converter for External Use

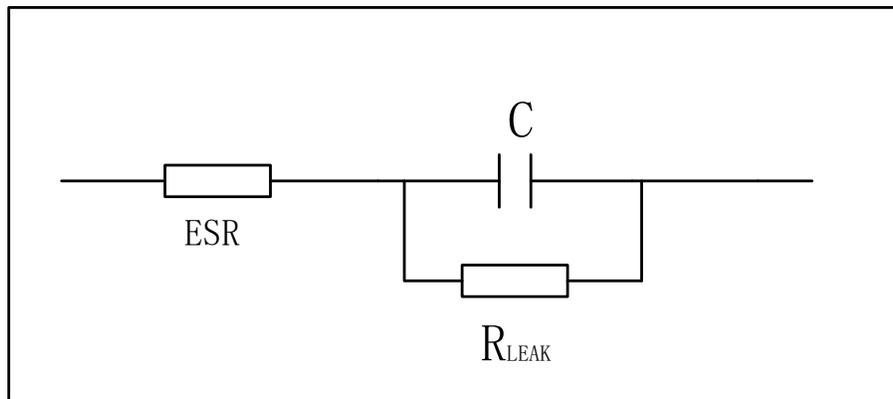
Symbol	Parameter	Conditions	Minimum	Maximum	Unit
V _{DDSMPS}	V _{OUT} = 0.9V	2.3	-	3.6	V
V _{OUT}	I _{OUT} = 1A	0.72	-	0.99	V
I _{OUT}	-	-	-	1	A
R _{DS(on)}	PMOS	-	56	116	mΩ
	NMOS	-	100	131	mΩ
I _{DDSMPS_Q}	Quiescent current	-	200	-	uA
T _{SMPS_START}	I _{load} = 0mA	-	-	0.2	ms

Table 4-6 Characteristics of External Components Required for the SMPS Step-Down Converter

Symbol	Parameter	Conditions
C _{in}	Capacitance of external capacitor on V _{DDSMPS}	47uF
	ESR of external capacitor	10mΩ
C _{out}	Capacitance of external capacitor on V _{FBSMPS} pin	20uF
	ESR of external capacitor	10mΩ
L	Inductance of external Inductor on V _{LXSMPS} pin	2.2uH
	Serial DC resistor	10mΩ

4.3.3 VCAP External Capacitor

The stability of the main regulator can be achieved by connecting an external capacitor C_{EXT} to the VCAP pin. Table 4-7 specifies C_{EXT}. Two external capacitors can be connected to the VCAP pin.

Figure 4-6 External Capacitor C_{EXT}


1. ESR is Equivalent Series Resistance

Table 4-7 VCAP Operating Conditions

Symbol	Parameter	Conditions
C _{EXT}	DCDC	2*10uF + 1 * 0.1uF
	External LDO	22uF + 4 * 0.1uF
ESR	External capacitor ESR	< 100 m Ω

4.3.4 Operating Conditions During Power-up and Power-down

The parameters given in the table below are tested at the ambient temperature (25°C) listed in Table 4-4.

Table 4-8 Operating Conditions During Power-up and Power-down

Symbol	Parameter	Conditions	Minimum	Maximum	Unit
tvDD	V _{DD} rise rate	-	20	+∞	μs/V
	V _{DD} fall rate		80	+∞	
tvCAP	V _{CAP} rise rate	-	100	+∞	μs/V
	V _{CAP} fall rate		100	+∞	

- It is recommended that VCAP power down after V_{DD}, i.e., V_{CAP} shall not power down until V_{DD} drops below 1.45V

4.3.5 Embedded Reset and Power Control Module Characteristics

The parameters given in the table below are tested at the ambient temperature (25°C) and V_{DD} supply voltage listed in Table 4-4.

Table 4-9 Embedded Reset and Power Control Module Characteristics

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V _{VPD}	Programmable voltage detector level selection	AFEC_PRS[2:0]=0101 (Rising edge)	2.19	2.28	2.36	V
		AFEC_PRS[2:0]=0101 (Falling edge)	2.09	2.18	2.26	
		AFEC_PRS[2:0]=0110 (Rising edge)	2.28	2.38	2.46	
		AFEC_PRS[2:0]=0110 (Falling edge)	2.19	2.28	2.36	
		AFEC_PRS[2:0]=0111 (Rising edge)	2.36	2.48	2.56	
		AFEC_PRS[2:0]=0111 (Falling edge)	2.28	2.38	2.46	
		AFEC_PRS[2:0]=1000 (Rising edge)	2.46	2.58	2.66	
		AFEC_PRS[2:0]=1000 (Falling edge)	2.36	2.48	2.56	
		AFEC_PRS[2:0]=1001 (Rising edge)	2.56	2.68	2.76	
		AFEC_PRS[2:0]=1001 (Falling edge)	2.46	2.58	2.66	
		AFEC_PRS[2:0]=1010 (Rising edge)	2.66	2.78	2.86	
		AFEC_PRS[2:0]=1010 (Falling edge)	2.6	2.68	2.76	
		AFEC_PRS[2:0]=1011 (Rising edge)	2.8	2.88	2.96	
		AFEC_PRS[2:0]=1011 (Falling edge)	2.7	2.78	2.86	
		AFEC_PRS[2:0]=1100 (Rising edge)	3.2	3.28	3.36	
		AFEC_PRS[2:0]=1100 (Falling edge)	3.1	3.18	3.26	
		AFEC_PRS[2:0]=1101 (Rising edge)	3.28	3.38	3.46	
		AFEC_PRS[2:0]=1101 (Falling edge)	3.19	3.28	3.36	
AFEC_PRS[2:0]=1110 (Rising edge)	3.38	3.48	3.56			
AFEC_PRS[2:0]=1110 (Falling edge)	3.29	3.38	3.46			

		AFEC_PRS[2:0]=1111 (Rising edge)	3.49	3.58	3.66	
		AFEC_PRS[2:0]=1111 (Falling edge)	3.39	3.48	3.56	
V _{PVDhyst} ⁽¹⁾	PVD hysteresis	-	-	100	-	mV
V _{POR}	V _{DD} power on reset threshold	-	-	1.65	-	V
V _{POR}	V _{DD} power down reset threshold	-	-	1.60	-	V
V _{POR}	POR hysteresis	-	-	50	-	mV
V _{BOR}	BOR power-on/power-down reset threshold	BOR_CFG[2:0]=011(Rising edge)	2.45	2.5	2.55	V
		BOR_CFG [2:0]=011(Falling edge)	2.35	2.4	2.45	
		BOR_CFG[2:0]=100(Rising edge)	2.75	2.8	2.85	
		BOR_CFG[2:0]=100(Falling edge)	2.65	2.7	2.75	
		BOR_CFG[2:0]=101(Rising edge)	3.0	3.1	3.15	
		BOR_CFG[2:0]=101(Falling edge)	2.9	3.0	3.05	
		BOR_CFG[2:0]=110(Rising edge)	3.3	3.45	3.5	
		BOR_CFG[2:0]=011(Falling edge)	3.2	3.35	3.4	
V _{AVD}	AVD Analog voltage detector	AFEC_ALS[3:0]=0110(Rising edge)	2.28	2.38	2.46	V
		AFEC_ALS[3:0]=0110(Falling edge)	2.19	2.28	2.36	
		AFEC_ALS[3:0]=0111(Rising edge)	2.36	2.48	2.56	
		AFEC_ALS[3:0]=0111(Falling edge)	2.28	2.38	2.46	
		AFEC_ALS[3:0]=1000(Rising edge)	2.46	2.58	2.66	
		AFEC_ALS[3:0]= 1000(Falling edge)	2.36	2.48	2.56	
		AFEC_ALS[3:0]=1001(Rising edge)	2.56	2.68	2.76	
		AFEC_ALS[3:0]=1001(Falling edge)	2.46	2.58	2.66	
		AFEC_ALS[3:0]=1010(Rising edge)	2.66	2.78	2.86	
		AFEC_ALS[3:0]=1010(Falling edge)	2.6	2.68	2.76	
		AFEC_ALS[3:0]=1011(Rising edge)	2.8	2.88	2.96	
		AFEC_ALS[3:0]=1011(Falling edge)	2.7	2.78	2.86	
		AFEC_ALS[3:0]=1100(Rising edge)	3.2	3.28	3.36	
		AFEC_ALS[3:0]=1100(Falling edge)	3.1	3.18	3.26	
		AFEC_ALS[3:0]=1101(Rising edge)	3.3	3.38	3.46	
		AFEC_ALS[3:0]=1101(Falling edge)	3.2	3.28	3.36	
		AFEC_ALS[3:0]=1110(Rising edge)	3.4	3.48	3.56	
		AFEC_ALS[3:0]=1110(Falling edge)	3.3	3.38	3.46	
		AFEC_ALS[3:0]=1111(Rising edge)	3.5	3.58	3.66	

		AFEC_ALS[3:0]=1111(Falling edge)	3.4	3.48	3.56	
$T_{RSTTEMPO}^{(1)}$	Reset duration	-	-	0.35	-	ms

1. Guaranteed by design, not tested in production.

4.3.6 Built-in Bandgap Reference Voltage

The parameters given in the table below are tested at the ambient temperature (25°C) and V_{DD} supply voltage listed in Table 4-4.

Table 4-10 Built-in Reference Voltage

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
V_{BG}	Built-in bandgap reference voltage	-40°C < T_J < +125°C	1.164	1.2	1.3 ⁽²⁾	V
$T_{S_BG}^{(1)}$	ADC sampling time when reading internal bandgap reference voltage	-	-	2	17.1 ⁽²⁾	μs
ΔV_{BG}	Internal voltage drift over the full temperature range	$V_{DD} = 3.3V$ -40°C < T_J < +125°C	-	-	50	mV

1. The minimum sampling time is obtained through multiple cycles in the application.
2. Guaranteed by design, not tested in production.

4.3.7 Supply Current Characteristics

Current consumption is a comprehensive indicator of various parameters and factors, including operating voltage, ambient temperature, I/O pin load, product software configuration, operating frequency, I/O pin switching rate, program location in memory, and executed code.

For current consumption measurement method details, see Figure 4-4.

All current consumption measurements in running modes given in this section are performed while executing a simplified set of code.

4.3.7.1 Maximum Current Consumption

The microcontroller is under the following conditions:

- All I/O pins are in input mode and connected to a static level— V_{DD} or V_{SS} (no load).
- All peripherals are turned off, unless otherwise specified.
- TCM memory access time is adjusted to the fastest frequency that can be run.
- Instruction prefetch function is enabled (Note: this parameter must be set before setting the clock and bus dividers).
- When peripherals are enabled: AXI, AHB, APB clock frequencies are configured to maximum.
- $V_{DD}=3.63V$, junction temperature equals $125^{\circ}C$.

The parameters given in Table 4-11 and Table 4-12 are tested at the ambient temperature ($25^{\circ}C$, $85^{\circ}C$, $105^{\circ}C$), V_{CAP} and V_{DD} supply voltage listed in Table 4-4.

Table 4-11 Maximum Current Consumption in Run Mode, Code Running in ITCM(only CM7 runs), Cache enable

Symbol	Parameter	Conditions	f _{sys}	T _A = 25°C		T _A = 85°C		T _A = 105°C		Unit
				I _{VCAP}	I _{VDD}	I _{VCAP}	I _{VDD}	I _{VCAP}	I _{VDD}	
I _{DD} ⁽¹⁾	Supply current in run mode	External clock, all peripherals enabled, V _{DD} =3.3V, V _{CAP} =0.9V	600M	325.3	11.2	390.7	12.3	462.0	13.4	mA
			400M	238.2	10.8	301.3	11.5	371.1	12.6	
		External clock, all peripherals disabled, V _{DD} =3.3V, V _{CAP} =0.9V	600M	184.7	6.4	232.5	7.6	283.8	8.3	
			400M	142.8	5.8	189.6	6.4	240.6	7.5	

1. Derived from comprehensive evaluation, not tested in production.

Table 4-12 Maximum Current Consumption in Sleep Mode, Code Running in ITCM(only CM7 runs), Cache disable

Symbol	Parameter	Conditions	f _{HCLK}	T _A = 25°C		T _A = 85°C		T _A = 105°C		Unit
				I _{VCAP}	I _{VDD}	I _{VCAP}	I _{VDD}	I _{VCAP}	I _{VDD}	

$I_{DD}^{(1)}$	Supply current in sleep mode	External clock, all peripherals enabled, VDD=3.3V, VCAP=0.9V	600M	254.1	11.2	288.8	12.6	355.5	13.8	mA
			400M	160.1	10.4	216.5	11.5	280.9	12.7	
		External clock, all peripherals disabled, VDD=3.3V, VCAP=0.9V	600M	79.2	6.8	118.9	8.1	164.0	9.6	
			400M	57.5	5.9	96.6	7.0	140.8	8.1	

1. Guaranteed by comprehensive evaluation results, not tested in production

4.3.7.2 Low-power Mode Current Consumption

MCU is under the following conditions:

- All I/O pins are in input mode and connected to a static level—V_{DD} or V_{SS} (no load).
- All peripherals are turned off unless specifically stated.

Table 4-13 Maximum current consumption in stop and standby

Symbol	Parameter	Conditions	T _A =25°C		T _A =85°C		T _A =105°C		Unit
			I _{VCAP}	I _{VDD}	I _{VCAP}	I _{VDD}	I _{VCAP}	I _{VDD}	
$I_{DD}^{(1)}$	Supply current in STOP0 mode	LSI HSI, HSE off, all GPIOs are in the analog mode	5.7	2.6	44.8	3.2	91	3.6	mA
	Supply current in STANDBY mode	LSE on, RTC on, IWDG off, BackupSRAM hold	0.67	0.32	3.54	0.67	6.93	1.03	
		LSE on, RTC off, IWDG off, BackupSRAM not holding	0.64	0.31	3.51	0.64	6.82	0.94	

1. Guaranteed by comprehensive evaluation results, not tested in production.

Table 4-14 Maximum current consumption in VBAT

Symbol	Parameter	Conditions	T _A =25°C	T _A =85°C	T _A =105°C	Unit
$I_{DD}^{(1)}$	Supply current in VBAT mode	V _{BAT} =3.3V, LSE off, RTC off, IWDG off, BackupSRAM not holding	59.1	332.4	591.1	μA

1. Guaranteed by comprehensive evaluation results, not tested in production.

4.3.8 External Clock Source Characteristics

4.3.8.1 High-Speed External Clock Source (External Clock)

High-speed external user clock is generated from an external source.

In bypass mode, the HSE oscillator is turned off, and the input pin functions as a standard I/O.

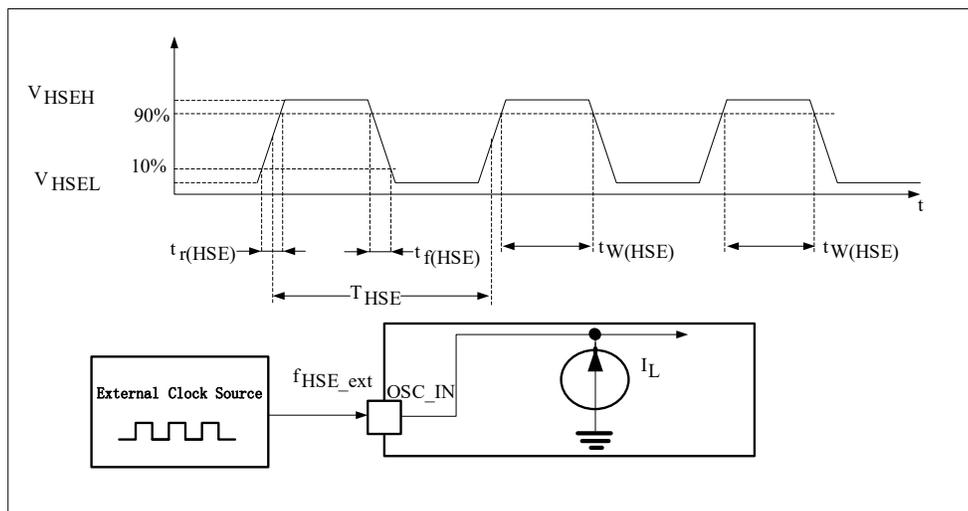
The external clock signal must comply with Table 4-15, and the recommended clock input waveform is shown in Figure 4-7.

Table 4-15 High-Speed External User Clock Characteristics⁽¹⁾

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
$f_{\text{HSE-ext}}$	User external clock frequency ⁽¹⁾	$V_{\text{DD}}=3.3\text{V}$, $T_{\text{A}}=-40\sim 105^{\circ}\text{C}$	4	25	50	MHz
V_{HSEH}	OSC_IN input pin high level voltage		$0.7V_{\text{DD}}$	-	V_{DD}	V
V_{HSEL}	OSC_IN input pin low level voltage		V_{SS}	-	$0.3V_{\text{DD}}$	V
$t_{\text{w(HSE)}}$	OSC_IN high or low time ⁽¹⁾		7	-	-	ns

1. Guaranteed by design..

Figure 4-7 High-speed external clock source AC timing diagram



4.3.8.2 Low-Speed External Clock Source (External Clock)

In bypass mode, the LSE oscillator is turned off, and the input pin functions as a standard I/O. The external clock signal must comply with Table 4-16, and the recommended clock input waveform is shown in Figure 4-8.

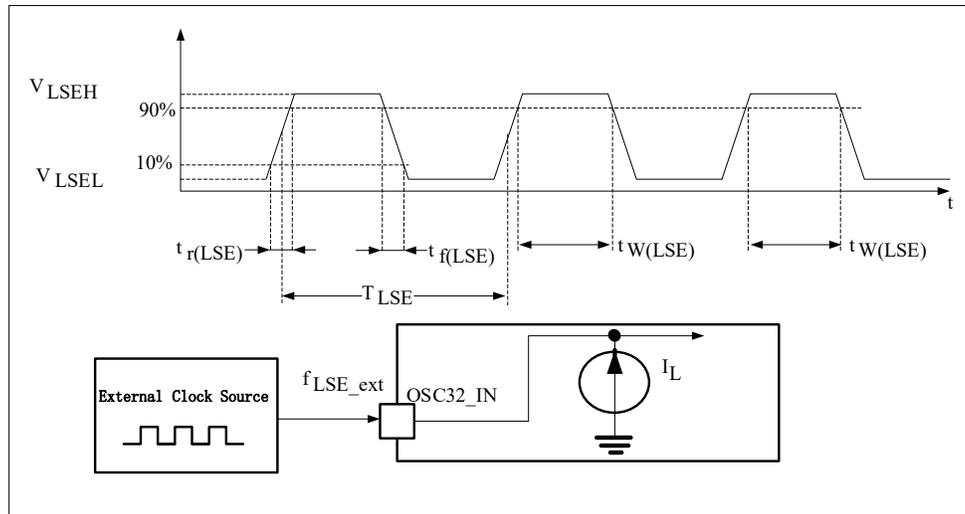
Table 4-16 Low-Speed External User Clock Characteristics(1)

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
$f_{\text{LSE-ext}}$	User external clock frequency ⁽¹⁾	$V_{\text{DD}}=3.3\text{V}$, $T_{\text{A}}=-40\sim 105^{\circ}\text{C}$	-	32.768	1000	KHz

V_{LSEH}	OSC32_IN input pin high level voltage		$0.7V_{DD}$	-	V_{DD}	V
V_{LSEL}	OSC32_IN input pin low level voltage		V_{SS}	-	$0.3V_{DD}$	V
$t_{w(LSE)}$	OSC32_IN high or low time ⁽¹⁾		250	-	-	ns

1. Guaranteed by design..

Figure 4-8 Low-speed external clock source AC timing diagram



4.3.8.3 High-Speed External Clock Source (External Crystal/Ceramic)

The high-speed external (HSE) clock can be provided by a 4 to 48 MHz crystal/ceramic resonator oscillator. All information given in this section is based on the analysis results of typical external component characteristics specified in the table below. In applications, the resonator and load capacitors must be placed as close as possible to the oscillator pins to minimize output distortion and startup stabilization time. For more details on resonator characteristics (frequency, package, accuracy), please consult the crystal resonator manufacturer.

Table 4-17 HSE 4~48MHz Oscillator Characteristics⁽¹⁾

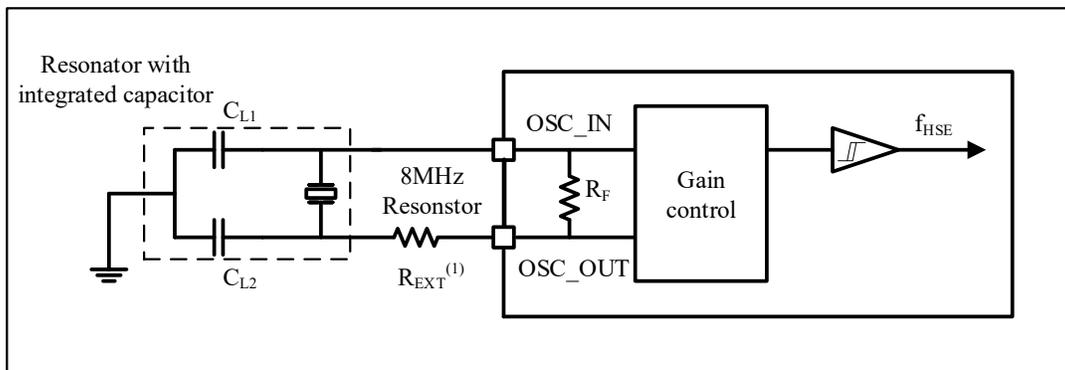
Symbol	Parameter	Conditions ⁽²⁾	Minimum	Typical	Maximum	Unit
f	Oscillator frequency	-	4	25	48	MHz
R	Feedback resistance	-	-	200	-	K Ω
I_{DDHSE}	HSE drive current	During startup ⁽³⁾	-	-	4	mA
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 4 MHz, TRIM[2:0]=010	-	TBD	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 4 MHz, TRIM[2:0]=100(default)	-	TBD	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 8 MHz, TRIM[2:0]=010	-	1.2	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 8 MHz, TRIM[2:0]=100(default)	-	1.79	-	

		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 16 MHz, TRIM[2:0]=010	-	1.5	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 16 MHz, TRIM[2:0]=100(default)	-	2.19	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 32 MHz, TRIM[2:0]=010	-	1.65	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 32 MHz, TRIM[2:0]=100(default)	-	2.56	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 48 MHz, TRIM[2:0]=010	-	TBD	-	
		$V_{DD}=3\text{ V}$, $R_m=30\ \Omega$, $CL=10\text{ pF}$ at 48 MHz, TRIM[2:0]=100(default)	-	TBD	-	
$G_{m\text{critmax}}$	Maximum oscillator transconductance	Startup	-	-	1.5	mA/V
$t_{\text{SU(HSE)}}^{(4)}$	Startup time	V_{DD} already stable	-	2	5	ms

1. Guaranteed by design.
2. Resonator characteristic parameters are provided by the crystal/ceramic resonator manufacturer.
3. Time consumption occurs during the first 2/3 phase of the $t_{\text{SU(HSE)}}$ startup time.
4. $t_{\text{SU(HSE)}}$ is the startup time, measured from when HSE is enabled by software until a stable 8MHz oscillation is obtained. This value is measured on a standard crystal resonator and may vary considerably depending on the crystal manufacturer.

Note: For CL1 and CL2, it is recommended to use high-quality external ceramic capacitors in the range of 5 pF to 25 pF (typical values), which are designed for high-frequency applications, and their selection should meet the requirements of the crystal or resonator (see Figure 4-9). CL1 and CL2 are typically the same size. Crystal manufacturers usually specify a load capacitance, which is the series combination of CL1 and CL2. When determining the size of CL1 and CL2, the PCB and MCU pin capacitance must be taken into account (10 pF can be used as a rough estimate for the combined pin and circuit board capacitance).

Figure 4-9 Typical application using an 8MHz crystal



1. The value of R_{EXT} is determined by the characteristics of the crystal.

4.3.8.4 Low-Speed External Clock Source (External Crystal/Ceramic Resonator)

The low-speed external clock (LSE) can be generated using an oscillator consisting of a 32.768kHz crystal or ceramic resonator (crystal mode). The information provided in this section is based on comprehensive characteristic evaluations using typical external components listed in the table below.

In applications, the resonator and load capacitors must be placed as close as possible to the oscillator pins to minimize output distortion and startup stabilization time. For detailed parameters of the crystal resonator (such as frequency, package, accuracy, etc.), please consult the respective manufacturers. (Note: The "crystal resonator" mentioned here refers to a standard passive crystal oscillator.)

Note: For C_{L1} and C_{L2} , it is recommended to use high-quality ceramic capacitors and to select crystals or resonators that meet the required specifications. Typically, C_{L1} and C_{L2} have the same specifications.

Crystal manufacturers usually specify the load capacitance parameters based on the series combination of C_{L1} and C_{L2} .

The load capacitance CL is calculated as follows:

$CL = C_{L1} \times C_{L2} / (C_{L1} + C_{L2}) + C_{stray}$ is the stray capacitance associated with the pins and PCB (Printed Circuit Board).

Example:

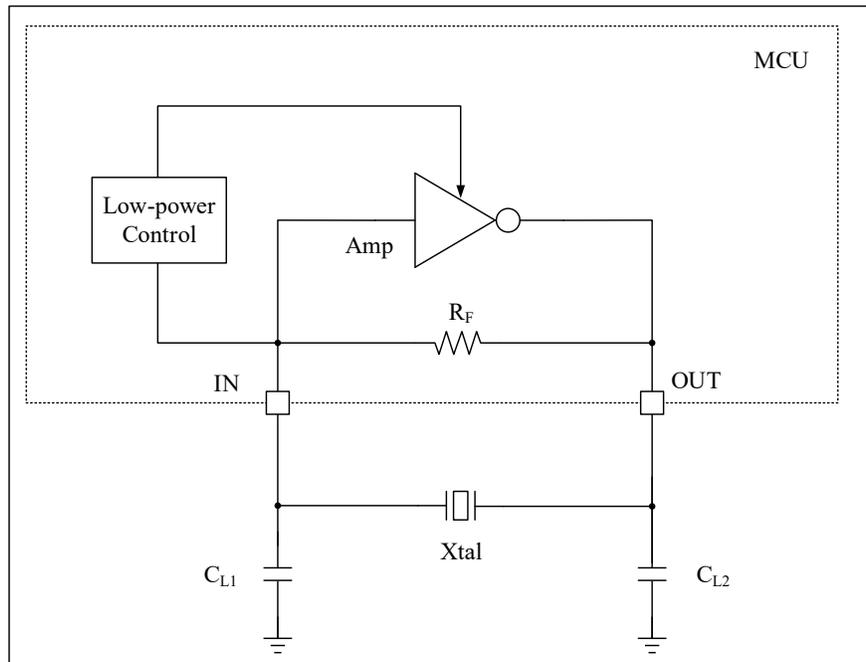
If a resonator with a specified load capacitance $C_L = 6\text{pF}$ is selected and $C_{stray} = 2\text{pF}$, then $C_{L1} = C_{L2} = 8\text{pF}$.

Table 4-18 LSE Oscillator Characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f	Oscillator Frequency	-	-	32.768	-	KHz
R	Feedback Resistor	-	-	100	-	K Ω
IDD _{LSE}	LSE Drive Current	Low drive capability	-	300	-	nA
		Medium-low drive capability	-	400	-	
		Medium-high drive capability	-	550	-	
		High drive capability	-	1000	-	
G _{meritmax}	Maximum Oscillator Transconductance	Low drive capability	-	-	0.5	uA/V
		Medium-low drive capability	-	-	1	
		Medium-high drive capability	-	-	2	
		High drive capability	-	-	3	
t _{SU}	Startup Time	After V _{DD} stabilizes	-	2	-	s

1. Guaranteed by comprehensive evaluation, not tested in production.
2. t_{SU} (LSE) is the startup time measured from the moment LSE is enabled via software until a stable 32.768kHz oscillation is achieved. This value is measured with a standard crystal resonator and may vary significantly depending on the crystal manufacturer.

Figure 4-10 Typical Application Using a 32.768kHz Crystal



4.3.9 Internal Clock Source Characteristics

The parameters provided in Table 4-19 to Table 4-21 are derived from tests conducted under the ambient temperature and V_{DD} supply voltage conditions outlined in Table 4-4

4.3.9.1 64MHz High-Speed Internal Oscillator (HSI64)

Table 4-19 HSI64 Oscillator Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI64}	Frequency	$V_{DD} = 3.3V, T_{JS} = 25^\circ C$, after calibration	63.68	64	64.32	MHz
TRIM	User calibration step size	-	-	0.5	-	%
USER TRIM COVERAGE	User calibration coverage	± 32 steps	± 4.79	± 5.60	-	%
ACC_{HSI64}	HSI64 Oscillator Accuracy	$V_{DD} = 3.3V, T_J = -40 \sim 125^\circ C$, including temperature drift and reflow effects	-2	-	2	%
		$V_{DD} = 3.3V, T_J = -20 \sim 105^\circ C$, including temperature drift and reflow effects	-1.5	-	1.5	%

ΔV_{DD} (HSI48)	HSI64 Oscillator frequency drift with V_{DD}	$V_{DD} = 3$ to 3.6 V	-	0.025	0.05	%
		$V_{DD} = 2.3$ V to 3.6 V	-	0.05	0.1	
$t_{SU(HSI64)}$	HSI Oscillator startup time	-	1	6	10	μ s
$DuCy(HSI64)$	Duty cycle	-	45	50	55	%
$I_{DD(HSI64)}$	HSI Oscillator power consumption	-	-	250	350	μ A
P_T jitter	Jitter relative to the ideal cycle	-	-	50	-	ps

4.3.9.2 Multi-Speed Internal Oscillator (MSI)

Table 4-20 MSI Oscillator Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{MSI}	Frequency	$V_{DD} = 3.3$ V, $T_J = 25^\circ$ C, after calibration, default MSI = 16MHz	15.84	16	16.16	MHz
TRIM	User calibration step size	-	-	0.175	-	%
USER TRIM COVERAGE	User calibration coverage	± 32 steps	± 4.79	± 5.60	-	%
ACC_{MSI}	MSI Oscillator Accuracy	$V_{DD} = 3.3$ V, $T_J = -40 \sim 125^\circ$ C, including temperature drift and reflow effects	-2	-	2	%
		$V_{DD} = 3.3$ V, $T_J = -20 \sim 105^\circ$ C, including temperature drift and reflow effects	-1.5	-	1.5	%
$t_{SU(MSI)}$	MSI Oscillator startup time	-	-	4	6	μ s
$DuCy(MSI)$	Duty cycle	-	45	50	55	%
$I_{DD(MSI)}$	MSI Oscillator power consumption	-	-	150	200	μ A

4.3.9.3 Low-Speed Internal Oscillator (LSI)

Table 4-21 LSI Oscillator Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f _{LSI}	Output frequency	25°C calibration, V _{DD} = 3.3V	31.36 ⁽¹⁾	32	32.64 ⁽¹⁾	KHz
		V _{DD} = 2.3V ~ 3.6V, T _J = -40~105°C	30.4 ⁽²⁾	32	33.6 ⁽²⁾	KHz
t _{SU(LSI)} ⁽³⁾	LSI Oscillator startup time	-	-	70	120	μs
I _{DD(LSI)} ⁽³⁾	LSI Oscillator power consumption	-	-	1.2	2.4	μA

1. Guaranteed by test in production.
2. Guaranteed by characterization results.
3. Guaranteed by design.

4.3.10 Wake-up Time from Low-Power Modes

The wake-up time listed in Table 4-22 is measured during the wake-up phase of an 64MHz HSI RC oscillator. The clock source used when waking up depends on the current operating mode:

- STOP0 or STANDBY mode: clock source is RC oscillator
- SLEEP mode: The clock source is the clock used to enter SLEEP mode

All times were measured using ambient temperature and supply voltage in accordance with Table 4-4.

Table 4-22 Wake-up Times for Low-Power Modes

Symbol	Parameter	Typical Value ⁽¹⁾	Unit
t _{WUSLEEP}	Wake-up from Sleep mode	15	Cycles
t _{WUSTOP0}	Wake-up from Stop 0 mode	5.9	μs
t _{WUSTDBY}	Wake-up from Standby mode	11.82	μs

4.3.11 PLL Characteristics

The parameters listed in Table 4-23 and Table 4-24 were measured under ambient temperature (25°C) and supply voltage conditions as specified in Table 4-4.

4.3.11.1 PLL1/2/3 Characteristics

Table 4-23 PLL Characteristics

Symbol	Parameter	Value			Unit
		Min	Typ	Max ⁽¹⁾	
f _{PLL_IN}	PLL input clock ⁽²⁾	4	25	64	MHz
	PLL input clock duty cycle	40	50	60	%

f_{PLL_OUT}	PLL multiplied output clock	400	-	800	MHz
t_{LOCK}	PLL Ready signal output time	-	-	150	μ s
Jitter	Rms cycle-to-cycle jitter @800MHz	-	± 4	-	ps
f_{VCO_OUT}	PLL VCO output	400	-	800	MHz
I_{PLL}	Operating Current of PLL @600MHz frequency.	-	2.5	-	μ A

- Results based on comprehensive evaluation, not tested in production;
- Attention must be taken to use the correct multiplication factor so that the f_{PLL_OUT} remains within the allowed range according to the PLL input clock frequency.

4.3.11.2 SHRPLL Characteristics

Table 4-24 SHRPLL Characteristics

Symbol	Parameter	Value			Unit
		Min	Typ	Max ⁽¹⁾	
f_{SHRPLL_IN}	SHRPLL input clock ⁽²⁾	4	25	64	MHz
	SHRPLL input clock duty cycle	40	50	60	%
f_{SHRPLL_OUT}	SHRPLL multiplied output clock	400	-	1250	MHz
t_{LOCK}	SHRPLL Ready signal output time	10	62.5	125	μ s
Jitter	Rms period jitter @1250MHz	-	± 2	-	\pm ps
I_{SHRPLL}	Operating Current of SHRPLL @1250MHz VCO frequency.	-	4.8	-	mA

- Results based on comprehensive evaluation, not tested in production.
- Attention must be paid to using the correct multiplication factor to ensure that the f_{SHRPLL_OUT} falls within the permissible range based on the input clock frequency.

4.3.12 Absolute Maximum Ratings (Electrical Sensitivity)

Based on different tests (ESD, ES, LU), specific measurement methods are used to evaluate the chip's performance regarding electrical sensitivity.

Electrostatic Discharge (ESD)

electrostatic discharge (one positive pulse followed by one negative pulse after one second) is applied to all pins of all samples.

Table 4-25 ESD Absolute Maximum Ratings

Symbol	Parameter	Conditions	Type	Max ⁽¹⁾	Unit
$V_{ESD(HBM)}$	ESD Voltage (Human Body Model)	TA = +25°C, per MIL-STD-883K Method 3015.9	3A	2000	V
$V_{ESD(CDM)}$	ESD Voltage (Charged Device Model)	TA = +25°C, per ESDA/JEDEC JS-002-2018	C3	250	

- Results based on comprehensive evaluation, not tested in production.

Latch-Up (LU)

To evaluate latch-up performance, two complementary static latch-up tests are performed on six samples:

- Provide an over-limit supply voltage to each power pin.
- Inject current into each input, output, and configurable I/O pin.

This test complies with EIA/JESD78A IC latch-up standard.

Table 4-26 Static Latch-Up

Symbol	Parameter	Conditions	Type
LU	Static Latch-Up Class	$T_A = +105^\circ\text{C}$, perJESD 78E	Class II A

1. Tested under room temperature conditions.

4.3.13 Flash Memory Characteristics

Table 4-27 Flash Memory Characteristics

Symbol	Parameter	Conditions	Min	Unit
N_{END}	Program/erase endurance	$T_A = -20\sim+85^\circ\text{C}$	10	10K cycle
		$T_A = -40\sim+105^\circ\text{C}$	5	10K cycle
t_{RET}	data retention	$T_A = -40\sim+105^\circ\text{C}$	10	year
t_{PROG}	Page erasure time	$T_A = -40\sim+105^\circ\text{C}$	1	ms
t_{ERASE}	Sector Erase (4K)	$T_A = -40\sim+105^\circ\text{C}$	2	ms
	Chip erase (2M)	$T_A = -40\sim+105^\circ\text{C}$	2000	ms

4.3.14 I/O Port Characteristics

General Input/Output Characteristics

Unless otherwise specified, parameters listed below are measured under the conditions in Table 4-4. All I/O ports are CMOS and TTL compatible.

Table 4-28 I/O Static Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{IH}	Input high level voltage	$V_{\text{DD}}=3.3\text{V}$	2	-	V_{DD}	V
		$V_{\text{DD}}=2.3\text{V}$	1.7	-	V_{DD}	
V_{IL}	Input low level voltage	$V_{\text{DD}}=3.3\text{V}$	VSS	-	0.8	
		$V_{\text{DD}}=2.3\text{V}$	VSS	-	0.7	
V_{hys}	Schmitt trigger hysteresis voltage ⁽¹⁾	$V_{\text{DD}}=3.3\text{V}$	200	-	-	mV
		$V_{\text{DD}}=2.3\text{V}$	165	-	-	
$V_{\text{IL sdram}}$	SDRAM IO Input low level voltage	$V_{\text{DD}}=3.3\text{V}$	VSS	-	0.9	V
$V_{\text{IH sdram}}$	SDRAM IO Input high level voltage	$V_{\text{DD}}=3.3\text{V}$	2.3	-	V_{DD}	V

V _{hys sdram}	Schmitt trigger hysteresis voltage ⁽¹⁾	V _{DD} =3.3V	200	-	-	V
I _{lkg}	Input leakage current ⁽³⁾	V _{DD} =Maximum	-5	-	5	μA
		V _{PAD} =0 或 V _{PAD} =V _{DD} ⁽⁵⁾				
I _{fs}	Input leakage current for FT GPIO ⁽³⁾	V _{DD} =0, V _{PAD} =5.5V	-	-	20	uA
R _{PU}	Weak pull-up equivalent resistance ⁽⁴⁾	V _{DD} =3.3V, V _{IN} = V _{SS}	16	-	61.4	kΩ
		V _{DD} =2.3~3.3V, V _{IN} = V _{SS}	16	-	142.6	kΩ
R _{PD}	Weak pull-down equivalent resistance ⁽⁴⁾	V _{DD} =3.3V, V _{IN} = V _{DD}	16	-	61.4	kΩ
		V _{DD} =2.3~3.3V, V _{IN} = V _{DD}	16	-	142.6	kΩ
C _{IO}	I/O pin capacitance	-	-	5	-	pF

- Schmitt trigger hysteresis voltage at switching level. Results based on evaluation, not tested in production.
- At least 100mV.
- If there is reverse current injection between adjacent pins, leakage current may exceed the maximum value.
- Pull-up and pull-down resistors are implemented via switchable PMOS/NMOS.
- V_{PAD} refers to the I/O pin input voltage.

All I/O ports are CMOS and TTL compatible (no software configuration required). Their characteristics consider stringent CMOS process or TTL parameters:

Output Drive Current

GPIO (General Purpose I/O ports) can sink or source up to ±12mA of current. In user applications, the number of I/O pins must ensure that the drive current does not exceed the absolute maximum ratings defined in section 4.2:

- The total current drawn from V_{DD} by all I/O ports plus the MCU's maximum operating current must not exceed I_{VDD} (Table 4-2).
- The total current sunk into V_{SS} by all I/O ports plus the MCU's maximum current sourced to V_{SS} must not exceed I_{VSS} (Table 4-2).

Output Voltage

Unless otherwise specified, parameters in Table 4-31 are measured at room temperature (25°C) and under supply voltages per Table 4-4 . All I/O ports are CMOS and TTL compatible.

Table 4-29 FT IO Drive Capability Table⁽¹⁾

Drive Level	I _{OH} , VDD=3.3V	I _{OL} , VDD=3.3V	I _{OH} , VDD=2.5V	I _{OL} , VDD=2.5V	Unit
2	2.7	3.3	1.9	2.3	mA
4	5.7	6.6	4.1	4.6	mA
8	11.2	13.3	8	9.3	mA
12	16.8	19.9	12.1	13.9	mA

- Guaranteed by design, not tested in production

Table 4-30 TC IO Drive Capability Table⁽¹⁾

Drive Level	I _{OH} , V _{DD} =3.3V	I _{OL} , V _{DD} =3.3V	I _{OH} , V _{DD} =2.5V	I _{OL} , V _{DD} =2.5V	Unit
2	8.1	6.1	3.1	4.5	mA
4	16.2	12.2	6.2	9.1	mA
8	28.3	21.4	10.9	16	mA
12	44.1	33.5	17.2	25.2	mA

- Guaranteed by design, not tested in production.

 Table 4-31 Output Voltage Characteristics⁽³⁾

Symbol	Parameter	Conditions	Min	Max	Unit
V _{OL} ⁽¹⁾	Output low level voltage	V _{DD} =3.3V, I _{OL} ⁽⁴⁾ = 2/4/8/12	V _{SS}	0.4	V
		V _{DD} =2.3V, I _{OL} ⁽⁴⁾ = 2/4/8/12	V _{SS}	0.4	
V _{OH} ⁽²⁾	Output high level voltage	V _{DD} =3.3V, I _{OH} ⁽⁴⁾ = 2/4/8/12	2.4	V _{DD}	
		V _{DD} =2.3V, I _{OH} ⁽⁴⁾ = 2/4/8/12	2	V _{DD}	

- I_{IO} current drawn by the chip must comply with the absolute maximum ratings in Table 4-2. Total I_{IO} for all I/O and control pins must not exceed I_{VSS}.
- I_{IO} current drawn by the chip must comply with the absolute maximum ratings in Table 4-2. Total I_{IO} for all I/O and control pins must not exceed I_{VDD}.
- Results based on evaluation, not tested in production.
- Actual drive capability, see Table 4-29.
- PC13, PC14, and PC15 are excluded.

Output Buffer Timing Characteristics

Unless otherwise specified, the parameters listed in Table 4-32 and Table 4-33 are measured at 25°C and under supply voltages per Table 4-4.

 Table 4-32 Output Timing Characteristics (TC IO)⁽¹⁾

Pmode	Symbol	Parameter	Conditions	Min	Max	Unit
00	F _{max} ⁽²⁾	Maximum Frequency	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	19	MHz
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	10	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	31	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	16	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	84	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	48	
	t _r /t _f ⁽³⁾	Fall time from high level to low level and rise time from low level to high level	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	17.9	ns
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	33.5	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	11	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	20.6	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	4.1	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	7.7	
01	F _{max} ⁽²⁾	Maximum frequency	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	51	MHz

			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	32		
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	85		
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	45		
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	222		
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	118		
	t _r /t _f ⁽³⁾	Fall time from high level to low level and rise time from low level to high level	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	6.6		ns
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	9.9		
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	4.1		
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	7.7		
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	1.7		
10	F _{max} ⁽²⁾	Maximum frequency	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	87	MHz	
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	46		
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	143		
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	75		
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	339		
	t _r /t _f ⁽³⁾	Fall time from high level to low level and rise time from low level to high level	C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	185	ns	
			C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	3.92		
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	7.52		
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	2.41		
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	4.61		
11	F _{max} ⁽²⁾	Maximum frequency	C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	1.06	ns	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ^v	-	1.98		
			C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ^v	-	138		
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	69		
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ^v	-	215		
	t _r /t _f ⁽³⁾	Fall time from high level to low level and rise time from low level to high level.	C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	122	MHz	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	467		
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	260		
			C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	2.52		
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	5.05		
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	1.6	ns	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	2.9		
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	0.77		
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	1.385		

1. Design guaranteed.

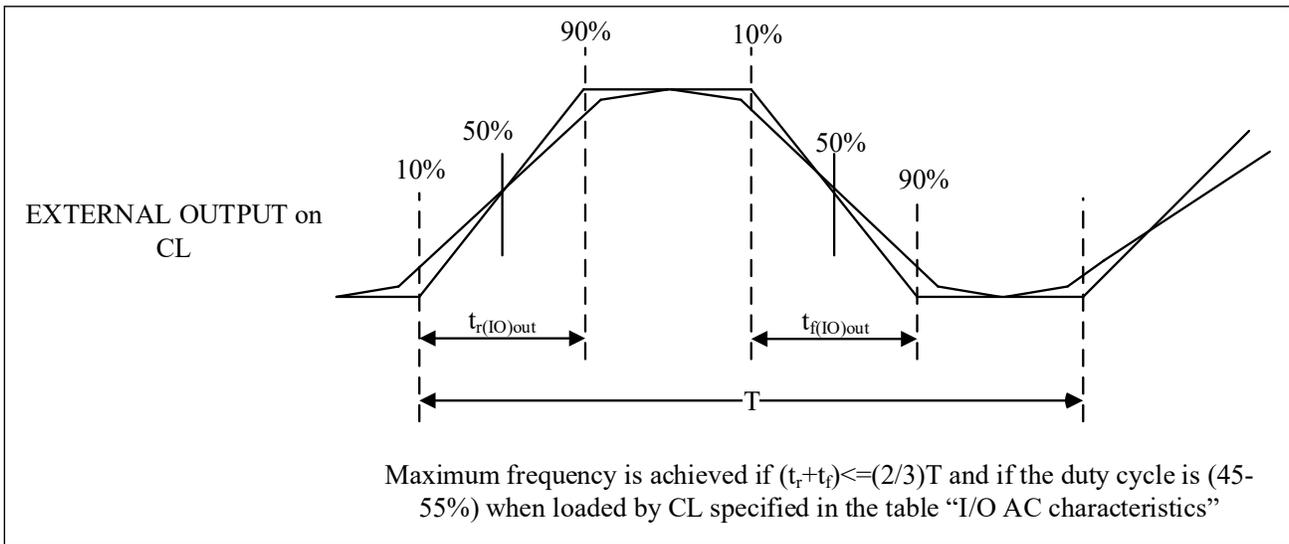
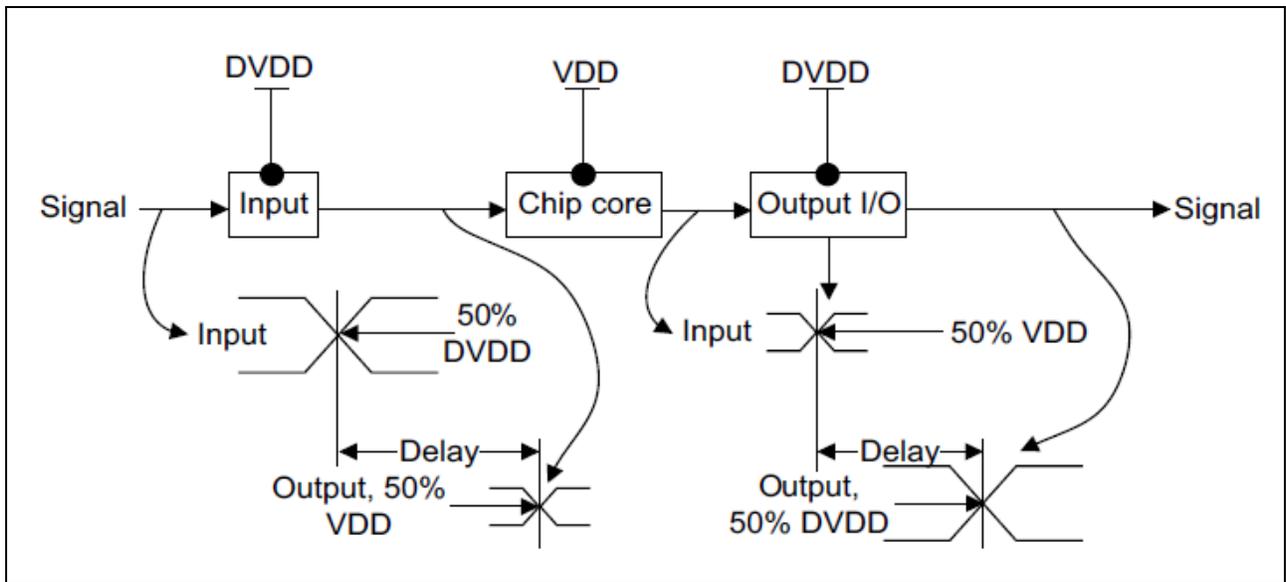
2. The definition conditions for the maximum frequency are as follows:
 $(t_r + t_f) \leq 2/3 T$
 Skew $\leq 1/20 T$
 $45\% < \text{Duty Cycle} < 55\%$
3. The fall time and rise time are defined respectively as the time between 90% and 10% of the output waveform, and between 10% and 90%.
4. Compensation system enabled.

Table 4-33 Output Timing Characteristics (FT IO)⁽¹⁾

PMODE	Symbol	Parameter	Conditions	Min	Max	Unit
00 Fast	F _{max} ⁽²⁾	Maximum Frequency	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	13	MHz
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	6	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	20	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	10	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	46	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	24	
	t _r /t _f ⁽³⁾	Fall time from high to low and rise time from low to high	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	26.4	ns
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	48.8	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	17	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	31.1	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	7.7	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	13.6	
01 Fast	F _{max} ⁽²⁾	Maximum Frequency	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	26	MHz
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	13	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	40	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	21	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	86	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	46	
	t _r /t _f ⁽³⁾	Fall time from high to low and rise time from low to high	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	13.2	ns
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	24.8	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	8.6	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	16.1	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V	-	4	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V	-	7.3	
10	F _{max} ⁽²⁾	Maximum frequency	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	50	MHz
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	36	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	75	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	39	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	151	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	83	
	t _r /t _f ⁽³⁾		C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	6.97	ns

		Fall time from high to low and rise time from low to high	C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	9.65	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	4.66	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	8.4	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	2.26	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ^v	-	4	
11 Fast	F _{max} ⁽²⁾	Maximum frequency	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ^v	-	72	MHz
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	38	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ^v	-	106	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	56	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	202	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	113	
	t _r /t _f ⁽³⁾	Fall time from high to low and rise time from low to high	C=50 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	4.82	ns
			C=50 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	8.9	
			C=30 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	3.28	
			C=30 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	5.93	
			C=10 pF, 2.7 V ≤ V _{DD} ≤ 3.6 V ⁽⁴⁾	-	1.65	
			C=10 pF, 2.3 V ≤ V _{DD} ≤ 2.7 V ⁽⁴⁾	-	2.98	

- Design guarantee.
- The definition conditions for the maximum frequency are as follows:
 $(t_r + t_f) \leq 2/3 T$
 Skew $\leq 1/20 T$
 $45\% < \text{Duty Cycle} < 55\%$
- The fall time and rise time are defined as the time between 90% and 10% of the output waveform, and between 10% and 90% of the waveform, respectively.
- Enable compensation system.

Figure 4-11 Definition of Input/Output AC Characteristics

Figure 4-12 Transmission Delay


4.3.15 NRST Pin Characteristics

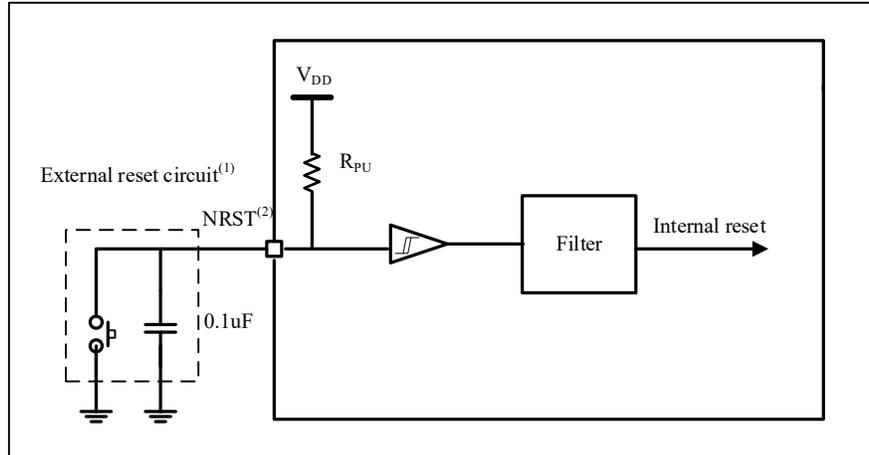
The NRST pin input drive uses CMOS technology, and an internal non-removable pull-up resistor, RPU (see Table 4-34), is integrated. Unless otherwise specified, the parameters listed in Table 4-34 are measured under conditions where the ambient temperature is 25°C, and the supply voltage meets the conditions specified in Table 4-4.

Table 4-34 NRST Pin Characteristics

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$V_{IL(NRST)}^{(1)}$	NRST Input Low Voltage	-	VSS	-	$0.3 * V_{DD}$	V
$V_{IH(NRST)}^{(1)}$	NRST Input High Voltage	-	$0.7 * V_{DD}$	-	V_{DD}	
$V_{hys(NRST)}$	NRST Schmitt Trigger Hysteresis	-	-	70	-	mV
R_{PU}	Weak Pull-up Equivalent Resistance ⁽²⁾	$V_{IN} = V_{SS}$	30	50	70	k Ω
$V_{F(NRST)}^{(1)}$	NRST Input Filtered Pulse	$V_{DD} = 3.3V$	-	-	100	ns
$V_{NF(NRST)}^{(1)}$	NRST Input Non-Filtered Pulse	$V_{DD} = 3.3V$	300	-	-	ns

1. Guaranteed by design, not tested during production.
2. The pull-up resistor is designed as a true resistor in series with a switchable PMOS. The resistance of the PMOS/NMOS switch is very small (about 10%).

Figure 4-13 Recommended NRST Pin Protection



1. Filtering function.
2. The user must ensure that the potential of the NRST pin is lower than the maximum $V_{IL(NRST)}$ listed in Table 4-34; otherwise, the MCU cannot be reset.

4.3.16 TIM Timer Characteristics

The parameters listed in Table 4-35, Table 4-36, Table 4-37, and Table 4-38 are guaranteed by design.

For details on the characteristics of input/output multiplexing function pins (output compare, input capture, external clock, PWM output), please refer to section 4.3.14.

Table 4-35 ATIM1/2/3/4 Characteristics ⁽¹⁾

Symbol	Parameter	Condition	Min	Max	Unit
t _{res(TIM)}	Timer Resolution Time	-	1	-	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	3.33	-	ns
f _{EXT}	External Clock Frequency for CH1 to CH4	-	0	f _{TIMxCLK} /2	MHz
		f _{TIMxCLK} = 300MHz	0	150	MHz
Restim	Timer Resolution	-	-	16	bit
t _{COUNTER}	16-bit Counter Clock Cycle (Internal Clock)	-	1	65536	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	0.00333	218	μs
t _{MAX_COUNT}	Maximum Possible Count	-	-	65536x65536	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	-	14.3	s

1. Guaranteed by design, not tested during production.

Table 4-36 GTIMA1/2/3/4/5/6/7 Characteristics ⁽¹⁾

Symbol	Parameter	Condition	Min	Max	Unit
t _{res(TIM)}	Timer Resolution Time	-	1	-	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	3.33	-	ns
f _{EXT}	External Clock Frequency for CH1 to CH4	-	0	f _{TIMxCLK} /2	MHz
		f _{TIMxCLK} = 300MHz	0	150	MHz
Restim	Timer Resolution	-	-	16	bit
t _{COUNTER}	16-bit Counter Clock Cycle (Internal Clock)	-	1	65536	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	0.00333	218	μs
t _{MAX_COUNT}	Maximum Possible Count	-	-	65536x65536	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	-	14.3	s

1. Guaranteed by design, not tested during production.

Table 4-37 GTIMB1/2/3 Characteristics ⁽¹⁾

Symbol	Parameter	Condition	Min	Max	Unit
t _{res(TIM)}	Timer Resolution Time	-	1	-	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	3.33	-	ns
f _{EXT}	External Clock Frequency for CH1 to CH4	-	0	f _{TIMxCLK} /2	MHz
		f _{TIMxCLK} = 300MHz	0	150	MHz
Restim	External Clock Frequency for CH1 to CH4	-	-	16	bit
t _{COUNTER}	16-bit Counter Clock Cycle (Internal Clock)	-	1	65536	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	0.00333	218	μs

t _{MAX_COUNT}	Maximum Possible Count	-	-	65536x65536	t _{TIMxCLK}
		f _{TIMxCLK} = 300MHz	-	14.3	s

1. Guaranteed by design, not tested during production.

Table 4-38 LPTIM1/2/3/4/5 Characteristics ⁽¹⁾

Symbol	Parameter	Condition	Min	Max	Unit
t _{res(TIM)}	Timer Resolution Time	-	1	-	t _{TIMxCLK}
		f _{TIMxCLK} = 150MHz	6.67	-	ns
f _{EXT}	External Clock Frequency for CH1 to CH4	-	0	f _{TIMxCLK} /2	MHz
		f _{TIMxCLK} = 150MHz	0	75	MHz
Res _{TIM}	Timer Resolution	-	-	16	bit
t _{COUNTER}	16-bit Counter Clock Cycle (Internal Clock)	-	1	65536	t _{TIMxCLK}
		f _{TIMxCLK} = 150MHz	0.00667	437	μs
t _{MAX_COUNT}	Maximum Possible Count	-	-	128x65536	t _{TIMxCLK}
		f _{TIMxCLK} = 150MHz	-	55.9	ms

1. Guaranteed by design, not tested during production.

4.3.17 SHRTIM Characteristics

Unless otherwise specified, the parameters in Table 4-39 are measured using ambient temperature and supply voltage that comply with the conditions in Table 4-4.

Table 4-39 SHRTIM Characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
T _A	Timer ambient temperature range	f _{SHRTIM} = 312.5 MHz	-40	-	105	°C
f _{SHRTIM}	HRTIM input clock for PLL calibration	As per T _A conditions	-	-	312.5	MHz
t _{SHRTIM}			3.2	-	-	ns
t _{RES(SHRTIM)}	High-resolution step size	f _{SHRTIM} = 312.5MHz, T _A from -40 to 105°C	-	100	-	ps
R _{ESSHRTIM}	Timer resolution	-	-	-	16	bit
t _{DTG}	Dead time generator clock period	-	0.125	-	16	t _{SHRTIM}
		f _{SHRTIM} = 312.5MHz	0.4	-	51.2	ns
t _{DTR} / t _{DTF} max	Dead time range (absolute value)	-	-	-	511	t _{DTG}
		f _{SHRTIM} = 312.5MHz	0.2	-	26.16	µs
f _{CHPFRQ}	Chopper stage clock frequency	-	1/256	-	1/16	f _{SHRTIM}
		f _{SHRTIM} = 312.5MHz	1.221	-	19.531	MHz
t _{1STPW}	Chopper first pulse length	-	16	-	256	t _{SHRTIM}
		f _{SHRTIM} = 312.5MHz	0.051	-	0.819	µs

1. Guaranteed by design, not tested in production.

Table 4-40 SHRTIM output response to fault protection⁽¹⁾

Symbol	Parameter	Condition	Min	Typ	Max ⁽²⁾	Unit
t _{LAT(DF)}	Digital fault response latency	Propagation delay from SHRTIM_FALTINx digital input to SHRTIM_CHxy output pin	-	9	13	ns
T _{W(FALT)}	Minimum Fault pulse width	-	6.4	-	-	
t _{LAT(AF)}	Analog fault response latency	Propagation delay from COMPx_INP digital input to SHRTIM_CHxy	-	23	40	

1. Refer to Fault paragraph in SHRTIM section.

2. Guaranteed by design, not tested in production.

Table 4-41 SHRTIM output response to external events 1 to 10 (low latency mode⁽¹⁾)

Symbol	Parameter	Conditions	Min	Typ ⁽²⁾	Max ⁽²⁾	Unit
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$t_{LAT(DEEV)}$	Digital external event response delay	Propagation delay from SHRTIM_EXEVx digital input to SHRTIM_CHxy output pin (30pF load)	-	10	15	ns
$T_{W(EEV)}$	Minimum external event pulse width	-	6.4	-	-	ns
$t_{LAT(AEEV)}$	Analog external event response delay	Propagation delay from comparator COMPx_INP input pin to SHRTIM_CHxy output pin (30pF load)	-	24	42	ns

1. Please refer to the external event delay paragraph in the SHRTIM section of the user manual.
2. Data are based on characterization results, not tested in production.

Table 4-42 SHRTIM output response to external events 1 to 10 (synchronous mode⁽¹⁾)

Symbol	Parameter	Conditions	Min	Typ ⁽²⁾	Max ⁽²⁾	Unit
$t_{LAT(DEEV)}$	Digital external event response delay	Propagation delay from SHRTIM_EXEVx digital input pin to SHRTIM_CHxy output pin (30pF load)(3)	-	46	50	ns
$t_{LAT(AEEV)}$	Analog external event response delay	Propagation delay from COMPx_INP input pin to SHRTIM_CHxy output pin (30pF load)(3)	-	58	71	ns
$t_{W(EEV)}$	Minimum external event pulse width	-	6.4	-	-	ns
$T_{JIT(EEV)}$	External event response jitter	Delay jitter from SHRTIM_EXEVx digital input or COMPx_INP to SHRTIM_CHxy output pin	-	-	1	$t_{SHRTIM}^{(4)}$

1. Please refer to the external event delay paragraph in the SHRTIM section of the user manual.
2. Data are based on characterization results, not tested in production.
3. This parameter is given at $f_{SHRTIM} = 312.5$ MHz.
4. $t_{SHRTIM} = 1 / f_{SHRTIM}$, $f_{SHRTIM} = 312.5$ MHz.

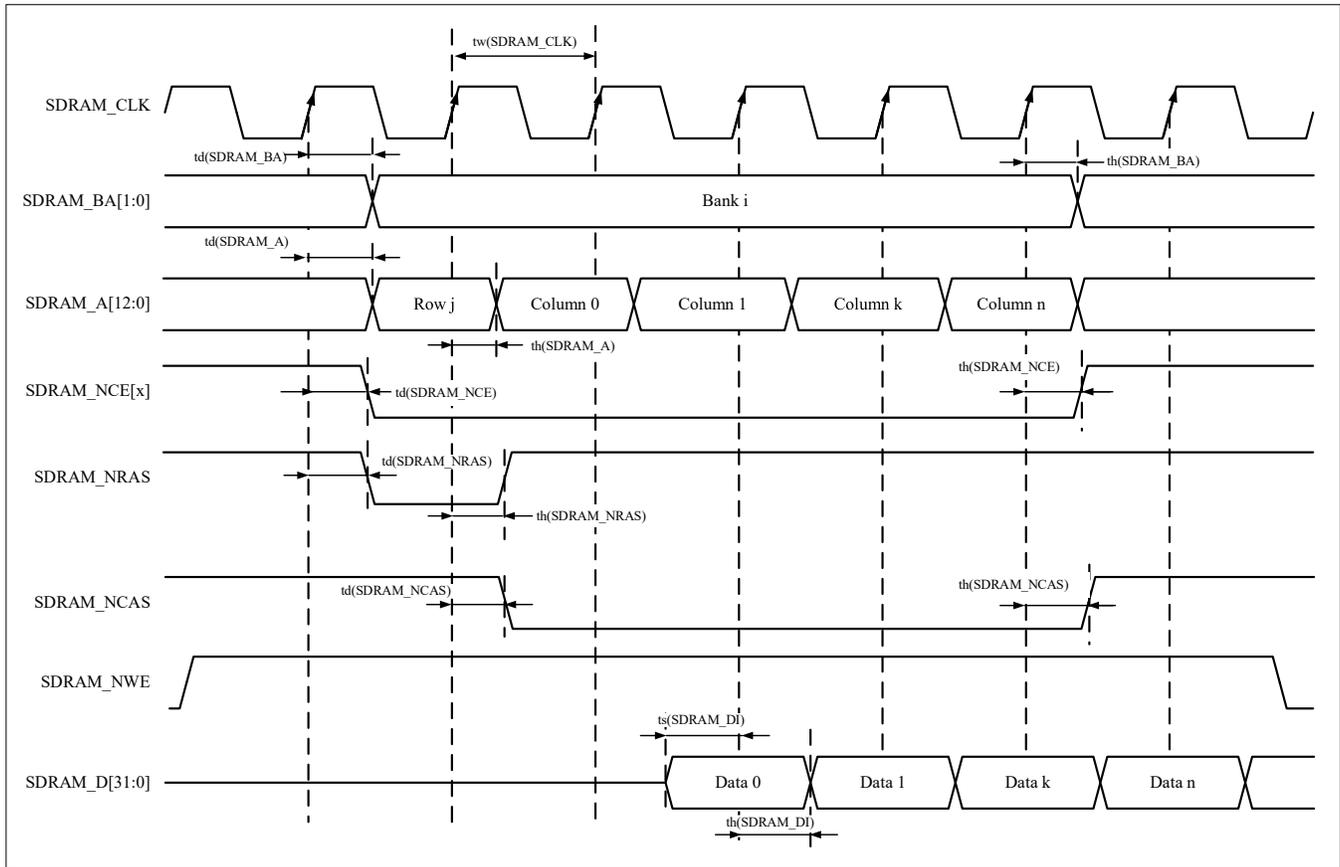
Table 4-43 SHRTIM synchronization input/output⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{W(SYNCIN)}$	Minimum pulse width for synchronization input (including SHRTIM_SCIN)	-	1	-	-	t_{SHRTIM}
$t_{RES(ESR)}$	Response time to external synchronization request	-	-	-	3	t_{SHRTIM}
$t_{W(SYNCOUT)}$	Pulse width of SHRTIM_SCOU output	-	-	16	-	t_{SHRTIM}
		$f_{SHRTIM}=312.5$ MHz	-	51.2	-	ns

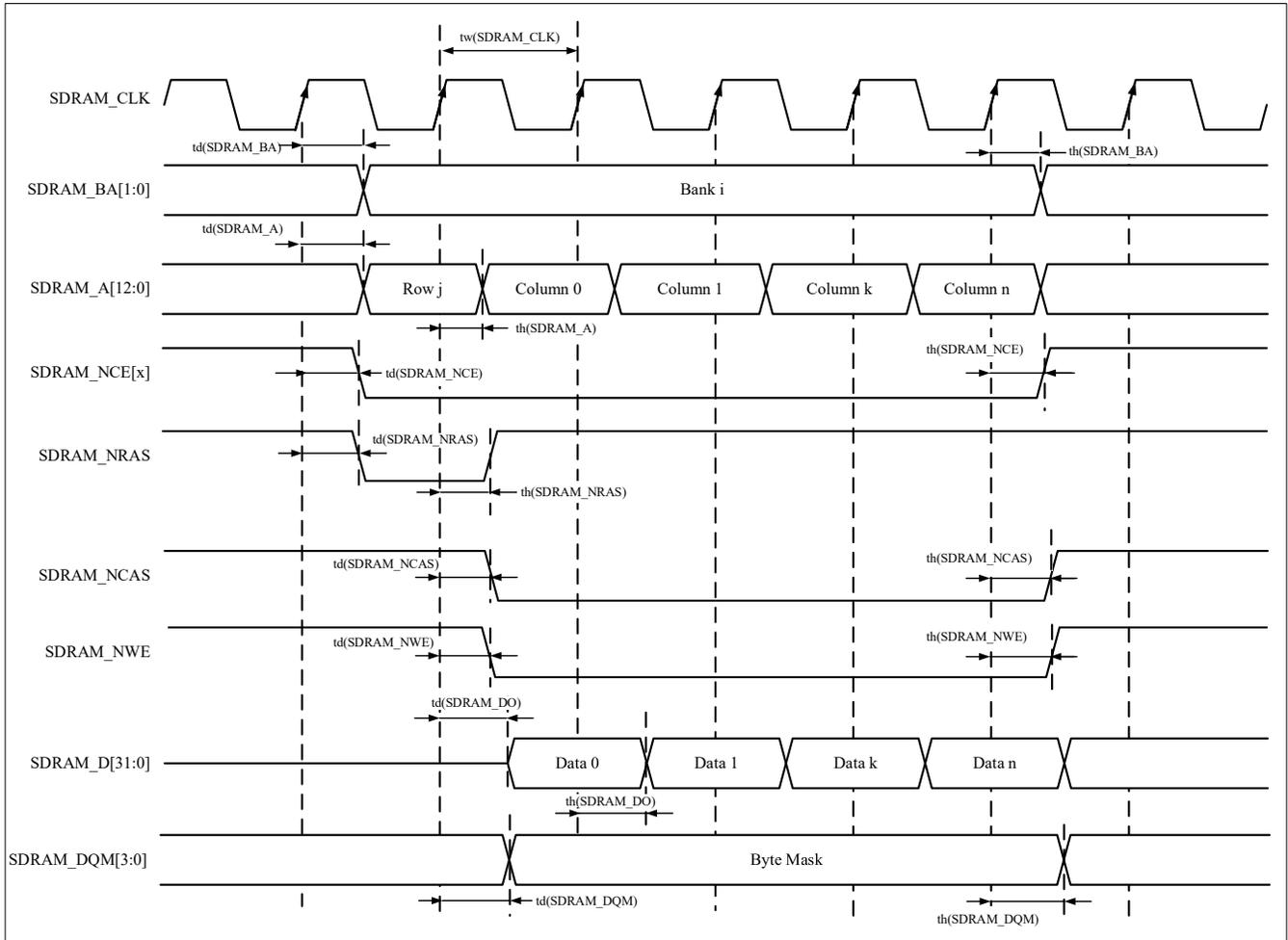
1. Guaranteed by design, not tested in production.

4.3.18 SDRAM Characteristics

Figure 4-14 SDRAM Read Timing Diagram


 Table 4-44 SDRAM Read Timing ⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{SDRAM_CLK})$	SDRAM_CLK Period	7.51(133M)	-	ns
$t_d(\text{SDRAM_BA})$	Bank Address Valid Time	-	4.0	
$t_h(\text{SDRAM_BA})$	Bank Address Hold Time	0.8	-	
$t_d(\text{SDRAM_A})$	Address (Row/Column) Valid Time	-	3.51	
$t_h(\text{SDRAM_A})$	Address (Row/Column) Hold Time	0.8	-	
$t_d(\text{SDRAM_NCE})$	Chip Select Valid Time	-	3.51	
$t_h(\text{SDRAM_NCE})$	Chip Select Hold Time	0.8	-	
$t_d(\text{SDRAM_NRAS})$	SDRAM_NRAS Valid Time	-	3.51	
$t_h(\text{SDRAM_NRAS})$	SDRAM_NRAS Hold Time	0.8	-	
$t_d(\text{SDRAM_NCAS})$	SDRAM_NCAS Valid Time	-	3.51	
$t_h(\text{SDRAM_NCAS})$	SDRAM_NCAS Hold Time	0.8	-	
$t_s(\text{SDRAM_DI})$	Data Input Setup Time	1.2	-	
$t_h(\text{SDRAM_DI})$	Data Input Hold Time	TBD	-	

Figure 4-15 SDRAM Write Timing Diagram

Table 4-45 SDRAM Write Timing ⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{SDRAM_CLK})$	SDRAM_CLK Period	7.51(133M)	-	ns
$t_d(\text{SDRAM_BA})$	Bank Address Valid Time	-	3.51	
$t_h(\text{SDRAM_BA})$	Bank Address Hold Time	0.8	-	
$t_d(\text{SDRAM_A})$	Address (Row/Column) Valid Time	-	3.51	
$t_h(\text{SDRAM_A})$	Address (Row/Column) Hold Time	0.8	-	
$t_d(\text{SDRAM_NCE})$	Chip Select Valid Time	-	3.51	
$t_h(\text{SDRAM_NCE})$	Chip Select Hold Time	0.8	-	
$t_d(\text{SDRAM_NRAS})$	SDRAM_NRAS Valid Time	-	3.51	
$t_h(\text{SDRAM_NRAS})$	SDRAM_NRAS Hold Time	0.8	-	
$t_d(\text{SDRAM_NCAS})$	SDRAM_NCAS Valid Time	-	3.51	

$t_h(\text{SDRAM_NCAS})$	SDRAM_NCAS Hold Time	0.8	-
$t_d(\text{SDRAM_NWE})$	Write Enable Valid Time	-	3.51
$t_h(\text{SDRAM_NWE})$	Write Enable Hold Time	0.8	-
$t_d(\text{SDRAM_DO})$	Data Output Valid Time	-	3.51
$t_h(\text{SDRAM_DO})$	Data Output Hold Time	0.6	-
$t_d(\text{SDRAM_DQM})$	Output Byte Mask Valid Time	-	3.51
$t_h(\text{SDRAM_DQM})$	Output Byte Mask Hold Time	0.8	-

4.3.19 Watchdog Features

Table 4-46 IWDG Maximum and Minimum Count Reset Times (LSI = 32 KHz)

Prescaler	PD[2:0]	Minimum Duration RL[11:0]=0	Maximum Duration RL[11:0]=0xFFF	Unit
/4	000	0.125	512	ms
/8	001	0.25	1024	
/16	010	0.5	2048	
/32	011	1.0	4096	
/64	100	2.0	8192	
/128	101	4.0	16384	
/256	11x	8.0	32768	

1. Guaranteed by design, not tested in production.

Table 4-47 WWDG Maximum and Minimum Count Reset Times (PCLK1 = 150MHz)

Prescaler	TIMERB[1:0]	Minimum Timeout	Maximum Timeout	Unit
/1	0	0.02728	445.54	ms
/2	1	0.05456	891.07	
/4	2	0.1088	1782.14	
/8	3	0.2184	3564.29	

1. Guaranteed by design, not tested in production.

4.3.20 I2C Interface Features

Unless specified otherwise, the parameters listed in Table 4-48 are measured with environmental temperature, f_{PCLK1} frequency, and V_{DD} supply voltage meeting the conditions in Table 4-4.

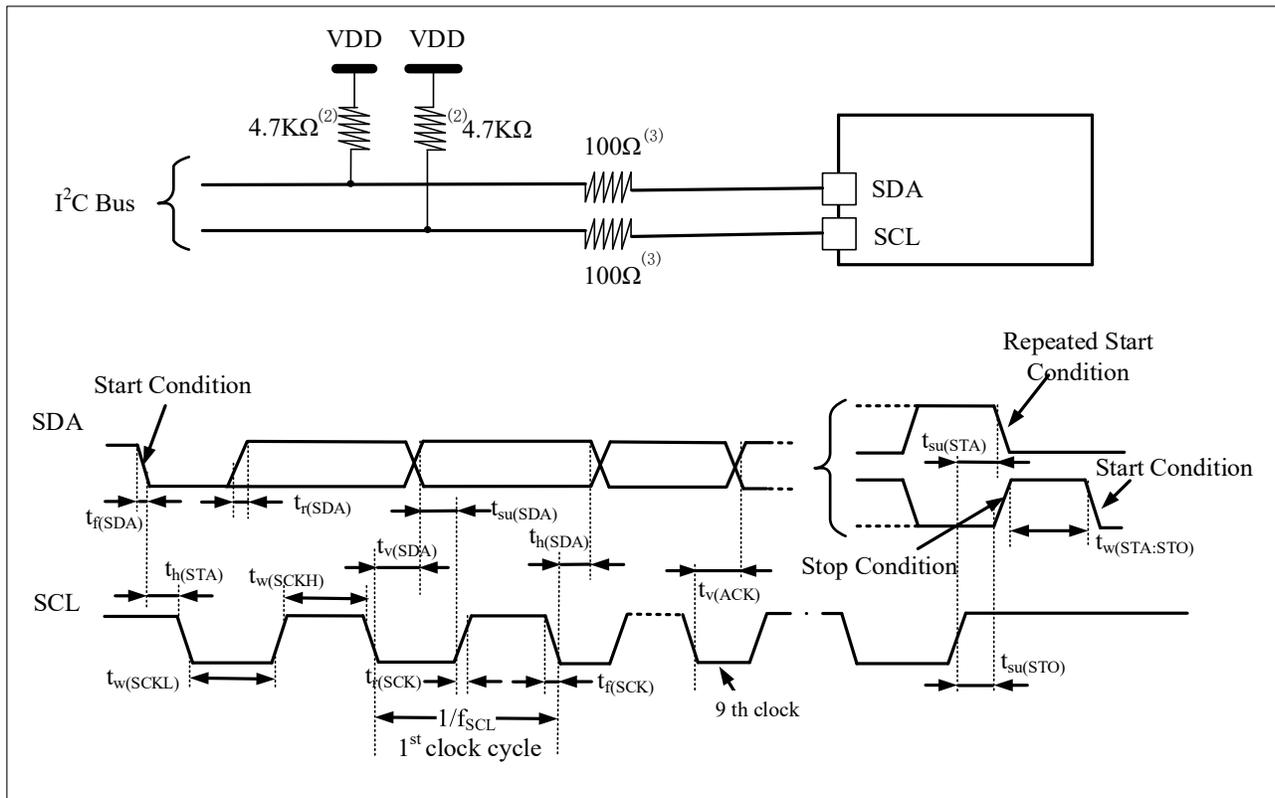
This product's I2C interface complies with the standard I2C communication protocol, but with the following limitations: SDA and SCL are not "true" open-drain pins. When configured for open-drain output, the PMOS transistor between the pin and V_{DD} is turned off, but still exists.

The characteristics of the I2C interface are listed in Table 4-48. For detailed characteristics of I2C pins (SDA and SCL) and input/output multiplexing features, refer to section 4.3.14.

Table 4-48 I2C Interface Features ⁽¹⁾

Symbol	Parameter	Standard Mode		Fast Mode		Fast+Mode		High-speed mode		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
f_{SCL}	I2C Interface Frequency	0.0	100	0	400	0	1000	0	3400	KHz
$t_{h(STA)}$	Start Condition Hold Time	4.0	-	0.6	-	0.26	-	0.16	-	μ s
$t_{w(SCLL)}$	SCL Clock Low Time	4.7	-	1.3	-	0.5	-	0.16	-	μ s
$t_{w(SCLH)}$	SCL Clock High Time	4.0	-	0.6	-	0.26	-	0.06	-	μ s
$t_{su(STA)}$	Repeated Start Condition Setup Tim	4.7	-	0.6	-	0.26	-	0.16	-	μ s
$t_{h(SDA)}$	SDA Data Hold Time	0	-	0	-	0	-	0	-	μ s
$t_{su(SDA)}$	SDA Setup Time	250	-	100	-	50	-	10	-	ns
$t_{r(SDA)}$ $t_{r(SCL)}$	SC, SDA Rise Time	-	1000	20	300	-	120	10	SCL=40 SDA=80	ns
$t_{f(SDA)}$ $t_{f(SCL)}$	SCL, SDA Fall Time	-	300	-	300	-	120	10	SCL=40 SDA=80	ns
$t_{su(STO)}$	Stop Condition Setup Time	4.0	-	0.6	-	0.26	-	0.16	-	μ s
$t_{w(STO:STA)}$	Stop Condition to Start Condition Time (Bus Idle)	4.7	-	1.3	-	0.5	-	-	-	μ s
C_b	Capacitive Load per Bus	-	400	-	400	-	400	-	400	pf
$t_v(SDA)$	Data Valid Time	-	3.45	-	0.9	-	0.45	-	0.1	μ s
$t_v(ACK)$	Acknowledge Valid Time	-	3.45	-	0.9	-	0.45	-	0.1	μ s
t_{SP}	Input Filter Spike Pulse Width Suppression	0	Analog filter: 35ns. Digital filter: up to 15 I2CCLK period	0	Analog filter: 35ns. Digital filter: up to 15 I2CCLK period	0	Analog filter: 35ns. Digital filter: up to 15 I2CCLK period	0	Analog filter: 35ns. Digital filter: up to 15 I2CCLK period	ns

1. Guaranteed by design, not tested in production.

Figure 4-16 I2C Bus AC Waveform and Measurement Circuit⁽¹⁾


1. Measurement points are set at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.
2. Pull-up resistor values depend on the I2C interface speed.
3. Resistance values depend on actual electrical characteristics; serial resistors can be omitted and signal lines can be directly connected.

4.3.21 SPI/I2S Interface Characteristics

Unless otherwise specified, the SPI parameters listed in Table 4-49 and the I2S parameters listed in Table 4-50 are measured at ambient temperature (25°C), f_{PCLKx} frequency, and V_{DD} supply voltage meeting the conditions in Table 4-4.

For details on the characteristics of input/output multiplexed function pins (NSS, SCLK, MOSI, MISO for SPI; WS, CLK, SD for I2S), refer to Section 4.3.14(I/O Port Characteristics).

 Table 4-49 SPI Characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{SCK}	SPI clock frequency	$2.3 < V_{DD} < 3.6\text{ V}$	-	-	50	MHz
$t_{su(NSS)}^{(1)}$	NSS setup time	Slave mode	2	-	-	-

$t_{h(NSS)}^{(1)}$	NSS hold time	Slave mode	1	-	-	ns
$t_{w(SCKH)}^{(1)}$ $t_{w(SCKL)}^{(1)}$	SCK high and low time	Master mode	$T_{plk}-2$	T_{plk}	$T_{plk}+2$	
$t_{su(MI)}^{(1)}$	Data input setup time	Master mode	1	-	-	
$t_{su(SI)}^{(1)}$		Slave mode	1	-	-	
$t_{h(MI)}^{(1)}$	Data input hold time	Master mode	4	-	-	
$t_{h(SI)}^{(1)}$		Slave mode	2	-	-	
$t_{a(SO)}^{(1)(2)}$	Data output access time	Slave mode	9	13	27	
$t_{dis(SO)}^{(1)(3)}$	Data output disable time	Slave mode	0	1	5	
$t_{v(SO)}^{(1)}$	Data output valid time	Slave mode 2.7<VDD<3.6 V	-	12.5	16	
$t_{v(MO)}^{(1)}$		Slave mode 2.3<VDD<3.6 V	-	12.5	17	
		Master mode	-	1	3	
$t_{h(SO)}^{(1)}$	Data output hold time	Slave mode 2.3<VDD<3.6 V	10	-	-	
$t_{h(MO)}^{(1)}$		Master mode	0	-	-	

1. Guaranteed by design, not tested in production.
2. Minimum value indicates the minimum time to drive the output, maximum value indicates the maximum time to correctly acquire the data.
3. Minimum value indicates the minimum time to turn off the output, maximum value indicates the maximum time to place the data line in high impedance state.

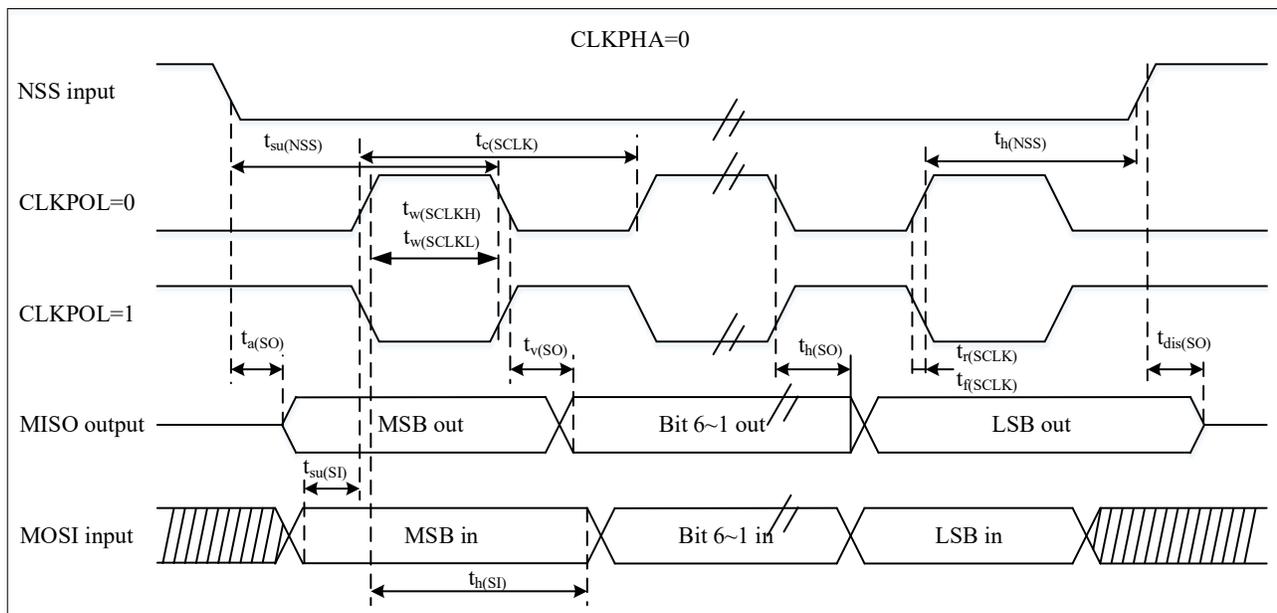
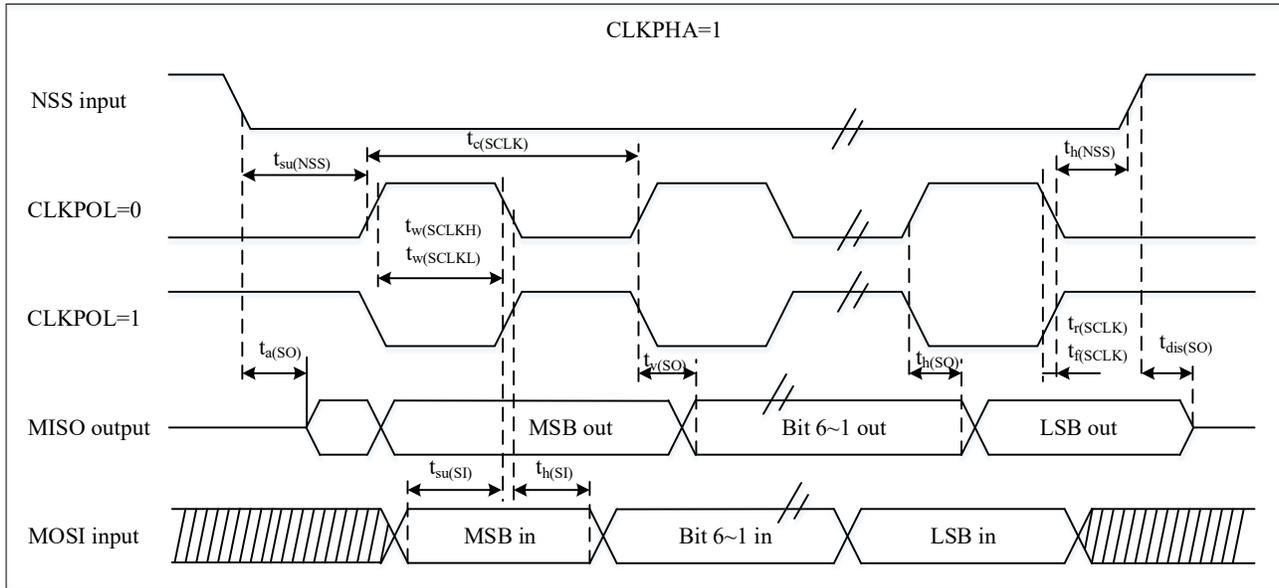
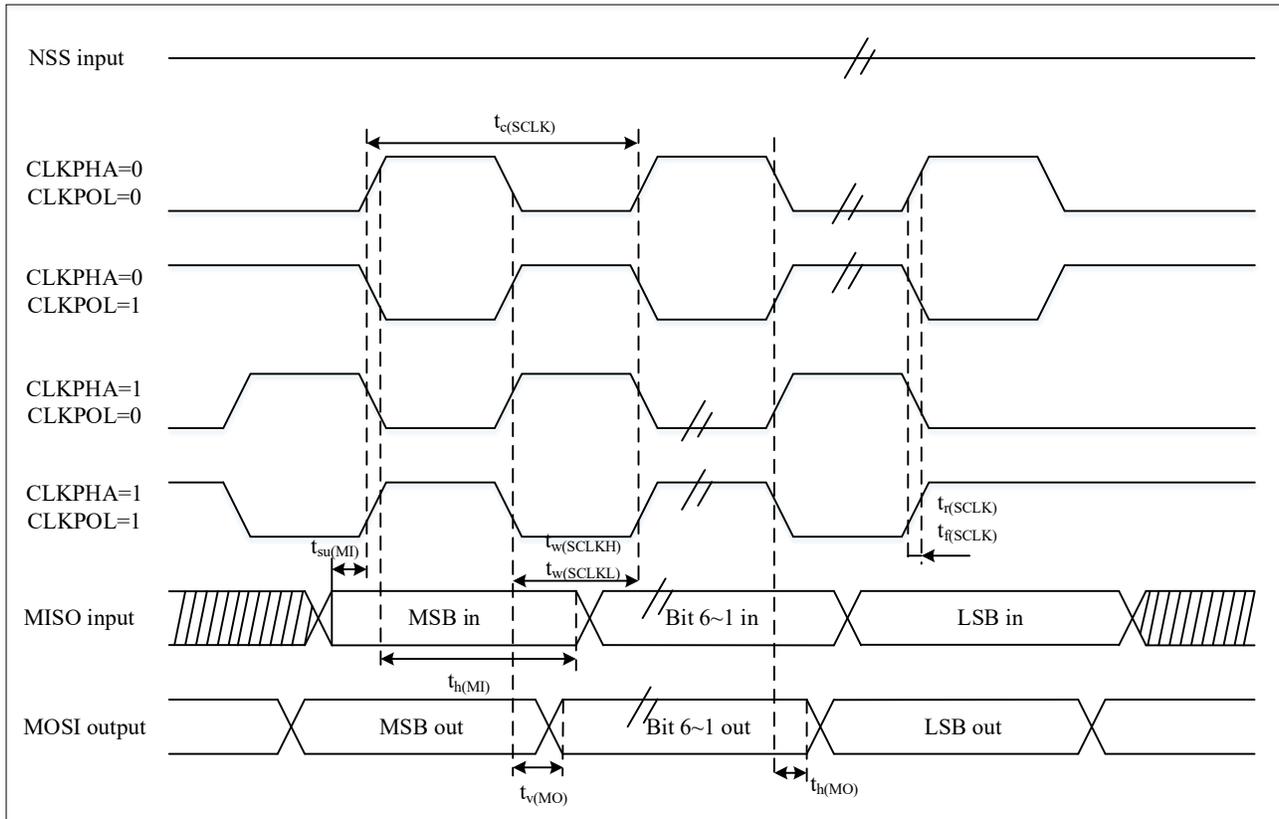
Figure 4-17 SPI Timing Diagram - Slave Mode and CLKPHA=0


Figure 4-18 SPI Timing Diagram — Slave Mode and CLKPHA=1⁽¹⁾


1. Measurement points are set at $0.5V_{DD}$, with external load capacitance (CL) of 30pF.

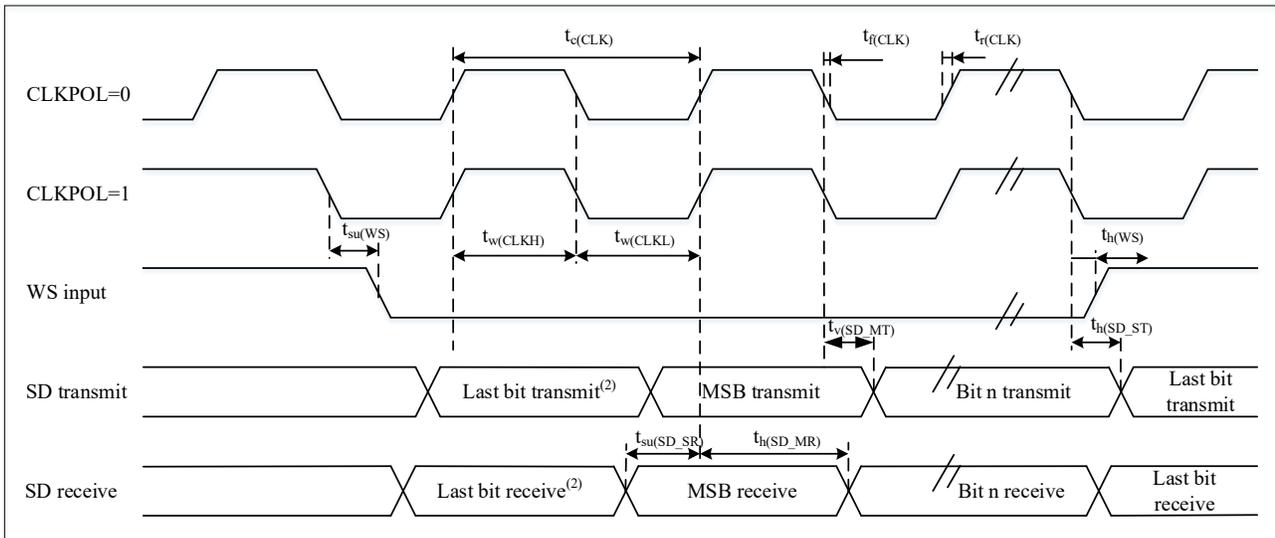
Figure 4-19 SPI Timing Diagram — Master Mode⁽¹⁾


1. Measurement points are set at $0.5V_{DD}$, with external load capacitance (CL) of 30pF.

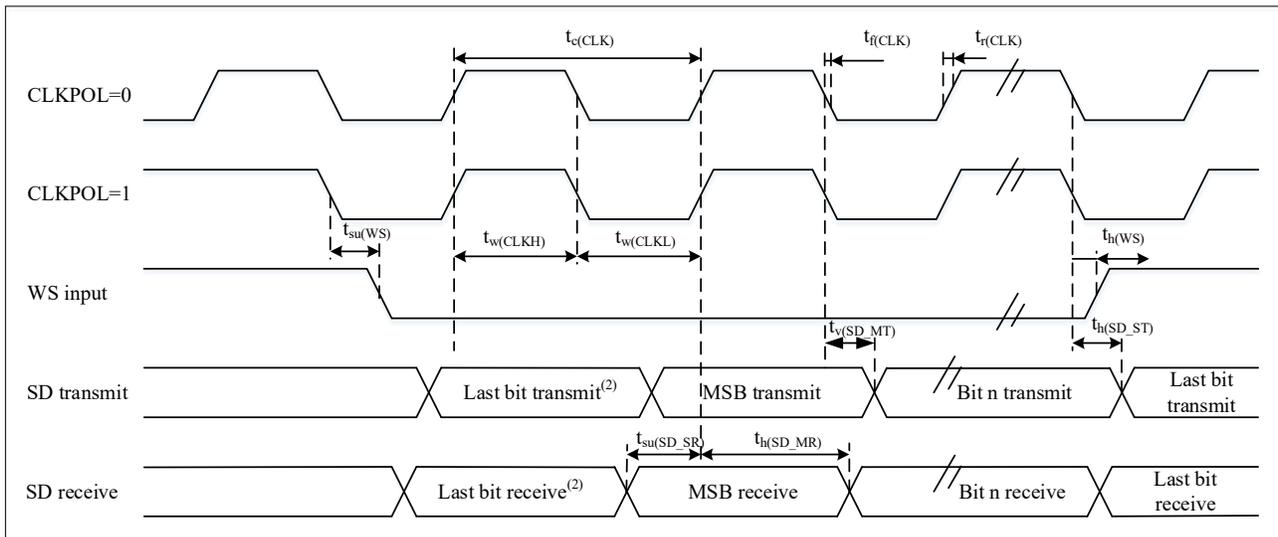
Table 4-50 I2S Characteristics ⁽¹⁾

Symbol	Parameter	Conditions	Min	Max	Unit
f_{MCLK}	I2S master clock frequency	Master mode	256x8K	256Fs ⁽³⁾	MHz
f_{CLK}	I2S clock frequency	Master mode (32bit)	-	64Fs ⁽³⁾	
$1/t_{c(CLK)}$		Slave mode (32bit)	-	64Fs ⁽³⁾	
DuCy(SCK)	I2S slave input clock duty cycle	I2S slave mode	30	70	%
$t_{v(WS)}^{(1)}$	WS valid time	Master mode	I2S2	-	6
			I2S3	-	6
$t_{h(WS)}^{(1)}$	WS hold time	Master mode	I2S2	2	-
			I2S3	2	-
$t_{su(WS)}^{(1)}$	WS setup time	Slave mode	I2S2	7	-
			I2S3	7	-
$t_{h(WS)}^{(1)}$	WS hold time	Slave mode	I2S2	0	-
			I2S3	0	-
$t_{w(CLKH)}^{(1)}$	CLK high and low time	-		312.5	-
$t_{w(CLKL)}^{(1)}$				345	-
$t_{su(SD_MR)}^{(1)}$	Data input setup time	Master receiver	I2S2	6	-
			I2S3	6	-
$t_{su(SD_SR)}^{(1)}$		Slave receiver	I2S2	7	-
			I2S3	7	-
$t_{h(SD_MR)}^{(1)(2)}$	Data output hold time	Master receiver	I2S2	0	-
			I2S3	0	-
$t_{h(SD_SR)}^{(1)(2)}$		Slave receiver	I2S2	1	-
			I2S3	1	-
$t_{v(SD_ST)}^{(1)(2)}$	Data output valid time	Slave transmitter (after enable edge)	I2S2	-	15
			I2S3	-	15
$t_{h(SD_ST)}^{(1)}$	Data output hold time	Slave transmitter (after enable edge)	I2S2	4	-
			I2S3	4	-
$t_{v(SD_MT)}^{(1)(2)}$	Data output valid time	Master transmitter (after enable edge)	I2S2	-	6
			I2S3	-	6
$t_{h(SD_MT)}^{(1)}$	Data output hold time	Master transmitter (after enable edge)	I2S2	0	-
			I2S3	0	-

1. Guaranteed by design, not tested in production.
2. Dependent on f_{CLK} .
3. Audio sampling frequency.

Figure 4-20 I2S Slave Mode Timing Diagram (Philips Protocol) ⁽¹⁾


1. Measurement points are set at $0.3V_{DD}$ and $0.7V_{DD}$.
2. The least significant bit of the previous byte is transmitted/received. There is no transmission/reception of this least significant bit before the first byte.

Figure 4-21 I2S Master Mode Timing Diagram (Philips Protocol) ⁽¹⁾


1. Measurement points are set at $0.3V_{DD}$ and $0.7V_{DD}$.
2. The least significant bit of the previous byte is transmitted/received. There is no transmission/reception of this least significant bit before the first byte.

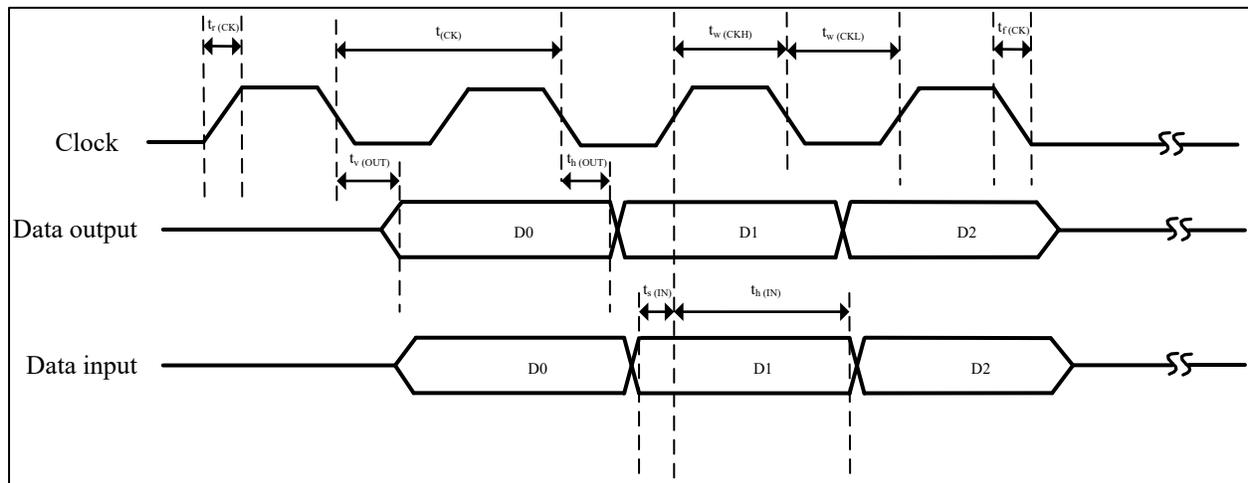
4.3.22 xSPI Interface Characteristics

 Table 4-51 xSPI Characteristics in SDR Mode⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F _{CK}	QSPI clock frequency	2.3 V < V _{DD} < 3.6 V, C _{LOAD} = 20 pF	-	-	133	MHz
t _{w(CKH)}	QSPI clock high/low time, even division	PRESCALER[7:0] = n n = 0,1,3,5	t _{(CK)/2}	-	t _{(CK)/2+1}	ns
t _{w(CKL)}			t _{(CK)/2-1}	-	t _{(CK)/2}	
t _{w(CKL)}			(n/2+1)*t _{(CK)/(n+1)-1}	-	(n/2+1)*t _{(CK)/(n+1)}	
t _{s(IN)}	Input data setup time	-	3	-	-	ns
t _{h(IN)}	Input data hold time	-	1.5	-	-	
t _{v(OUT)}	Output data valid time	-	-	-	0.5	
t _{h(OUT)}	Output data hold time	-	0	-	-	

- All values apply to both eight-line and four-line SPI modes.
- Guaranteed by design, not tested in production.

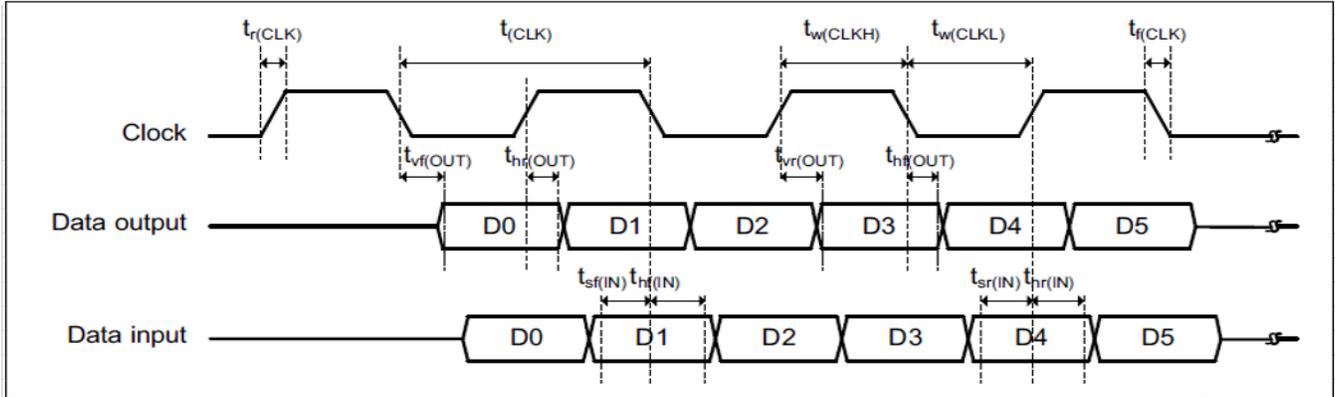
Figure 4-22 xSPI Read/Write Timing in SDR Mode


 Table 4-52 xSPI Characteristics in DTR Mode (non-DQS)⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F _{CK} 1/t _(CK)	xSPI clock frequency	2.3 V < V _{DD} < 3.6 V, C _{LOAD} = 20 pF	-	-	66.5	MHz
t _{w(CKH)}	QSPI clock high/low time, even division	PRESCALER[7:0] = n n = 0,1,3,5...	t _{(CK)/2}	-	t _{(CK)/2+1}	ns
t _{w(CKL)}			t _{(CK)/2-1}	-	t _{(CK)/2}	
t _{sr(IN)} t _{sf(IN)}	Input data setup time	-	-	-	3	ns
t _{hr(IN)} t _{hf(IN)}	Input data hold time	-	1.5	-	-	
t _{vr(OUT)}		TXDE[7:0] = 0	-	-	1.56	

$t_{v(OUT)}$	Output data valid time	TXDE[7:0] = n n= 1,2,3...	-	-	$n*t_{(CK)}/4+1.56$
$t_{hr(OUT)}$ $t_{hf(OUT)}$	Output data valid time	TXDE[7:0] =0 TXDE[7:0] = n n= 1,2,3...	0 $n*t_{(CK)}/4$	- -	- -

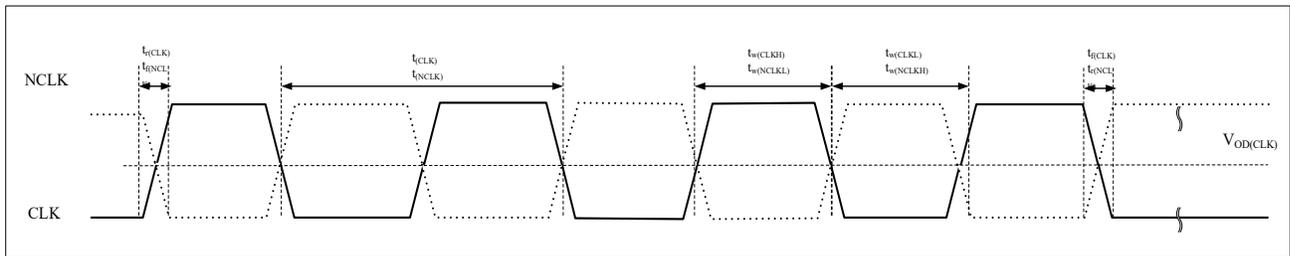
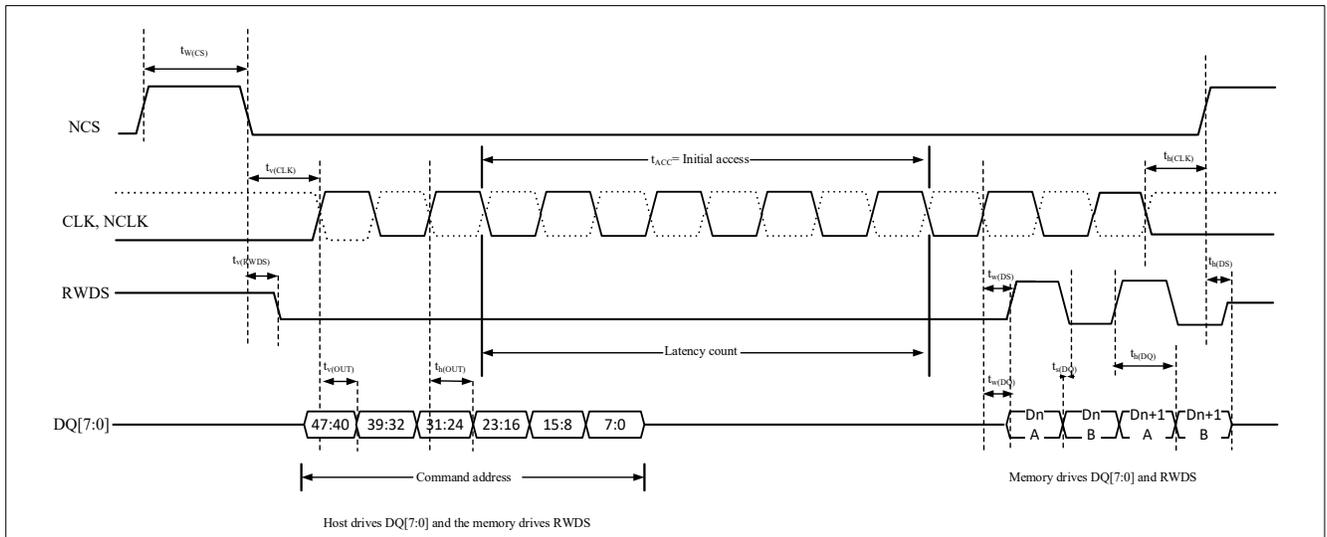
1. All values apply to both eight-line and four-line SPI modes.
2. Guaranteed by design, not tested in production.

Figure 4-23 xSPI Timing in DTR Mode

Table 4-53 xSPI Characteristics in DTR Mode (with DQS)/Eight-line and Hyperbus Protocol ⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$F_{CK}^{(2)(3)}$	xSPI clock frequency	$2.7\text{ V} < V_{DD} < 3.6\text{ V}$, $C_{LOAD} = 20\text{ pF}$	-	-	133	MHz
$t_{w(CKH)}$	QSPI clock high/low time, even division	PRESCALER[7:0] = n = 0,1,3,5...	$t_{(CK)}/2$	-	$t_{(CK)}/2+1$	ns
$t_{w(CKL)}$			$t_{(CK)}/2-1$	-	$t_{(CK)}/2$	
$t_v(CK)$	Clock valid time	-	-	-	$t_{(CK)}+1$	
$t_h(CK)$	Clock hold time	-	$t_{(CK)}/2$	-	-	
$V_{ODr(CK)}$	CK rising edge, CK and \overline{ck} crossing level	$V_{DD} = 2.3\text{ V}$	922	-	1229	mV
$V_{ODf(CK)}$	CK falling edge, CK and \overline{ck} crossing level	$V_{DD} = 2.3\text{ V}$	1000	-	1277	
$t_w(CS)$	Chip select high level time	-	$3 * t_{(CK)}$	-	-	ns
$t_v(DQ)$	Input data valid data	-	0	-	-	
$t_v(DS)$	Input data strobe valid data	-	0	-	-	
$t_h(DS)$	Input data strobe hold time	-	0	-	-	
$t_v(RWDQ)$	Output data strobe valid data	-	-	-	$3 * t_{(CK)}$	
$t_{sr(DQ)}$	Input data setup time	Rising edge	0	-	-	
$t_{sf(DQ)}$		Falling edge	0	-	-	

$t_{hr}(DQ)$	Input data hold time	Rising edge	1.5	-	-
$t_{hf}(DQ)$		Falling edge	1.5	-	-
$t_{vr}(OUT)$ $t_{vf}(OUT)$	Output data Rising edge/valid data	TXDE[7:0] = 0	-	-	1.56
		TXDE[7:0] = n n = 1,2,3...	-	-	$n * t_{(CK)}/4 + 1.56$
$t_{hr}(OUT)$ $t_{hf}(OUT)$	Output data Rising edge/hold time	TXDE[7:0] = 0	0	-	-
		TXDE[7:0] = n n = 1,2,3...	$n * t_{(CK)}/4$	-	-

1. Guaranteed by design, not tested in production.
2. The maximum deviation for the maximum frequency values given from RWDS to DQ is +/-1.0ns
3. To achieve this frequency, the corresponding register must be activated.

Figure 4-24 xSPI Hyperbus Clock Timing Diagram

Figure 4-25 xSPI Hyperbus Clock Read Timing Diagram


4.3.23 FEMC Characteristics

■ Asynchronous Waveforms and Timing

Figure 4-27 to Figure 4-30 show the asynchronous waveforms, and Table 4-54 to Table 4-57 provide the corresponding timing parameters.

Figure 4-27 Asynchronous Non-Multiplexed Bus SRAM/PSRAM/NOR Read Operation Waveform

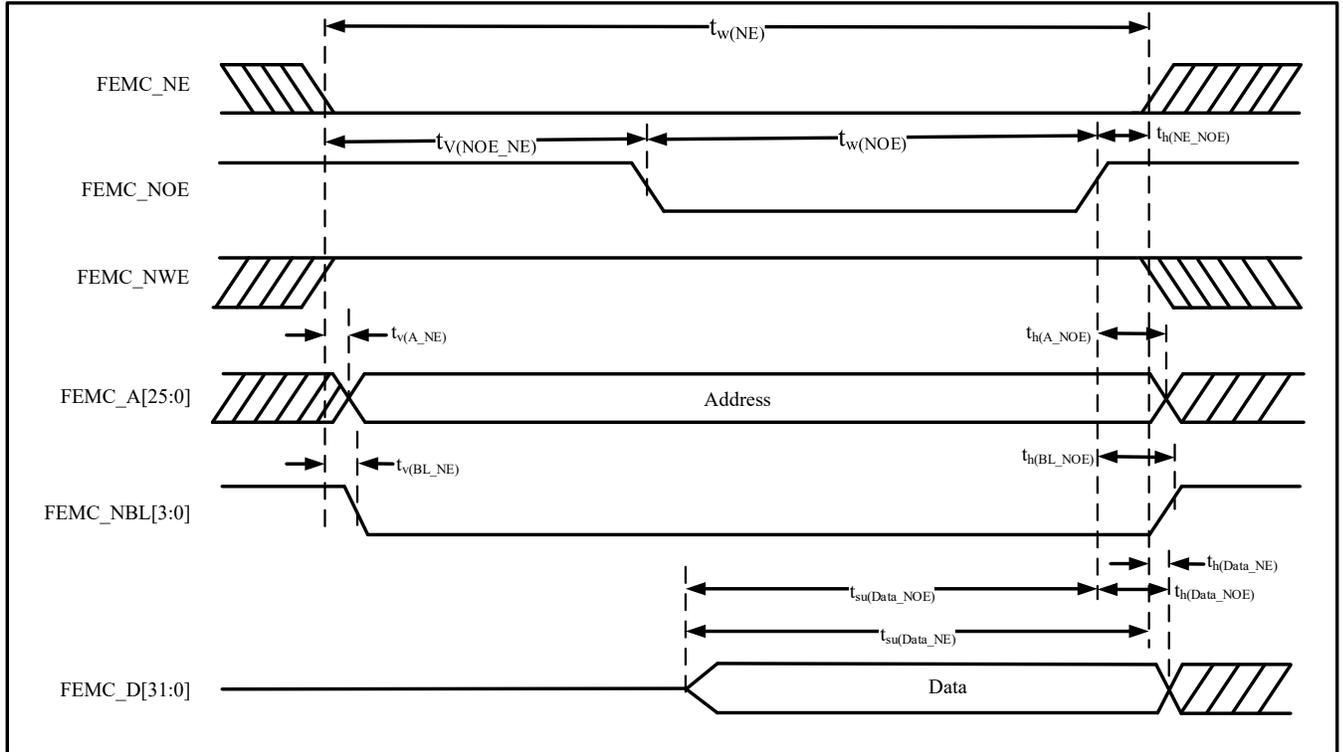


Table 4-54 Asynchronous Non-Multiplexed Bus SRAM/PSRAM/NOR Read Operation Timing ⁽¹⁾⁽²⁾

Symbol	Parameter	Min ⁽³⁾	Max ⁽³⁾	Unit
$t_{w(NE)}$	FEMC_NE low time	$2T_{FEMC_CLK} - 1$	$15T_{FEMC_CLK} + 1$	ns
$t_{v(NOE_NE)}$	FEMC_Nex low to FEMC_NOE low	$T_{FEMC_CLK} - 0.5$	$7T_{FEMC_CLK} + 0.5$	ns
$t_{w(NOE)}$	FEMC_NOE low time	$T_{FEMC_CLK} - 1$	$8T_{FEMC_CLK} + 1$	ns
$t_{h(NE_NOE)}$	FEMC_NOE high to FEMC_NE high hold time	0	-	ns
$t_{v(A_NE)}$	FEMC_Nex low to FEMC_A valid	-	0.5	ns
$t_{h(A_NOE)}$	Address hold time after FEMC_NOE high	0	-	ns
$t_{v(BL_NE)}$	FEMC_Nex low to FEMC_NBL valid	-	0.5	ns
$t_{h(BL_NOE)}$	FEMC_NBL hold time after FEMC_NOE high	$T_{FEMC_CLK} - 1$	-	ns
$t_{su(Data_NE)}$	Data setup time to FEMC_Nex high	-	$0.5T_{FEMC_CLK} + 1$	ns
$t_{su(Data_NOE)}$	Data setup time to FEMC_NOE high	-	$0.5T_{FEMC_CLK} + 1$	ns
$t_{h(Data_NOE)}$	Data hold time after FEMC_NOE high	$0.5T_{FEMC_CLK} - 1$	-	ns
$t_{h(Data_NE)}$	Data hold time after FEMC_Nex high	$0.5T_{FEMC_CLK} - 1$	-	ns

- IO drive strength = 8 mA, capacitive load = 30 pF
- Measurement point set at CMOS level: 0.5 V_{DD}

3. $T_{FEMC_CLK} \geq 1/100\text{MHz}$

Figure 4-28 Asynchronous Non-Multiplexed Bus SRAM/PSRAM/NOR Write Operation Waveform

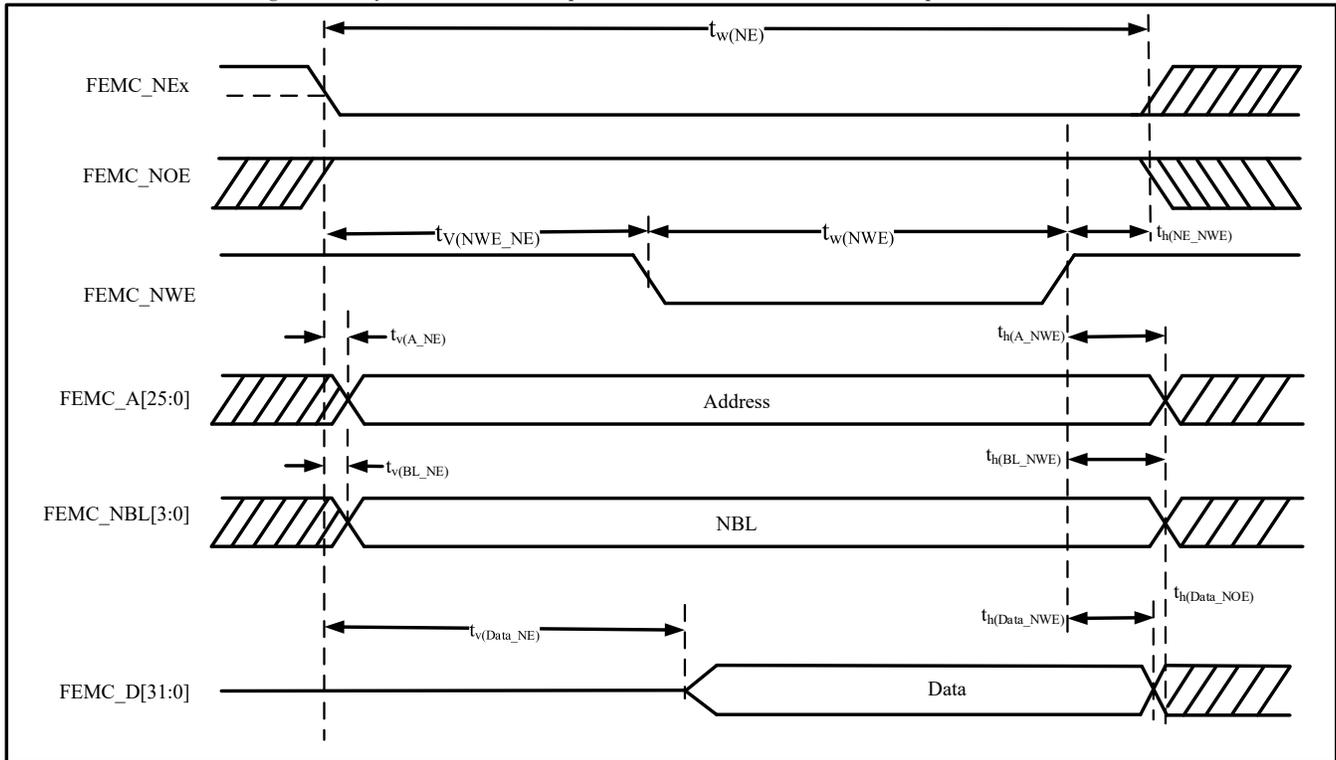
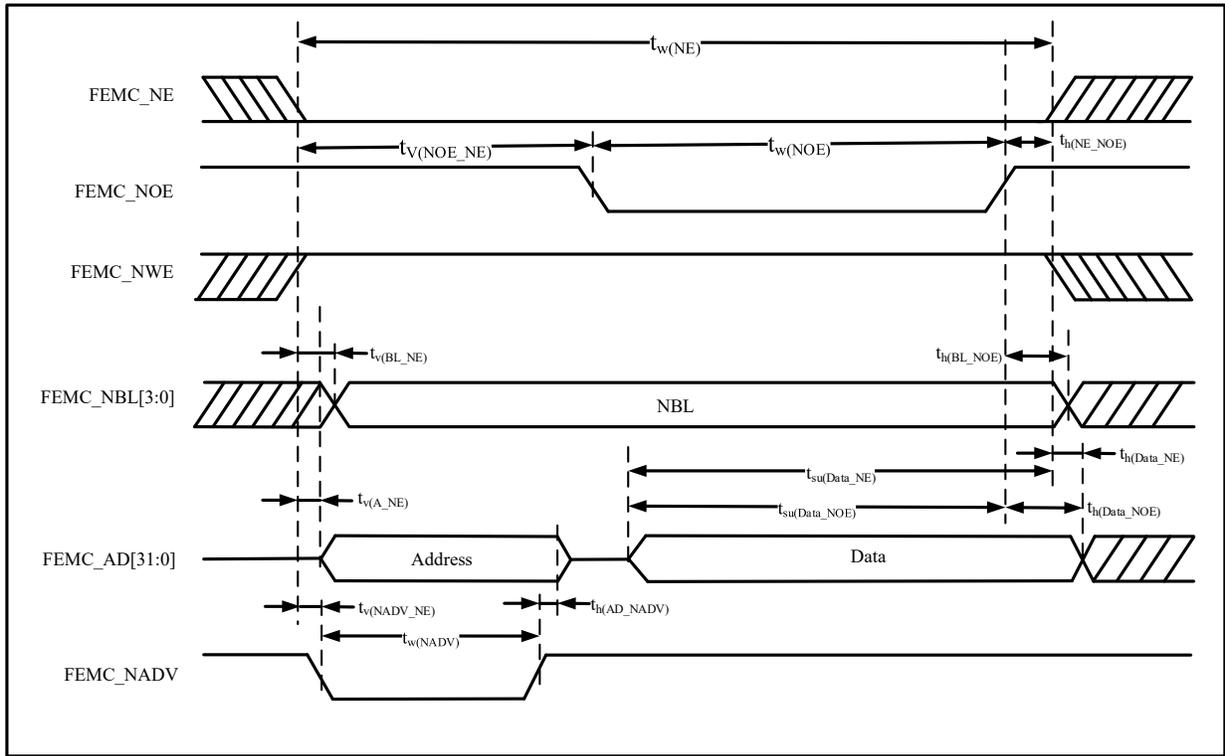


Table 4-55 Asynchronous Non-Multiplexed Bus SRAM/PSRAM/NOR Write Operation Timing ⁽¹⁾⁽²⁾

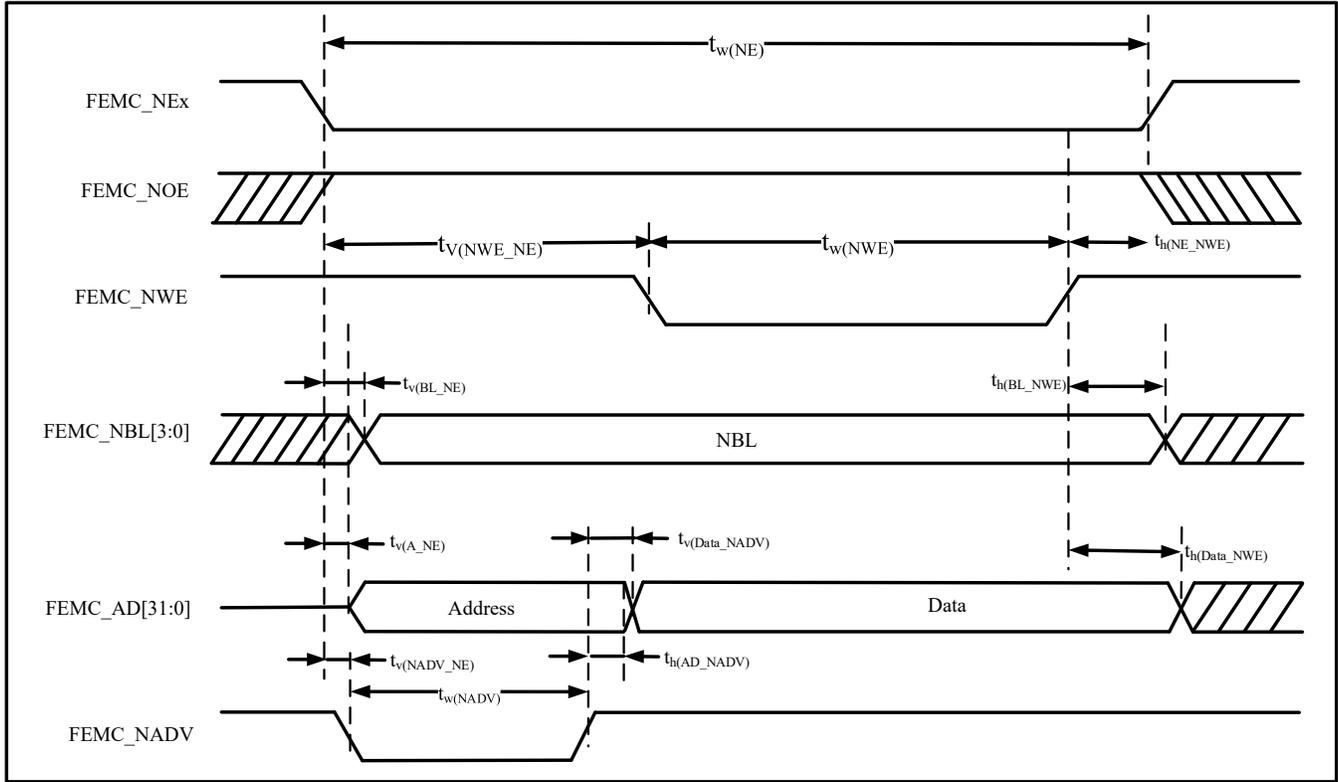
Symbol	Parameter	Min ⁽³⁾	Max ⁽³⁾	Unit
$t_{w(NE)}$	FEMC_NE low time	$2T_{FEMC_CLK} - 1$	$15T_{FEMC_CLK} + 1$	ns
$t_{v(NWE_NE)}$	FEMC_NEx low to FEMC_NWE low	0	$T_{FEMC_CLK} + 1$	ns
$t_{w(NWE)}$	FEMC_NWE low time	$T_{FEMC_CLK} - 0.5$	$7T_{FEMC_CLK} + 0.5$	ns
$t_{h(NE_NWE)}$	Hold time from FEMC_NWE high to FEMC_NE high	$T_{FEMC_CLK} - 0.1$	-	ns
$t_{v(A_NE)}$	FEMC_NEx low to FEMC_A valid	-	0.5	ns
$t_{h(A_NWE)}$	Address hold time after FEMC_NWE high	$T_{FEMC_CLK} - 0.1$	-	ns
$t_{v(BL_NE)}$	FEMC_NEx low to FEMC_NBL valid	-	0.5	ns
$t_{h(BL_NWE)}$	FEMC_NBL hold time after FEMC_NWE high	$T_{FEMC_CLK} - 0.1$	-	ns
$t_{v(Data_NE)}$	FEMC_NEx low to data valid	-	$T_{FEMC_CLK} + 1$	ns
$t_{h(Data_NWE)}$	Data hold time after FEMC_NWE high	$T_{FEMC_CLK} - 0.1$	-	ns

- IO drive strength = 8 mA, capacitive load = 30 pF
- Measurement point set at CMOS level: 0.5 VDD
- $T_{FEMC_CLK} \geq 1/100\text{MHz}$

Figure 4-29 Asynchronous Bus Multiplexed PSRAM/NOR Read Operation Waveform

Table 4-56 Asynchronous Bus Multiplexed PSRAM/NOR Read Timing ⁽¹⁾⁽²⁾

符号	参数	最小值 ⁽³⁾	最大值 ⁽³⁾	单位
$t_{w(NE)}$	FEMC_NE low time	$2T_{FEMC_CLK} - 1$	$15T_{FEMC_CLK} + 1$	ns
$t_{v(NOE_NE)}$	FEMC_NEx low to FEMC_NOE low	$T_{FEMC_CLK} - 0.5$	$7T_{FEMC_CLK} + 0.5$	ns
$t_{w(NOE)}$	FEMC_NOE low time	$T_{FEMC_CLK} - 1$	$8T_{FEMC_CLK} + 1$	ns
$t_{h(NE_NOE)}$	FEMC_NOE high to FEMC_NE high hold time	0	-	ns
$t_{v(A_NE)}$	FEMC_NEx low to FEMC_A valid	-	0.5	ns
$t_{v(NADV_NE)}$	FEMC_NEx low to FEMC_NADV low	0	0.2	ns
$t_{w(NADV)}$	FEMC_NADV low time	-	$T_{FEMC_CLK} + 1$	ns
$t_{h(AD_NADV)}$	FEMC_A valid hold time after FEMC_NADV high	$0.5T_{FEMC_CLK} - 1$	-	ns
$t_{h(A_NOE)}$	FEMC_A hold time after FEMC_NOE high	0	-	ns
$t_{h(BL_NOE)}$	FEMC_BL hold time after FEMC_NOE high	0	-	ns
$t_{v(BL_NE)}$	FEMC_NEx low to FEMC_BL valid	-	0.5	ns
$t_{su(Data_NE)}$	Data to FEMC_NEx high setup time	-	$0.5T_{FEMC_CLK} + 1$	ns
$t_{su(Data_NOE)}$	Data to FEMC_NOE high hold time	-	$0.5T_{FEMC_CLK} + 1$	ns
$t_{h(Data_NE)}$	Data hold time after FEMC_NEx high	$0.5T_{FEMC_CLK} - 1$	-	ns
$t_{h(Data_NOE)}$	Data hold time after FEMC_NOE high	$0.5T_{FEMC_CLK} - 1$	-	ns

- IO drive capability 8mA, Capacitive load = 30 pF
- Measurement points are set at CMOS level: 0.5VDD
- $T_{FEMC_CLK} \geq 1/100MHz$

Figure 4-30 Asynchronous Bus Multiplexed PSRAM/NOR Write Operation Waveform

Table 4-57 Asynchronous Bus-Multiplexed PSRAM/NOR Read Operation Timing ⁽¹⁾⁽²⁾

Symbol	Parameter	Min ⁽³⁾	Max ⁽³⁾	Unit
$t_{w(NE)}$	FEMC_NE low time	$2T_{FEMC_CLK} - 1$	$15T_{FEMC_CLK} + 1$	ns
$t_{v(NWE_NE)}$	FEMC_NEx low to FEMC_NOE low	0	$T_{FEMC_CLK} + 1$	ns
$t_{w(NWE)}$	FEMC_NOE low time	$T_{FEMC_CLK} - 0.5$	$7T_{FEMC_CLK} + 0.5$	ns
$t_{h(NE_NWE)}$	Hold time from FEMC_NOE high to FEMC_NE high	$T_{FEMC_CLK} - 0.1$	-	ns
$t_{v(A_NE)}$	FEMC_NEx low to FEMC_A valid	-	0.5	ns
$t_{v(NADV_NE)}$	Hold time of FEMC_AD (address) valid after FEMC_NADV high	0	0.2	ns
$t_{w(NADV)}$	Address hold time after FEMC_NOE high	-	$T_{FEMC_CLK} + 1$	ns
$t_{h(AD_NADV)}$	FEMC_NBL hold time after FEMC_NOE high	$T_{FEMC_CLK} - 0.1$	-	ns
$t_{h(A_NWE)}$	FEMC_NEx low to FEMC_NBL valid	$T_{FEMC_CLK} - 0.1$	-	ns
$t_{v(BL_NE)}$	Data setup time to FEMC_NEx high	-	0.5	ns
$t_{h(BL_NWE)}$	Data setup time to FEMC_NOE high	$T_{FEMC_CLK} - 0.1$	-	ns
$t_{v(Data_NADV)}$	Data hold time after FEMC_NEx high	-	$T_{FEMC_CLK} + 0.1$	ns
$t_{h(Data_NWE)}$	Data hold time after FEMC_NOE high	$T_{FEMC_CLK} - 0.1$	-	ns

- IO drive strength = 8 mA, capacitive load = 30 pF
- Measurement point set at CMOS level: 0.5 VDD
- $T_{FEMC_CLK} \geq 1/100\text{MHz}$

Synchronous Waveforms and Timing

Figure 4-31 to Figure 4-34 show the synchronous waveforms, and Table 4-58 to Table 4-61 provide the corresponding timing parameters.

Figure 4-31 Synchronous Non-Bus-Multiplexed NOR/PSRAM Read Timing

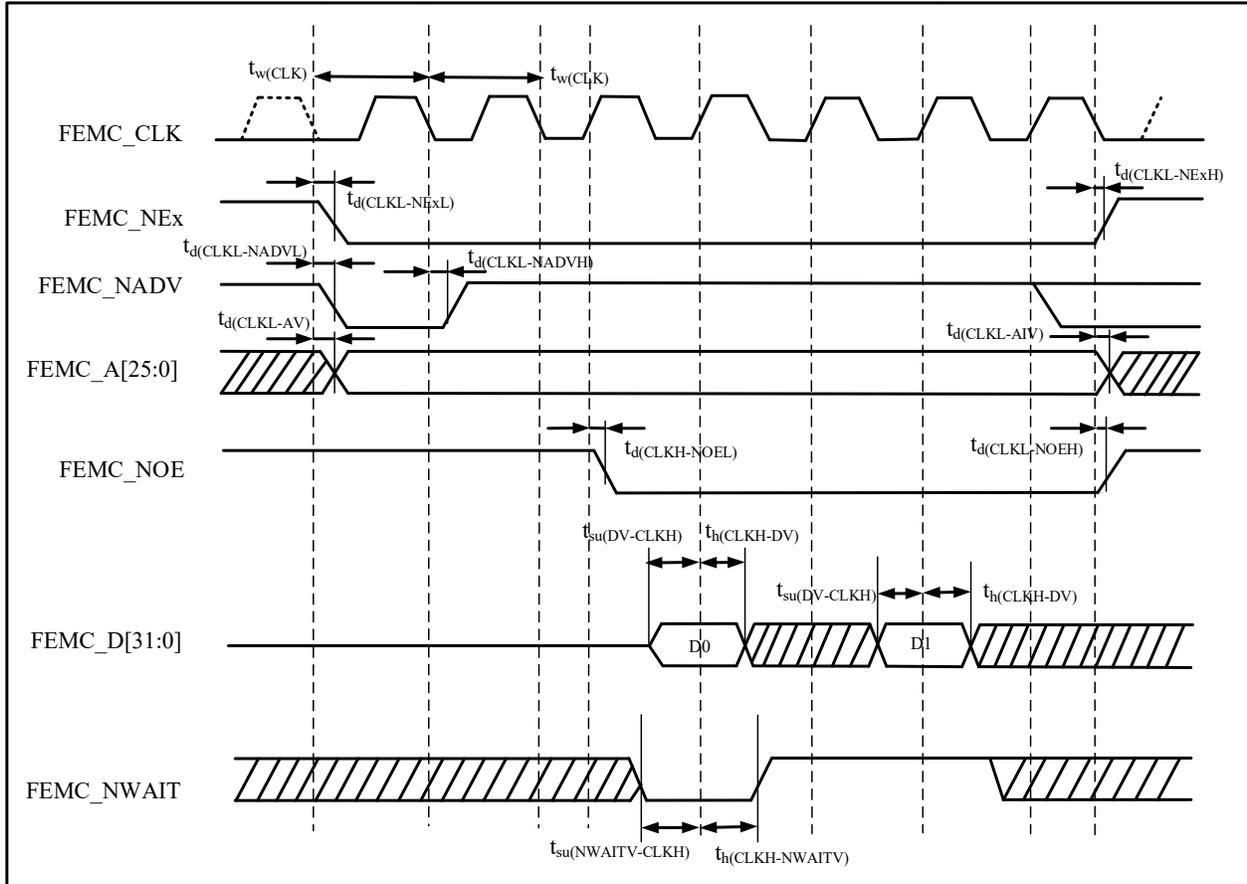
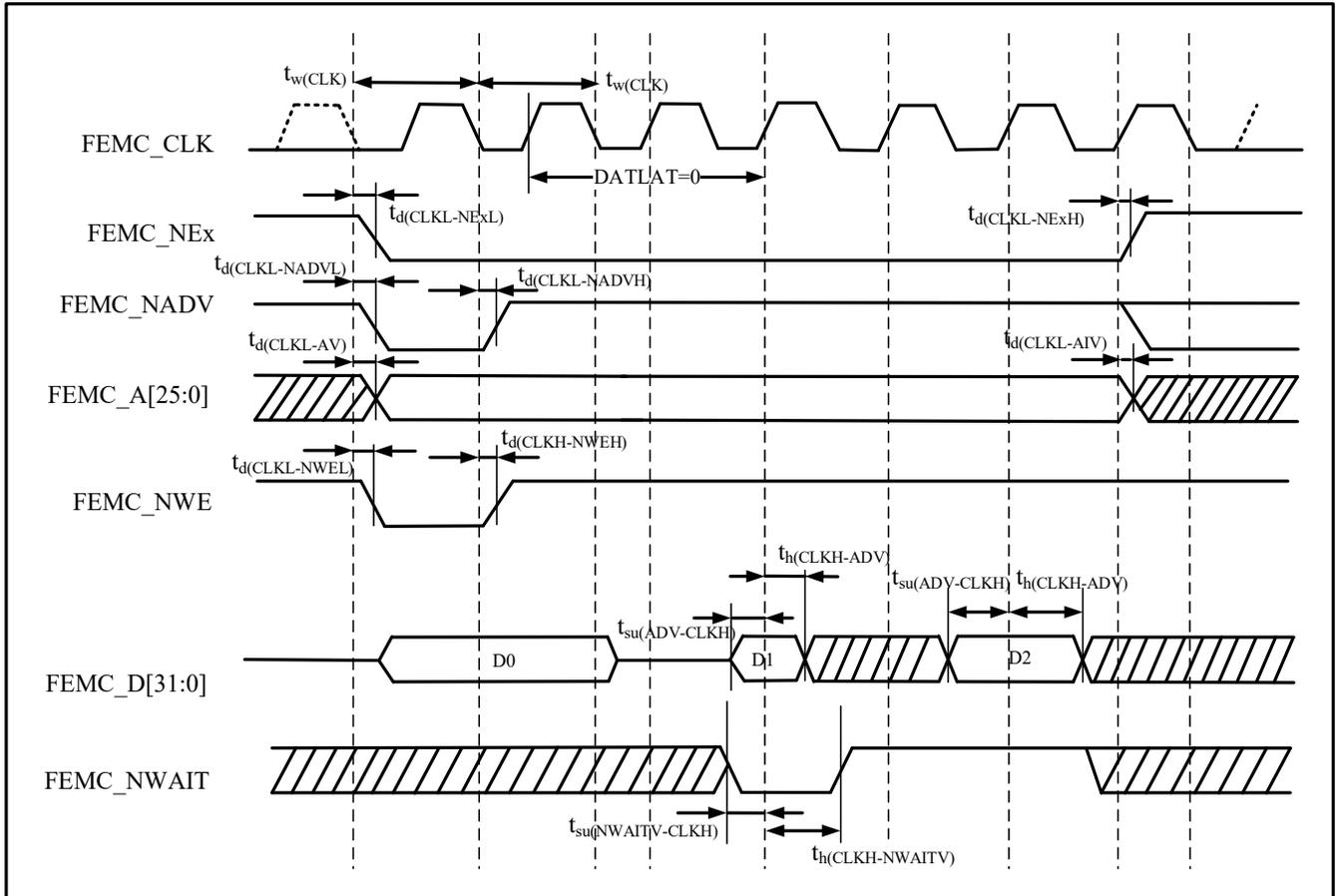


Table 4-58 Synchronous Non-Bus-Multiplexed NOR/PSRAM Read Timing⁽¹⁾⁽²⁾

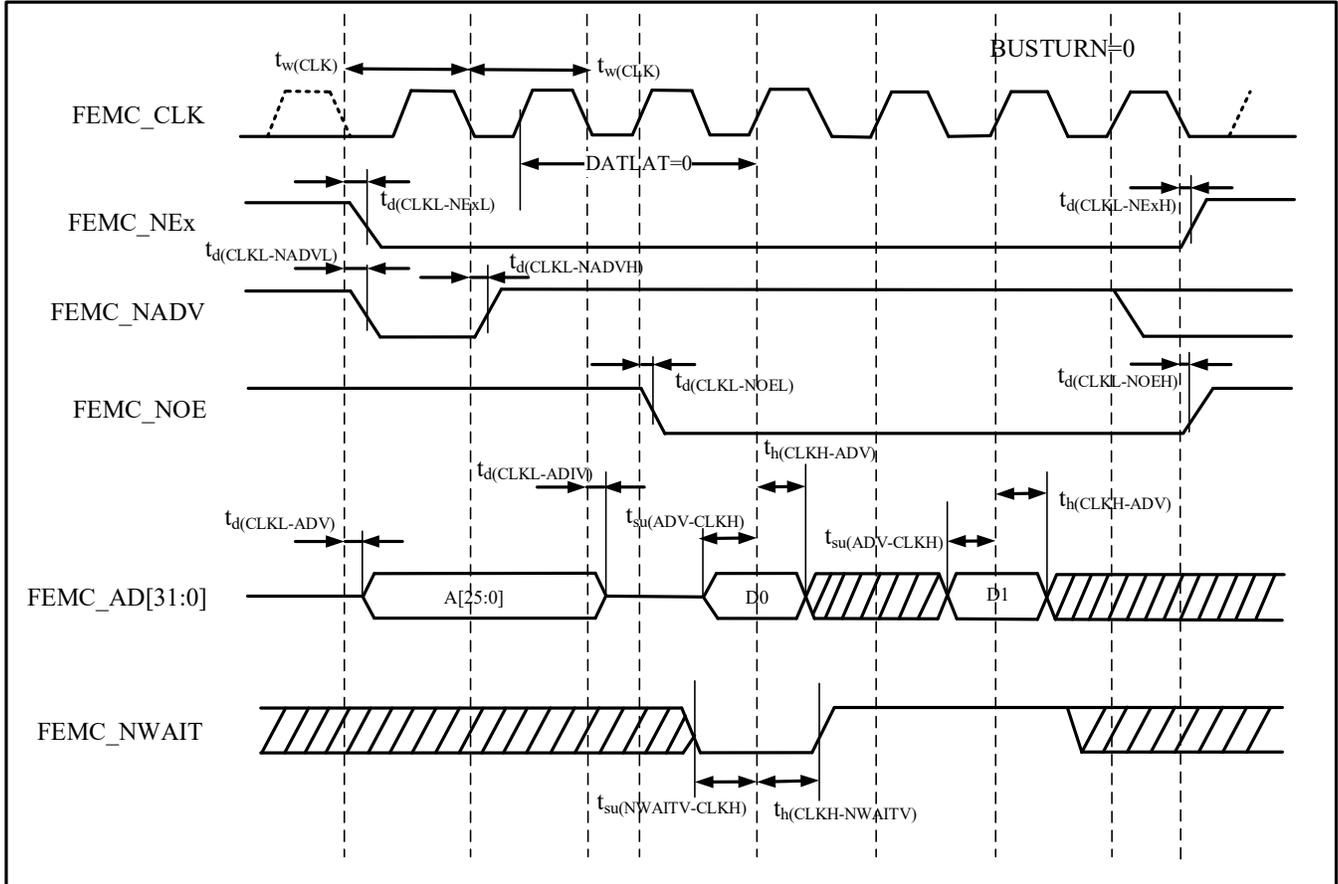
Symbol	Parameter	Min	Max	Unit
$t_{w(\text{CLK})}$	FEMC_CLK period	9.8	-	ns
$t_{d(\text{CLKL-NExL})}$	FEMC_CLK low to FEMC_NEx low ($x = 1 \dots 4$)	-	2.0	ns
$t_{d(\text{CLKL-NExH})}$	FEMC_CLK low to FEMC_NEx high ($x = 1 \dots 4$)	2.0	-	ns
$t_{d(\text{CLKL-NADV})}$	FEMC_CLK low to FEMC_NADV low	-	2.0	ns
$t_{d(\text{CLKL-NADVH})}$	FEMC_CLK low to FEMC_NADV high	2.0	-	ns
$t_{d(\text{CLKL-AV})}$	FEMC_CLK low to FEMC_Ax valid ($x = 0 \dots 25$)	-	3.0	ns
$t_{d(\text{CLKL-AIV})}$	FEMC_CLK low to FEMC_Ax invalid ($x = 0 \dots 25$)	2.0	-	ns
$t_{d(\text{CLKL-NOEL})}$	FEMC_CLK low to FEMC_NOE low	-	2.0	ns
$t_{d(\text{CLKL-NOEH})}$	FEMC_CLK low to FEMC_NOE high	2.0	-	ns
$t_{su(\text{DV-CLKH})}$	Data valid (FEMC_D[31:0]) setup time before FEMC_CLK high	2.6	-	ns
$t_{h(\text{CLKH-DV})}$	Data valid (FEMC_D[31:0]) hold time after FEMC_CLK high	0.3	-	ns
$t_{su(\text{NWAITV-CLKH})}$	FEMC_NWAIT valid setup time before FEMC_CLK high	2.6	-	ns
$t_{h(\text{CLKH-NWAITV})}$	FEMC_NWAIT valid hold time after FEMC_CLK high	0.3	-	ns

- IO drive strength: 8mA, Capacitive load = 30pF
- Measurement point set at CMOS level: 0.5VDD

Figure 4-32 Synchronous Non-Multiplexed PSRAM Write Timing

Table 4-59 Synchronous Non-Multiplexed PSRAM Write Timing ⁽¹⁾⁽²⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{CLK})$	FEMC_CLK period	9.8	-	ns
$t_d(\text{CLKL-NExL})$	FEMC_CLK low to FEMC_NEx low ($x = 1 \dots 4$)	-	2.0	ns
$t_d(\text{CLKL-NExH})$	FEMC_CLK low to FEMC_NEx high ($x = 1 \dots 4$)	2.0	-	ns
$t_d(\text{CLKL-NADVL})$	FEMC_CLK low to FEMC_NADV low	-	2.0	ns
$t_d(\text{CLKL-NADVH})$	FEMC_CLK low to FEMC_NADV high	2.0	-	ns
$t_d(\text{CLKL-AV})$	FEMC_CLK low to FEMC_A _x valid ($x = 0 \dots 25$)	-	3.0	ns
$t_d(\text{CLKH-AIV})$	FEMC_CLK high to FEMC_A _x invalid ($x = 0 \dots 25$)	2.0	-	ns
$t_d(\text{CLKL-NWEL})$	FEMC_CLK low to FEMC_NWE low	-	2.0	ns
$t_d(\text{CLKH-NWEH})$	FEMC_CLK high to FEMC_NWE high	2.0	-	ns
$t_d(\text{CLKL-Data})$	FEMC_CLK low to FEMC_D[31:0] valid data	-	3.0	ns
$t_{su}(\text{NWAITV-CLKH})$	FEMC_NWAIT valid setup time before FEMC_CLK high	2.6	-	ns
$t_h(\text{CLKH-NWAITV})$	FEMC_NWAIT valid hold time after FEMC_CLK high	0.3	-	ns

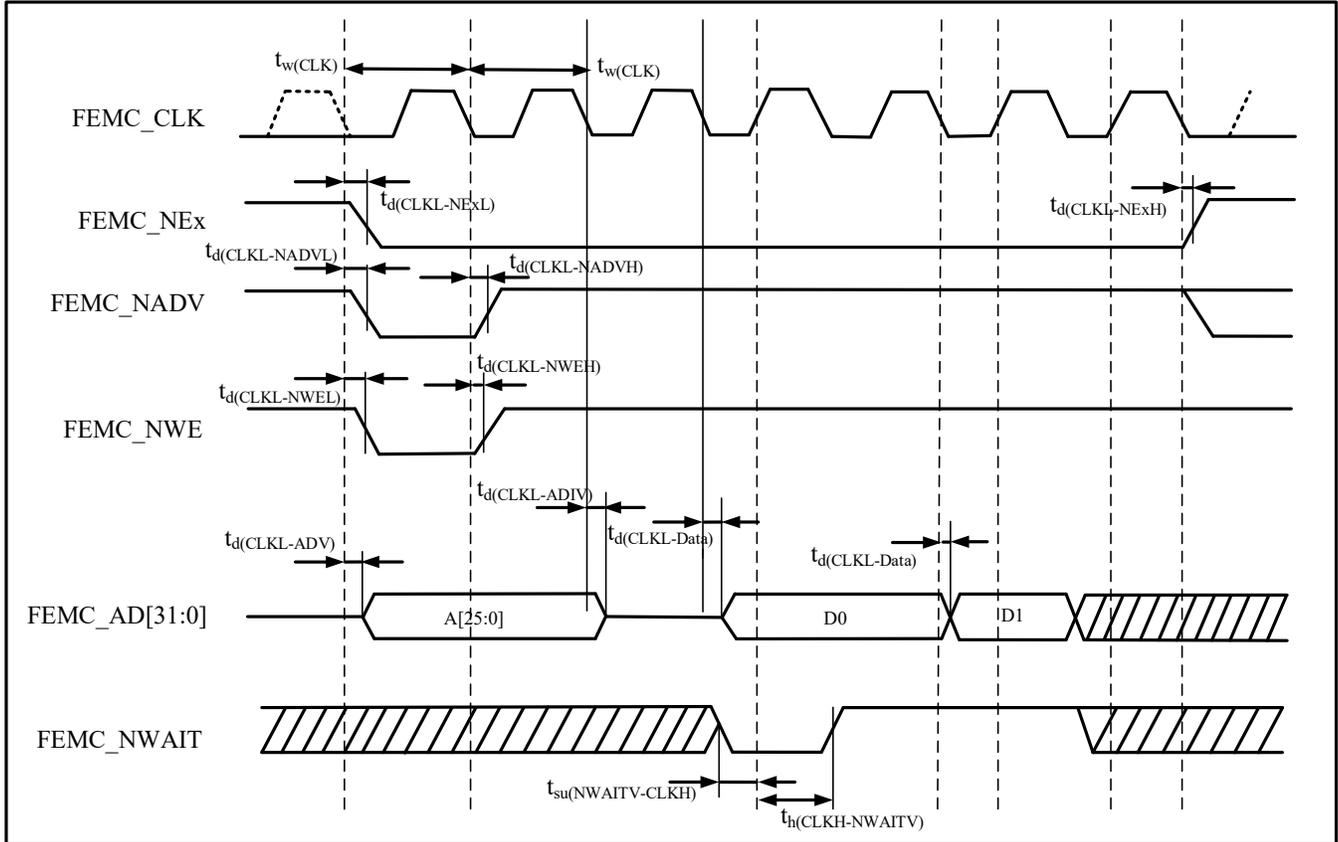
- IO drive strength: 8mA, Capacitive load = 30pF
- Measurement point set at CMOS level: 0.5V_{DD}

Figure 4-33 Synchronous Bus-Multiplexed NOR/PSRAM Read Timing

Table 4-60 Synchronous Bus-Multiplexed NOR/PSRAM Read Timing ⁽¹⁾⁽²⁾

Symbol	Parameter	Min ⁽³⁾	Max	Unit
$t_w(\text{CLK})$	FEMC_CLK period	9.8	-	ns
$t_d(\text{CLKL-NExL})$	FEMC_CLK low to FEMC_NEx low (x = 1...4)	-	2.0	ns
$t_d(\text{CLKL-NExH})$	FEMC_CLK low to FEMC_NEx high (x = 1...4)	2.0	-	ns
$t_d(\text{CLKL-NADVL})$	FEMC_CLK low to FEMC_NADV low	-	2.0	ns
$t_d(\text{CLKL-NADVH})$	FEMC_CLK low to FEMC_NADV high	2.0	-	ns
$t_d(\text{CLKL-NOEL})$	FEMC_CLK low to FEMC_NOE low	-	2.0	ns
$t_d(\text{CLKL-NOEH})$	FEMC_CLK low to FEMC_NOE high	2.0	-	ns
$t_d(\text{CLKL-ADV})$	FEMC_CLK low to FEMC_AD[31:0] valid	-	3.0	ns
$t_d(\text{CLKL-ADIV})$	FEMC_CLK low to FEMC_AD[31:0] invalid	2.0	-	ns
$t_{su}(\text{ADV-CLKH})$	FEMC_AD[31:0] valid data setup time before FEMC_CLK high	2.6	-	ns
$t_h(\text{CLKH-ADV})$	FEMC_AD[31:0] valid data hold time after FEMC_CLK high	0.3	-	ns
$t_{su}(\text{NWAITV-CLKH})$	FEMC_NWAIT valid setup time before FEMC_CLK high	2.6	-	ns
$t_h(\text{CLKH-NWAITV})$	FEMC_NWAIT valid hold time after FEMC_CLK high	0.3	-	ns

- IO drive strength: 8mA, Capacitive load = 30pF

- Measurement point set at CMOS level: 0.5V_{DD}
- T_{FEMC_CLK} >= 1/100MHz

Figure 4-34 Synchronous Bus-Multiplexed PSRAM Write Timing

Table 4-61 Synchronous Multiplexed PSRAM Write Timing ⁽¹⁾⁽²⁾

Symbol	Parameter	Min ⁽³⁾	Max	Unit
t _w (CLK)	FEMC_CLK cycle	9.8	-	ns
t _d (CLKL-NExL)	FEMC_CLK low to FEMC_NEx low (x = 1...4)	-	2.0	ns
t _d (CLKL-NExH)	FEMC_CLK low to FEMC_NEx high (x = 1...4)	2.0	-	ns
t _d (CLKL-NADV)	FEMC_CLK low to FEMC_NADV low	-	2.0	ns
t _d (CLKL-NADVH)	FEMC_CLK low to FEMC_NADV high	2.0	-	ns
t _d (CLKL-NWE)	FEMC_CLK low to FEMC_NWE low	-	2.0	ns
t _d (CLKL-NWEH)	FEMC_CLK low to FEMC_NWE high	2.0	-	ns
t _d (CLKL-ADV)	FEMC_CLK low to FEMC_AD[31:0] valid	-	3.0	ns
t _d (CLKL-ADIV)	FEMC_CLK low to FEMC_AD[31:0] invalid	2.0	-	ns
t _d (CLKL-Data)	FEMC_CLK low then FEMC_AD[31:0] valid	-	3.0	ns
t _{su} (NWAITV-CLKH)	FEMC_CLK high before FEMC_NWAIT valid	2.6	-	ns
t _h (CLKH-NWAITV)	FEMC_CLK high after FEMC_NWAIT valid	0.3	-	ns

- IO drive capability 8mA, Capacitive load = 30 pF
- Measurement points at CMOS level: 0.5V_{DD}
- T_{FEMC_CLK} >= 1/100MHz

- **NAND Controller Waveforms and Timing**

Figure 4-35 to Figure 4-36 show the waveforms for NAND operations.

Figure 4-35 NAND Controller Read Operation Waveform

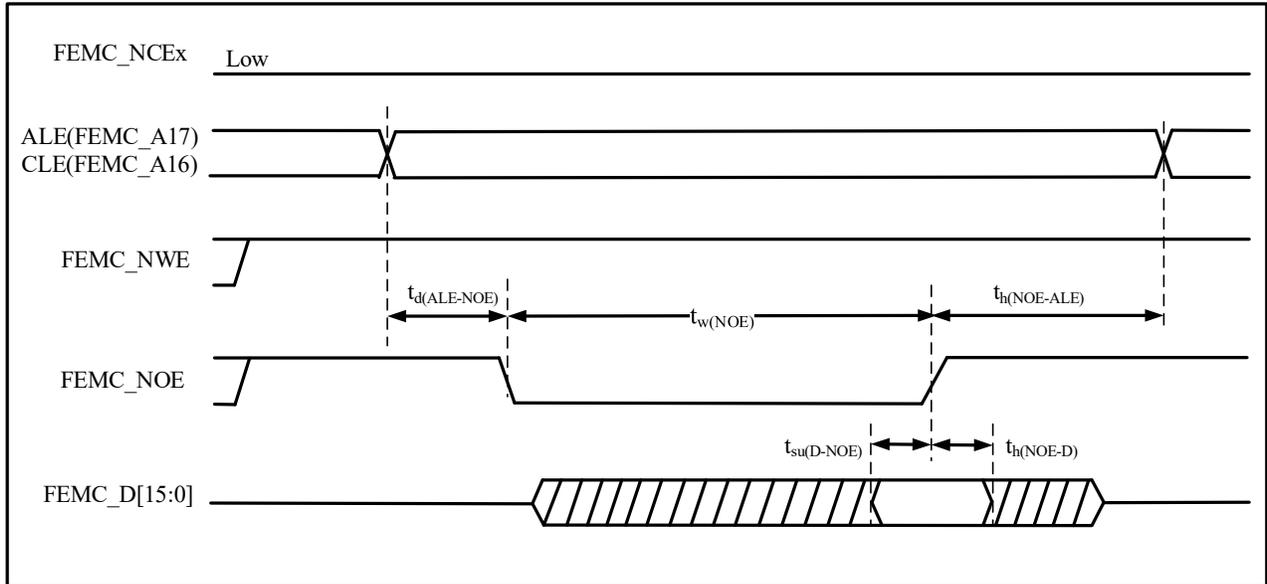


Figure 4-36 NAND Controller Write Operation Waveform

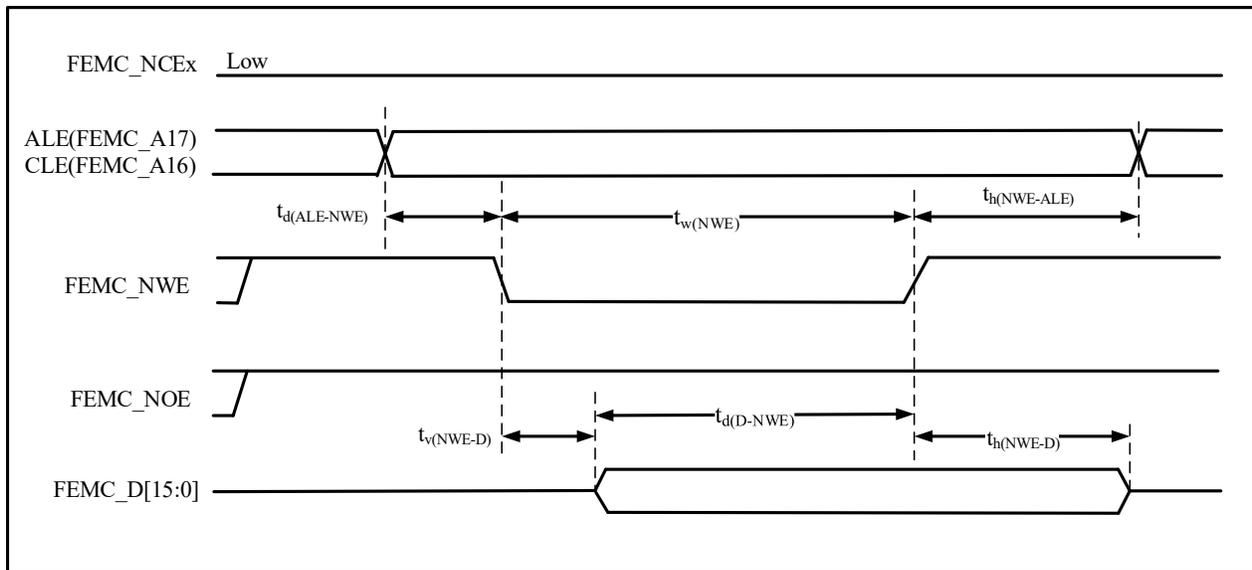


Table 4-62 NAND Flash Read/Write Cycle Timing Characteristics ⁽¹⁾

Symbol	Parameter	Min ⁽²⁾	Max ⁽²⁾	Unit
$t_{d(D-NWE)}$	Data valid before FEMC_NWE goes high	$1T_{FEMC_CLK} - 8$	$7T_{FEMC_CLK} - 3$	ns
$t_w(NOE)$	FEMC_NOE low time	$1T_{FEMC_CLK} - 1$	$8T_{FEMC_CLK} + 1$	ns
$t_{su(D-NOE)}$	Data valid before FEMC_NOE goes high	$1/2T_{FEMC_CLK} - 4.5$	$1T_{FEMC_CLK} - 0.5$	ns
$t_h(NOE-D)$	Data valid after FEMC_NOE goes high	4.5	-	ns

$t_{w(NWE)}$	FEMC_NWE low time	$1T_{FEMC_CLK} - 1$	$7T_{FEMC_CLK} + 1$	ns
$t_{v(NWE-D)}$	Data valid after FEMC_NWE goes low	4	7	ns
$t_{h(NWE-D)}$	Data invalid after FEMC_NWE goes high	$1T_{FEMC_CLK} - 1$	-	ns
$t_{d(ALE-NWE)}$	ALE valid before FEMC_NWE goes low	-	0	ns
$t_{h(NWE-ALE)}$	ALE invalid after FEMC_NWE goes high	$1T_{FEMC_CLK} - 1$	-	ns
$t_{d(ALE-NOE)}$	ALE valid before FEMC_NOE goes low	$1T_{FEMC_CLK} - 1$	$7T_{FEMC_CLK} - 1$	ns
$t_{h(NOE-ALE)}$	ALE invalid after FEMC_NOE goes high	$1T_{FEMC_CLK} - 1$	-	ns

1. Guaranteed by design, not tested in production.

2. $T_{FEMC_CLK} \geq 1/100\text{MHz}$

4.3.24 USB_HS_DualRole Characteristics

Table 4-63 USBHS DC Electrical Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
$V_{DD}^{(1)}$	USB Operating Voltage	-	3	-	3.6	V	
LS/FS FUNCTIONALITY							
Input Voltage ⁽¹⁾	V_{DIFS}	Differential Input Sensitivity (FS/LS)	-	0.2	-	V	
	V_{CMFS}	Differential Common-Mode Range (FS/LS)	包括 V_{DI} 范围	0.8	-		2.5
	V_{ILSE}	Single-Ended Receive Low Voltage (FS/LS)	-	-	-		0.8
	V_{IHSE}	Single-Ended Receive High Voltage (FS/LS)	-	2.0	-		-
Output Voltage ⁽¹⁾	V_{OLFS}	Static Output Low Level (FS/LS)	R_L of 1.5k Ω to 3.6V	-	-	0.3	
	V_{OHFS}	Static Output High Level (FS/LS)	R_L of 15 k Ω to V_{SS}	2.8	3.3	3.6	
$R_{PD}^{(1)}$	USBHS_DM/DP	$V_{IN} = V_{DD}$	-	15	-	k Ω	
$R_{PU}^{(1)}$	USBHS_DM/DP	$V_{IN} = V_{SS}$	-	1.5	-		
$Z_{HSDRV}^{(1)}$	Drive Output Impedance	Steady state drive	-	45	-	Ω	
HS FUNCTIONALITY							
Input Voltage ⁽¹⁾	D_{IHS}	Differential Input Sensitivity (HS)	-	0.1	-	V	
	V_{CMHS}	Differential Common-Mode Range (HS)	-	-50	-	500	
	V_{HSSQ}	HS Squelch Detection Threshold	-	100	-	150	
	V_{HSDSC}	HS Disconnect Threshold	-	525	-	625	
Output Voltage ⁽¹⁾	V_{OLHS}	High-Speed Low-Level Output Voltage	45 Ω load	-10	-	10	
	V_{OHHS}	High-Speed High-Level Output Voltage	45 Ω load	360	400	440	

1. Guaranteed by design, not tested in production.

Table 4-64 USBHS Dynamic Characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
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T_{FR}	Rise Time (FS/LS)	CL = 50 pF	4	-	20	ns
T_{HSR}	Differential Rise Time (HS)	-	500	-	-	ps
T_{FF}	Fall Time (FS/LS)	CL = 50 pF	4	-	20	ns
T_{HSF}	Differential Fall Time (HS)	-	500	-	-	ps
V_{CRS}	Output Single Crossing Voltage (FS/LS)	-	1.3	-	2	V

1. Guaranteed by design, not tested in production.

4.3.25 Controller Area Network (CAN) Electrical Characteristics

For detailed characteristics of the input/output multiplexed pins (CAN_TX and CAN_RX), refer to section 4.3.14.

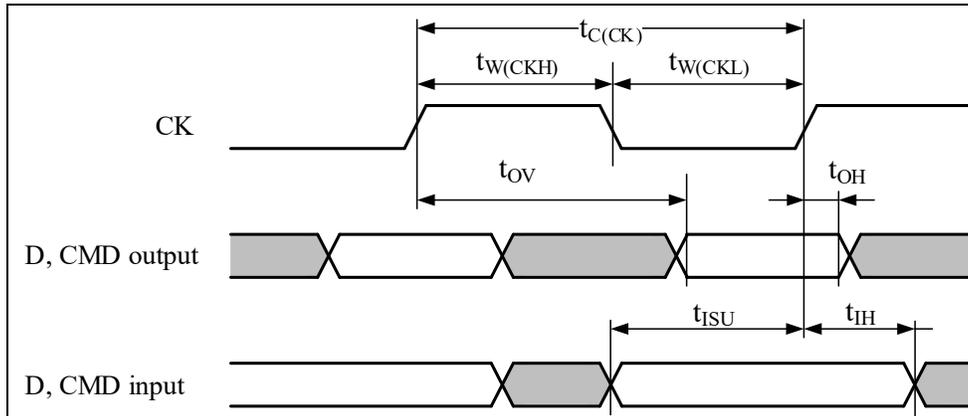
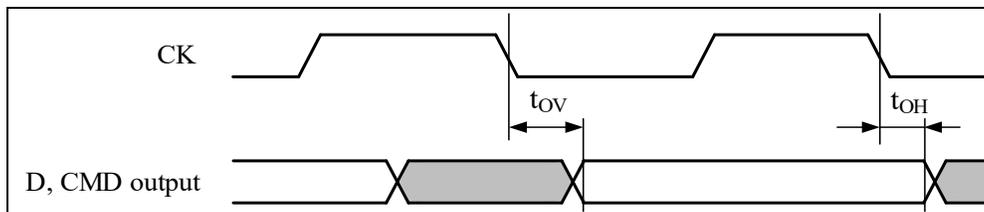
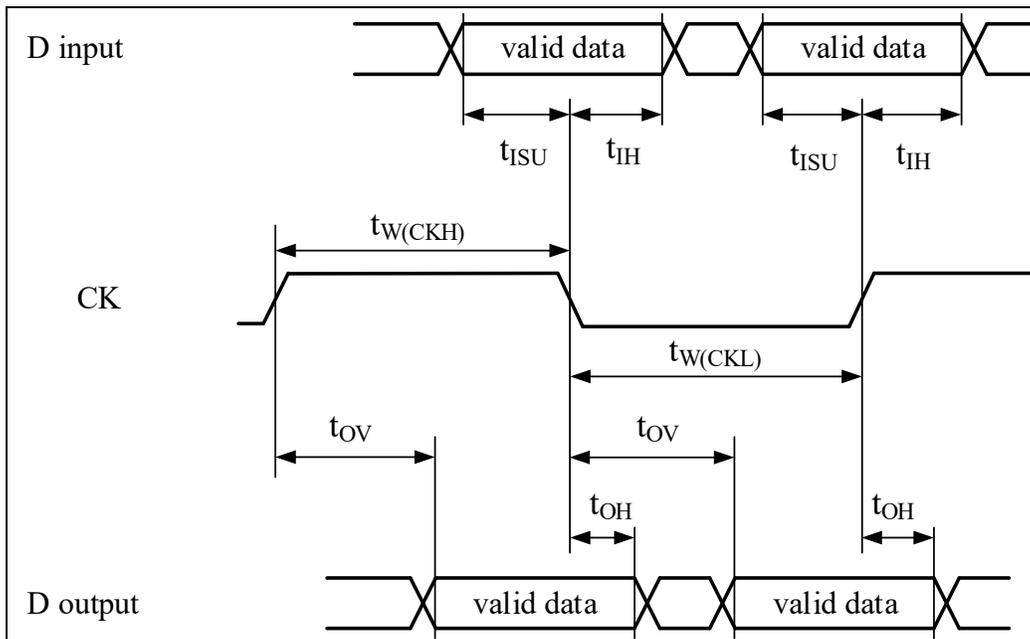
4.3.26 Secure Digital Multimedia Card (SDMMC) Characteristics

Unless otherwise specified, the parameters in Table 4-65 are measured under the environmental temperature, f_{HCLK} frequency, and V_{DDA} supply voltage conditions defined in Table 4-4.

Table 4-65 SD/MMC Characteristics, VDD = 2.7V to 3.6V⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{pp}	Clock frequency in data transfer mode	-	-	-	104	MHz
$t_{w(CKL)}$	Clock low time	$f_{pp}=50\text{MHz}$	8.6	9.6	-	ns
$t_{w(CKH)}$	Clock high time		8.6	9.6	-	ns
CMD, D input in MMC Legacy/SDR/DDR and SD HS/SDR/DDR modes (referenced to CK)						
t_{ISU}	Input setup time HS	$f_{pp} \geq 50 \text{ MHz}$	2.87	-	-	ns
t_{IH}	Input hold time HS		1.3	-	-	ns
$t_{IDW}^{(3)}$	Input valid window (variable window)		TBD	-	-	ns
CMD, D output in MMC Legacy/SDR/DDR and SD HS/SDR/DDR modes (referenced to CK)						
t_{OV}	Output valid data HS	$f_{pp} \geq 50 \text{ MHz}$	-	-	2.74	ns
t_{OH}	Output hold time HS		3.0	-	-	ns
CMD, D input in SD default mode (referenced to CK)						
t_{ISUD}	Input setup time SD	$f_{pp}=25\text{MHz}$	2.87	-	-	ns
t_{IHD}	Input hold time SD		1.3	-	-	ns
CMD, D output in SD default mode (reference CK)						
t_{OVD}	Output valid default time SD	$f_{pp}=25\text{MHz}$	-	-	2.74	ns
t_{OHD}	Output hold default time SD		3.0	-	-	ns

- Guaranteed by design, not tested in production.
- CL = 20 pF.
- In tuning mode, minimum time window where data must remain stable for correct sampling.

Figure 4-37 SD High-Speed Mode

Figure 4-38 SDMMC DDR Mode

Figure 4-39 SDMMC DDR Mode


4.3.27 Ethernet Interface Characteristics

Unless otherwise specified, parameters in Table 4-66, Table 4-67, Table 4-68, Table 4-69 are measured under the environmental temperature (25°C), f_{HCLK} frequency, and V_{DD} supply voltage defined in Table 4-4.

Table 4-66 lists the Ethernet MAC timing of MDIO/SMA, and Figure 4-40 shows the corresponding timing diagram.

Table 4-66 MDIO/SMA Timing

Symbol	Parameter	Min	Typ	Max	Unit
t_{MDC}	MDC period time (2.5 MHz)	-	2.5	-	MHz
$t_{d(MDIO)}$	Valid write data delay	-	-	5	ns
$t_{su(MDIO)}$	Read data setup time	17	-	-	ns
$t_{h(MDIO)}$	Read data hold time	0	-	-	ns

Figure 4-40 MDIO/SMA Timing Diagram

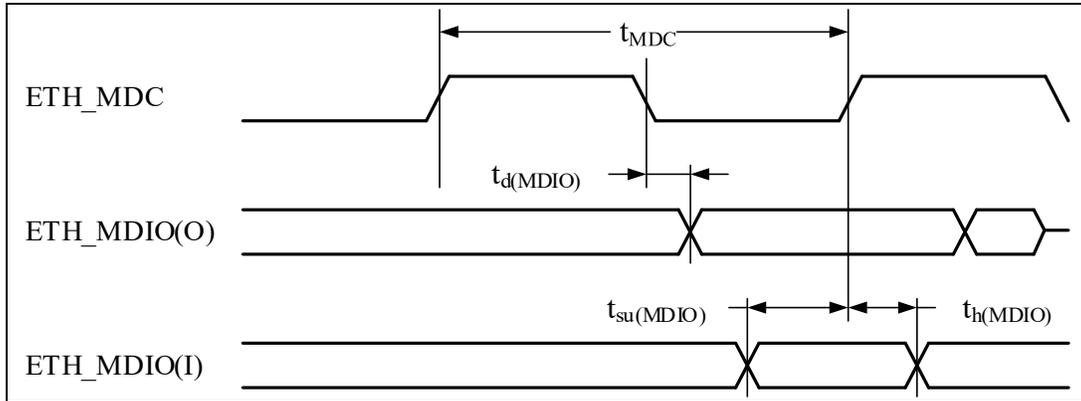


Table 4-67 lists the RMII Ethernet MAC timing parameters, and Figure 4-41 shows the corresponding timing diagram.

Table 4-67 RMII Timing

Symbol	Parameter	Min	Typ	Max	Unit
$t_{su(RXD)}$	Receive data setup time	2	-	-	ns
$t_{ih(RXD)}$	Receive data hold time	1.6	-	-	ns
$t_{su(CRS_DV)}$	Carrier sense/data valid setup time	2	-	-	ns
$t_{ih(CRS_DV)}$	Carrier sense/data valid hold time	1.6	-	-	ns
$t_{d(TXEN)}$	Transmit enable valid delay time	-	-	9.3	ns
$t_{d(TXD)}$	Transmit data valid delay time	-	-	9.3	ns

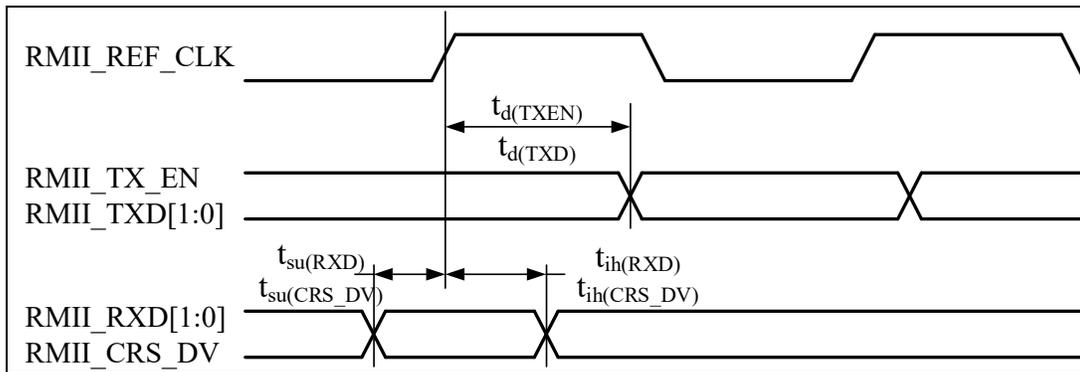
Figure 4-41 RMII Timing Diagram


Table 4-68 lists the Ethernet MAC timing of MII and Figure 4-42 shows the corresponding timing diagram.

Table 4-68 MII Timing

Symbol	Parameter	Min	Typ	Max	Unit
$t_{su(RXD)}$	Receive data setup time	2.5	-	-	ns
$t_{ih(RXD)}$	Receive data hold time	0.5	-	-	ns
$t_{su(DV)}$	Data valid setup time	2.5	-	-	ns
$t_{ih(DV)}$	Data valid hold time	0.5	-	-	ns
$t_{su(ER)}$	Error setup time	2.5	-	-	ns
$t_{ih(ER)}$	Error hold time	0.5	-	-	ns
$t_{d(TXEN)}$	Transmit enable valid delay time	-	-	12.0	ns
$t_{d(TXD)}$	Transmit data valid delay time	-	-	12.0	ns

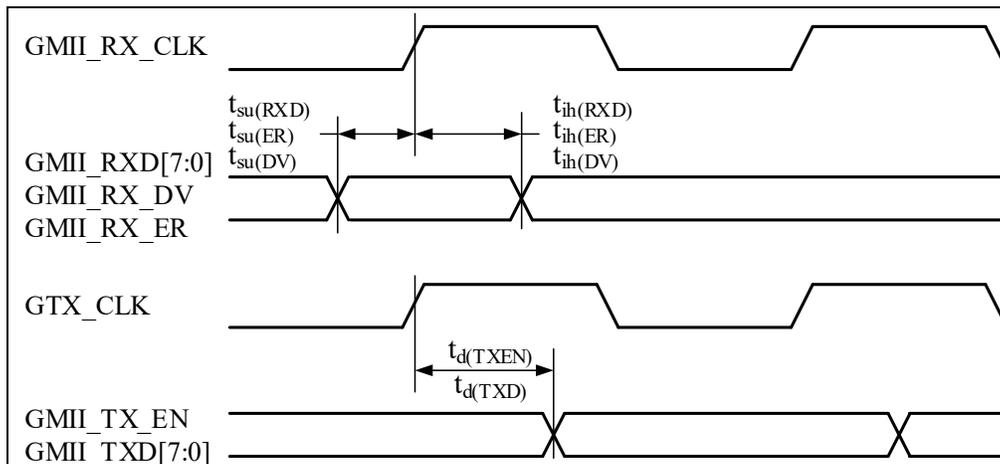
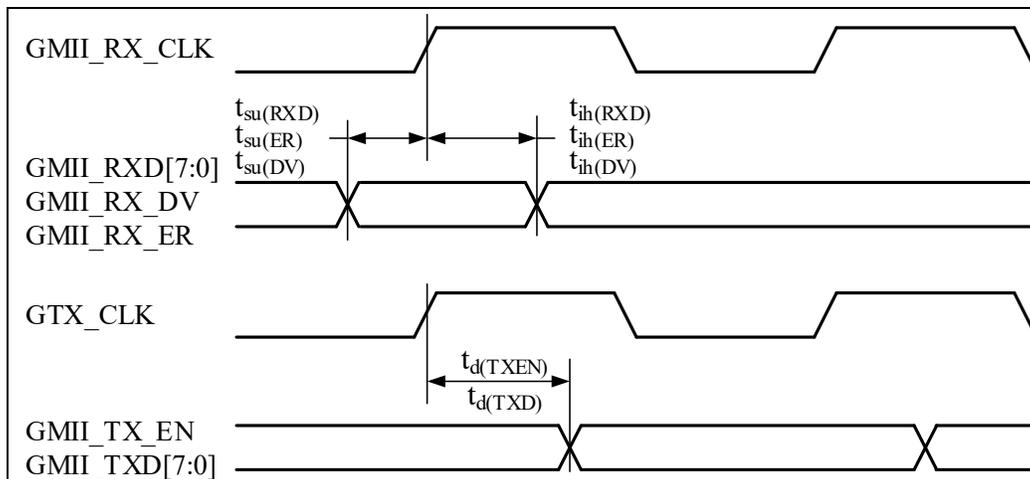
Figure 4-42 MII Timing Diagram


Table 4-69 lists the Ethernet MAC timing of GMII and Figure 4-43 shows the corresponding timing diagram.

Table 4-69 GMII Timing

Symbol	Parameter	Min	Typ	Max	Unit
$t_{su}(RXD)$	Receive data setup time	2.5	-	-	ns
$t_{ih}(RXD)$	Receive data hold time	0.5	-	-	ns
$t_{su}(DV)$	Data valid setup time	2.5	-	-	ns
$t_{ih}(DV)$	Data valid hold time	0.5	-	-	ns
$t_{su}(ER)$	Error setup time	2.5	-	-	ns
$t_{ih}(ER)$	Error hold time	0.5	-	-	ns
$t_d(TXEN)$	Transmit enable valid delay time	-	-	3.0	ns
$t_d(TXD)$	Transmit data valid delay time	-	-	3.0	ns

Figure 4-43 GMII Timing Diagram



4.3.28 Digital Video Port (DVP) Interface

Table 4-70 shows the characteristics of the DVP interface signals, and Figure 4-44 illustrates the related timing.

Figure 4-44 DVP Interface Timing Diagram

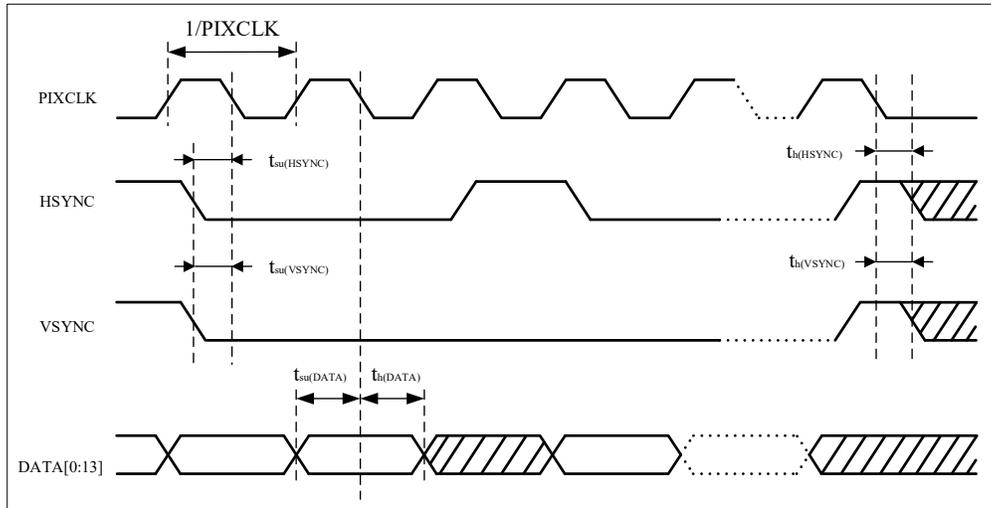


Table 4-70 DVP Signal Dynamic Characteristics

Symbol	Parameter	Conditions	Min	Max	Unit
PCLK	Pixel clock input	-	-	110	MHz
Dpixel	Pixel clock input duty cycle	-	30	70	%
$t_{su}(DATA)$	Data input setup time	-	3	-	ns
$t_h(DATA)$	Data input hold time	-	1	-	
$t_{su}(HSYNC),$ $t_{su}(VSYNC)$	HSYNC/VSYNC input setup time	-	3	-	
$t_h(HSYNC),$ $t_h(VSYNC)$	HSYNC/VSYNC input hold time	-	1	-	

4.3.29 LCD Display Controller (LCDC) Interface

Unless otherwise specified, the parameters in Table 4-71 are measured under the ambient temperature (25 °C), f_{CLK} frequency, and V_{DDA} supply voltage that meet the conditions specified in Table 4-4. For general operating conditions, the configuration is as follows:

LCD_CLK Polarity: High

LCD_DE Polarity: Low

LCD_VSYNC and LCD_HSYNC Polarity: High

Pixel Format: 24 bits

Output Speed:

Load Capacitance: $C_L = 30 \text{ pF}$

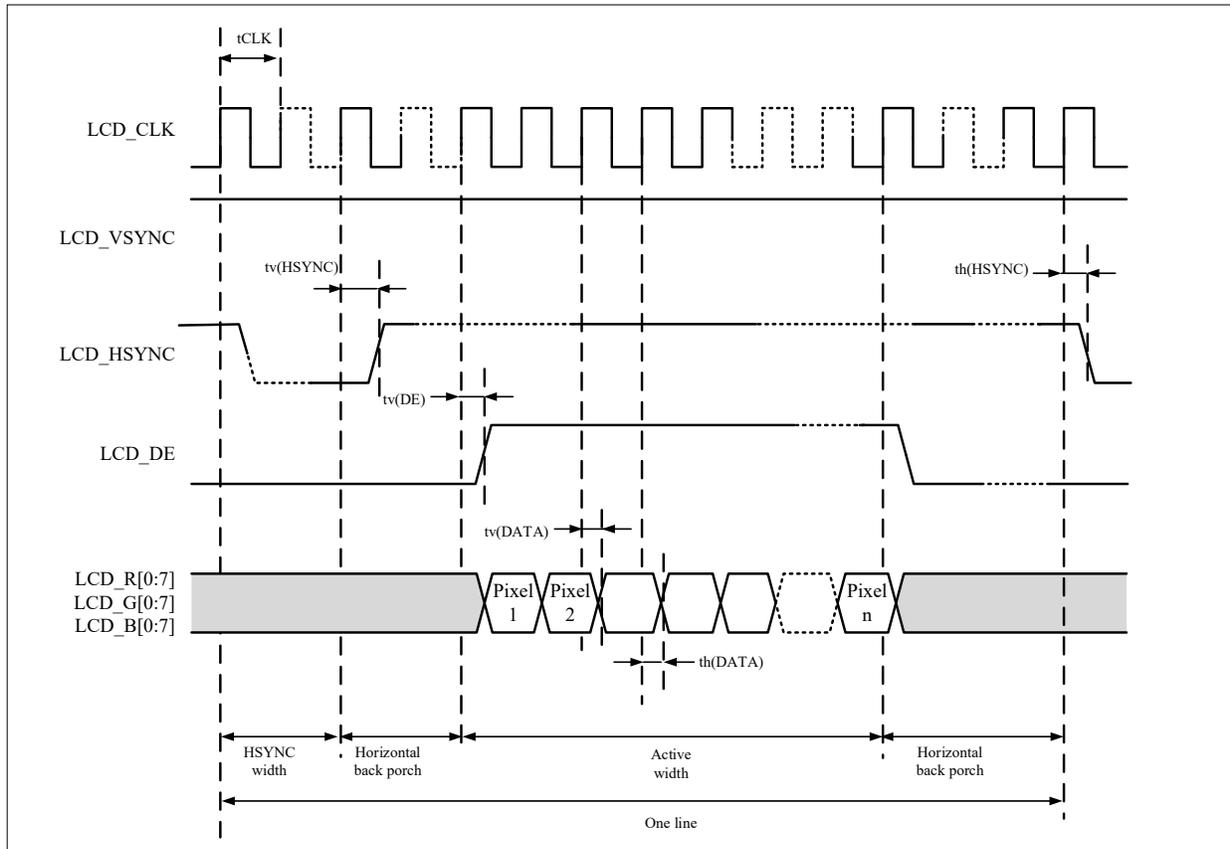
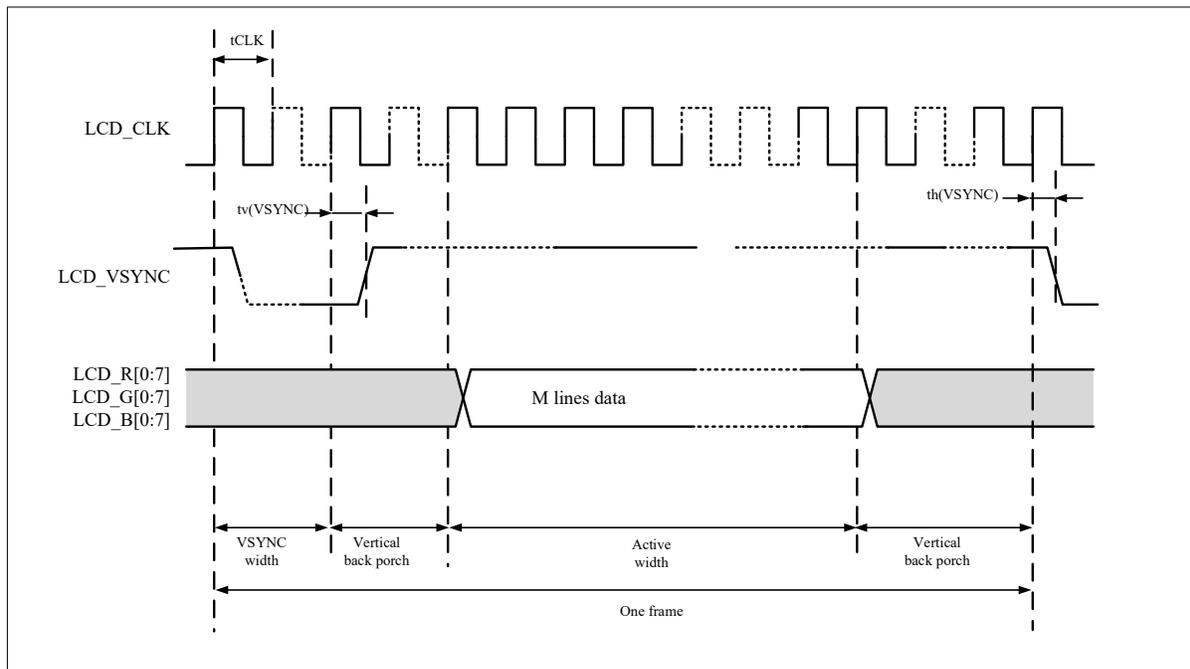
Measurement Point under CMOS: $0.5V_{\text{DD}}$

IO Compensation Unit Enabled

Table 4-71 LCDC Characteristics

Symbol	Parameter		Min	Max	Unit
f_{CLK}	LCDC Clock Output Frequency	$2.3 < V_{\text{DD}} < 3.6V$ 20pF	-	100	MHz
DCLK	LCDC Clock Output Duty Cycle		45	55	%
$t_{\text{W}}(\text{CLKH})$ $t_{\text{W}}(\text{CLKL})$	Clock High-Level Time Clock Low-Level Time		$t_{\text{W}}(\text{CLK})//2-0.5$	$t_{\text{W}}(\text{CLK})//2+0.5$	ns
$t_{\text{V}}(\text{DATA})$	Data Output Valid Time	$2.3 < V_{\text{DD}} < 3.6V$, $f_{\text{CLK}} = 100M$	-	8.01	
$t_{\text{H}}(\text{DATA})$	Data Output Hold Time		1.2	-	
$t_{\text{V}}(\text{HSYNC})$ $t_{\text{V}}(\text{VSYNC})$ $t_{\text{V}}(\text{DE})$	HSYNC/VSYNC/DE Output Valid Time	$2.3 < V_{\text{DD}} < 3.6V$, $f_{\text{CLK}} = 100M$	-	7.7	ns

1. Guaranteed by design, not tested in production.

Figure 4-45 LCD-TFT horizontal timing diagram

Figure 4-46 LCD-TFT vertical timing diagram


4.3.30 MIPI D-PHY Interface Characteristics

Unless otherwise specified, the parameters in Table 4-72 and Table 4-73 are measured under the ambient temperature (25 °C), f_{HCLK} frequency and V_{DD} supply voltage that comply with the conditions specified in Table 4-4.

Table 4-72 MIPI D-PHY characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Hi-Speed Input/Output Characteristics						
U_{INST}	UI instantaneous	-	2	-	12.5	ns
V_{CMTX}	HS transmit common mode voltage	-	150	200	250	mV
$ \Delta V_{CMTX} $	VCMTX mismatch when output is Differential-1 or Differential-0	-	-	-	5	
$ V_{OD} $	HS transmit differential voltage	-	140	200	270	
$ \Delta V_{OD} $	VOD mismatch when output is Differential-1 or Differential-0	-	-	-	14	
V_{OHHS}	HS output high voltage	-	-	-	360	
Z_{OS}	Single ended output impedance	-	40	50	60	Ω
ΔZ_{OS}	Single ended output impedance mismatch	-	-	-	20	%
t_{HSr} & t_{HSf}	20%~80% rise and fall time	-	-	-	0.3	UI
LP Receiver Input Characteristics						
V_{IL}	Logic 0 input voltage (not in ULP State)		TBD	-	250	mV
V_{IH}	Input high level voltage	-	740	-	-	
V_{hys}	Voltage hysteresis	-	25	-	-	
LP Emitter Output Characteristics						
V_{OL}	Output low level voltage	-	-50	-	50	mV
V_{OH}	Output low level voltage	-	0.95	1.2	1.3	V
Z_{OLP}	Output impedance of LP transmitter	-	-	-	-	Ω

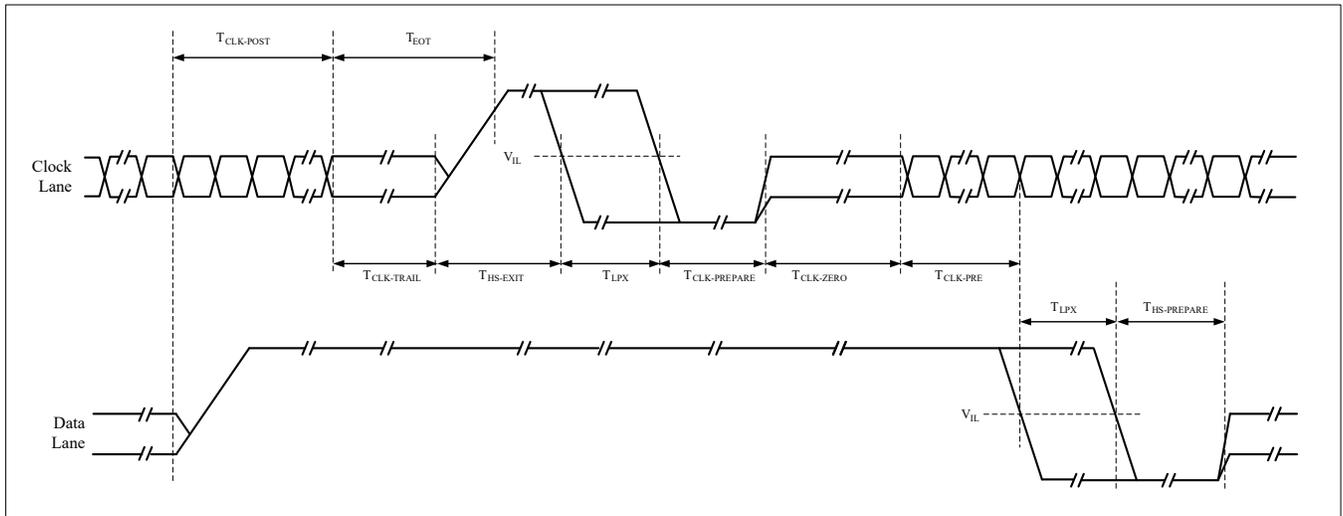
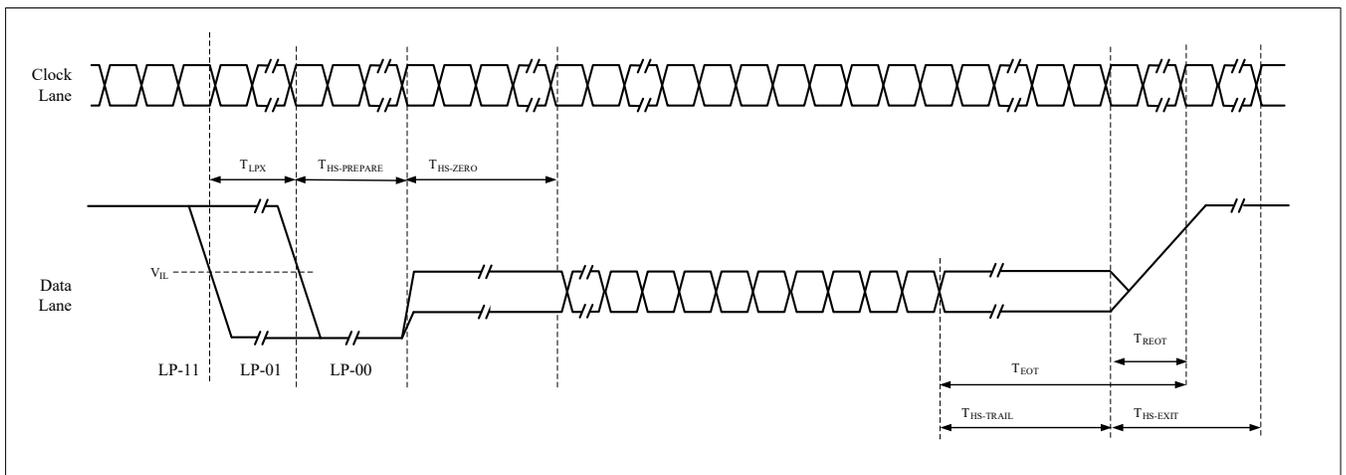
1. Guaranteed by design, not tested in production.

Table 4-73 MIPI D-PHY AC characteristics LP mode and HS/LP transitions⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
T_{LPIX}	Transmitted length of any Low-Power state period	-	50	-	-	ns
$T_{CLK-PREPARE}$	Time that the transmitter drives the Clock Lane LP-00 Line state immediately before the HS-0 Line state starting the HS transmission	-	38	-	95	
$T_{CLK-PREPARE} + T_{CLK-ZERO}$	Time that the transmitter drives the HS-0 state prior to starting the clock.	-	300	-	-	
$T_{CLK-PRE}$	Time that the HS clock shall be driven by the transmitter prior to any associated Data Lane beginning the transition from LP to HS mode.	-	8	-	-	UI
$T_{CLK-POST}$	Time that the transmitter continues to send HS clock after the last associated Data Lane has transitioned to LP Mode.	-	$60ns + 52*UI$	-	-	ns
$T_{CLK-TRAIL}$	Time that the transmitter drives the HS-0 state after the last payload clock bit of an HS transmission burst.	-	60	-	-	
$T_{HS-PREPARE}$	Time that the transmitter drives the Data Lane LP-00 Line state immediately before the HS-0 Line state starting the HS transmission.	-	$40ns + 10*UI$	-	$85ns + 6*UI$	
$T_{HS-PREPARE} + T_{HS-ZERO}$	THS-PREPARE+ Time that the transmitter drives the HS-0 state prior to transmitting the Sync sequence.	-	$145ns + 10*UI$	-	-	
$T_{HS-TRAIL}$	Time that the transmitter drives the flipped differential state after last payload data bit of a HS transmission burst.	-	Max ($n*8*UI$, $60ns + n*4*UI$)	-	-	

$T_{HS-EXIT}$	Time that the transmitter drives LP-11 following a HS burst.	-	100	-	-
T_{REOT}	0%~85% rise time and fall time	-	-	-	35
T_{EOT}	Transmitted time interval from the start of THS-TRAIL or TCLK-TRAIL, to the start of the LP-11 state following a HS burst.	-	-	$105ns + n*12*UI$	-

1. Guaranteed by design, not tested in production.
2. If $a > b$, the maximum value is a; otherwise, it is b.
3. For the forward-direction HS mode, $n = 1$; for the reverse-direction HS mode, $n = 4$.

Figure 4-47 MIPI D-PHY HS/LP Clock Lane Transmission Timing Diagram

Figure 4-48 MIPI D-PHY HS/LP Data Lane Transmission Timing Diagram


4.3.31 MIPI D-PHY regulator characteristics

Unless otherwise specified, the parameters in Table 4-74 are measured under the ambient temperature (25°C), f_{HCLK} frequency and V_{DD} supply voltage that comply with the conditions specified in Table 4-4.

Table 4-74 DSI regulator characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDDSI}	Regulator output voltage on V_{DDDSI}	-	2.97	3.3	3.36	V
I_{LOAD}	Static load current	-	-	-	-	mA
t_{WAKEUP}	Startup delay	Counting starts after the module reset is released.	-	250	-	μ s

1. Guaranteed by design, not tested in production.

4.3.32 Digital Filter Unit Based on Σ - Δ Modulator (DSMU) Characteristics

Unless otherwise specified, the Parameters in Table 4-75 are measured under the environmental conditions (ambient temperature 25 °C, f_{HCLK} frequency, and V_{DD} supply voltage) conforming to Table 4-4. Additional test conditions are as follows:

- Port switching speed configuration: $DSy[1:0] = 2b10$, $SRy = 1b0$
- Load capacitance $C_L = 30$ pF
- Reference CMOS level standards, I/O measurement point at 0.5 V_{DD}

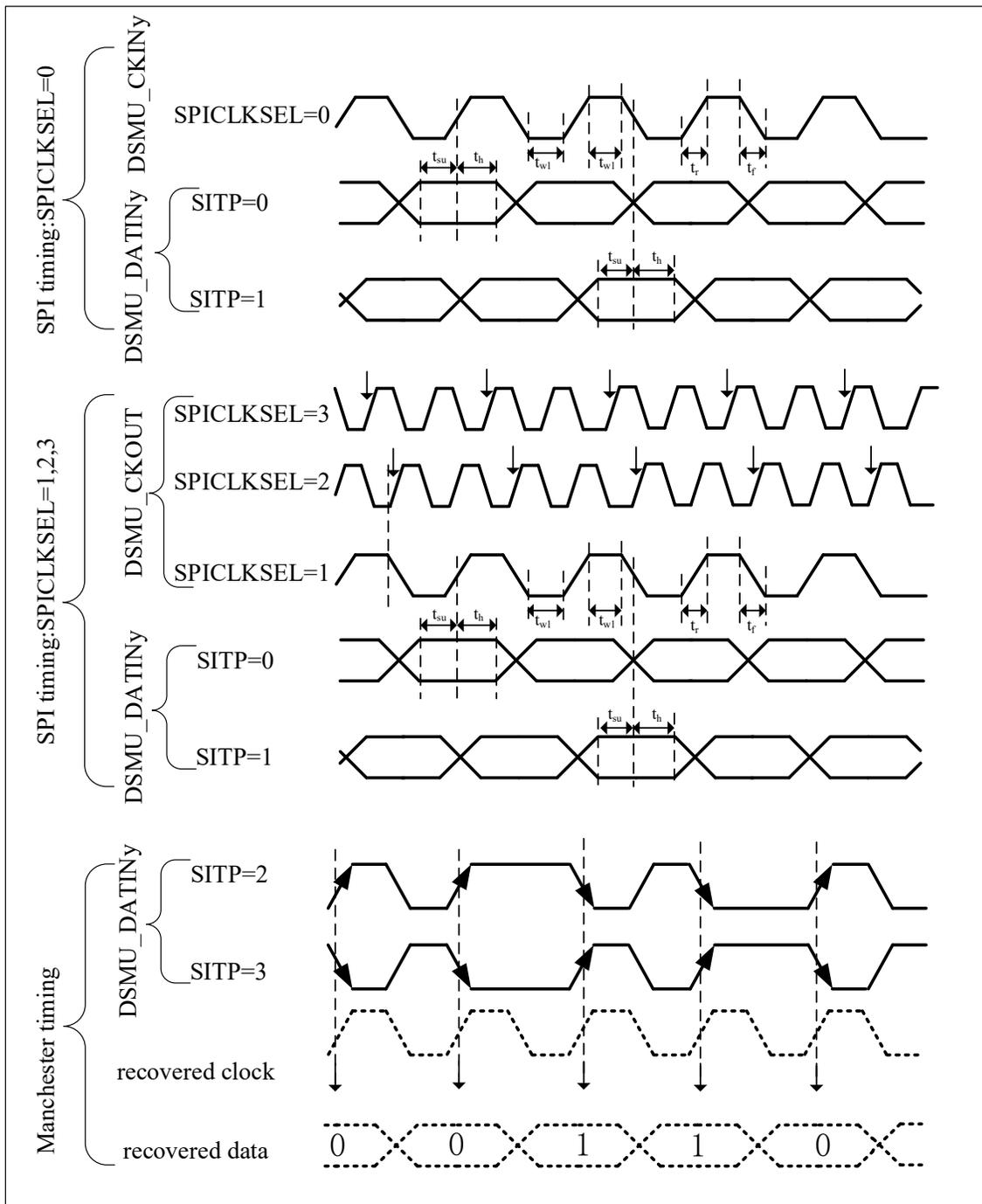
For more details on the characteristics of ports ($DSMU_CKINx$, $DSMU_DATINx$, $DSMU_CKOUT$), please refer to the I/O Port Characteristics section 4.3.14.

Table 4-75 DSMU Timing Parameters

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{DSMU} ($1/T_{DSMU}$)	DSMU clock	$2.3V < V_{DD} < 3.63V$	-	-	300	MHz
f_{CKIN} ($1/T_{CKIN}$)	Input clock frequency	$2.3V < V_{DD} < 3.63V$, SPI interface (SITP[1:0] = 0,1), external clock mode (SPICKSEL[1:0] = 0)	-	-	20	
		$2.3V < V_{DD} < 3.63V$, SPI interface (SITP[1:0] = 0,1), external clock mode (SPICKSEL[1:0] = 0)	-	-	20	
		$2.3V < V_{DD} < 3.63V$, SPI interface (SITP[1:0] = 0,1), internal clock mode (SPICKSEL[1:0] \neq 0)	-	-	20	
		$2.3V < V_{DD} < 3.63V$, SPI interface (SITP[1:0] = 0,1), internal clock mode (SPICKSEL[1:0] \neq 0)	-	-	20	
f_{CKOUT}	Output clock frequency	$2.3V < V_{DD} < 3.63V$	-	-	20	

Duty _{CKOUT} T	Output clock duty cycle	2.3V < VDD < 3.63V	45	50	55	%
t _{wh} (CKIN) t _{wl} (CKIN)	Input clock high/low pulse width	2.3V < VDD < 3.63V, SPI interface (SITP[1:0] = 0,1), external clock mode (SPICLKSEL[1:0] = 0)	-	Tclk/2	-	ns
t _{su}	Input data setup time	2.3V < VDD < 3.63V, SPI interface (SITP[1:0] = 0,1), external clock mode (SPICLKSEL[1:0] = 0)	TBD	TBD	TBD	
t _h	Input data hold time	2.3V < VDD < 3.63V, SPI interface (SITP[1:0] = 0,1), external clock mode (SPICLKSEL[1:0] = 0)	TBD	TBD	TBD	
T _{Manchester}	Manchester data period (self-recovery clock period)	2.3V < VDD < 3.63V, Manchester interface (SITP[1:0] = 2,3), internal clock mode (SPICLKSEL[1:0] ≠ 0)	(CKOUTDIV+1) * T _{DSMUCLK}	-	(2*CKOUTDIV) *T _{DSMUCLK}	

Figure 4-49 DSMU Channel Transceiver Timing Diagram



4.3.33 12-bit Analog-to-Digital Converter (ADC) Electrical Characteristics

Unless otherwise specified, the parameters in Table 4-76 are measured under the environmental conditions (ambient temperature 25 °C), f_{HCLK} frequency, and V_{DDA} supply voltage specified in Table 4-4.

Note: It is recommended to perform a calibration each time after power-up.

Table 4-76 ADC Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Supply voltage	-	2.3	-	3.6	V
V_{REF+}	Positive reference voltage	-	2.3	-	V_{DDA}	V
f_{ADC}	ADCclock frequency	-	-	-	20	MHz
f_s	Sampling rate ⁽¹⁾	-	-	-	5	Msp/s
V_{AIN}	Conversion voltage range ⁽²⁾	-	0(V_{SSA} or V_{REF-} tied to ground)	-	V_{REF+}	V
R_{ADC}	Sample switch resistance	2.4~3.3V	-	250		ohm
		2.3~2.4V	-	350		
C_{ADC}	Internal sample and hold capacitor	-	-	1.5	-	pF
SNDR	Singal noise distortion ration	$f_{ADC} = 20$ MHz, sample rate=5Msp $f_{in}=200k$ $T_A = 25$ °C differential mode	-	68.73	-	dBFS
T_{cal}	Calibration time	-	74			$1/f_{ADC}$
t_s	Sampling time	$f_{ADC} = 20$ MHz	0.05	-	7	us
T_S			1	-	-	$1/f_{ADC}$
t_{STAB}	Power-up time	-	0	0	20	μs
$t_{CONV}^{(2)}$	Total conversion time (including sampling time)	-	4~400 (sampling t_s + successive approximation 3)			$1/f_{ADC}$

1. Guaranteed by design, not tested in production.
2. Depending on the package, V_{REF+} may be internally connected to V_{DDA} , and V_{REF-} may be internally connected to V_{SSA} .
3. The relationship between maximum input impedance R_{in} and sampling time is detailed in Table 4-77.

Table 4-77 ADC Sampling Time⁽¹⁾⁽²⁾

Resolution	R_{in} (kΩ)	Minimum Sampling Time (ns)
12-bit	0	50
	0.45	100
	0.7	150
	0.95	200
	1.95	400
	2.95	600
	3.95	800

	4.95	1000
	9.95	2000

- Guaranteed by design, not tested in production.
- Test conditions: $V_{DDA} = 2.4V$ to $3.6V$, $V_{CAP} = 0.9V$, $T_A = 105^\circ C$, $f_{clk} = 20$ MHz.

Table 4-78 ADC Accuracy – Limited Test Conditions⁽¹⁾⁽²⁾

Symbol	Parameter	Test Conditions	Typ	Max ⁽³⁾	Unit
ET ⁽⁴⁾	Comprehensive error	$f_{HCLK} = 200$ MHz, $f_{ADC} = 20$ MHz, sample rate = 3.33M sps, $V_{DDA} = 3.3V$, $T_A = 25^\circ C$ Measurements are made after the ADC is calibrated, $V_{REF+} = 2.5V$, Single-ended mode	TBD	-	LSB
EO ⁽⁴⁾	Offset error		TBD	-	
ED	Differential linear error		± 1.3	-	
EL	Integral linear error		± 1.4	-	
ET ⁽⁴⁾	Comprehensive error	$f_{HCLK} = 200$ MHz, $f_{ADC} = 20$ MHz, sample rate = 3.33M sps, $V_{DDA} = 3.3V$, $T_A = 25^\circ C$ Measurements are made after the ADC is calibrated $V_{REF+} = 3.3V$ differential mode	TBD	-	
EO ⁽⁴⁾	Offset error		TBD	-	
ED	Differential linear error		± 2.2	-	
EL	Integral linear error		± 2.2	-	

- ADC DC accuracy values are measured after internal calibration.
- Relationship between ADC accuracy and reverse injection current: avoid injecting reverse currents on any standard analog input pins, as it significantly degrades the conversion accuracy of other analog inputs. It is recommended to add a Schottky diode (between the pin and ground) on any analog input pins that may have reverse injection currents.
- Forward injection currents within the $I_{INJ(PIN)}$ range specified in Section 4.2 will not affect ADC accuracy.
- Guaranteed by overall evaluation, not tested in production.

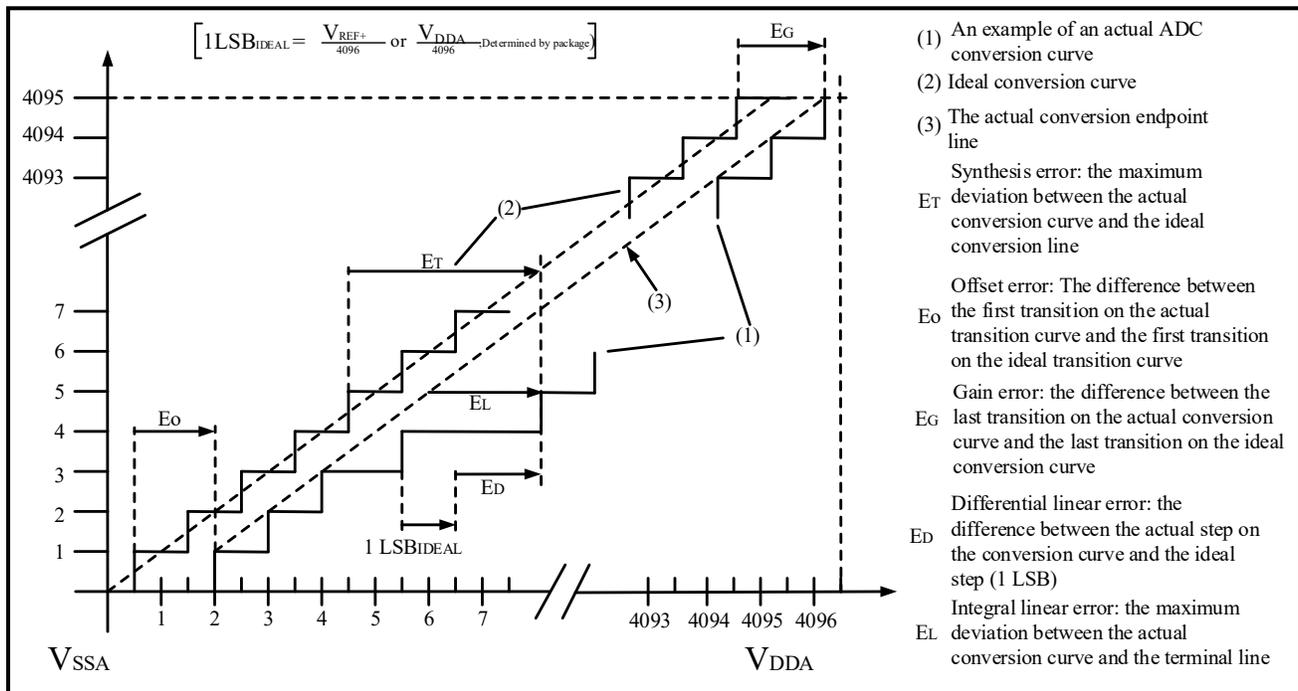
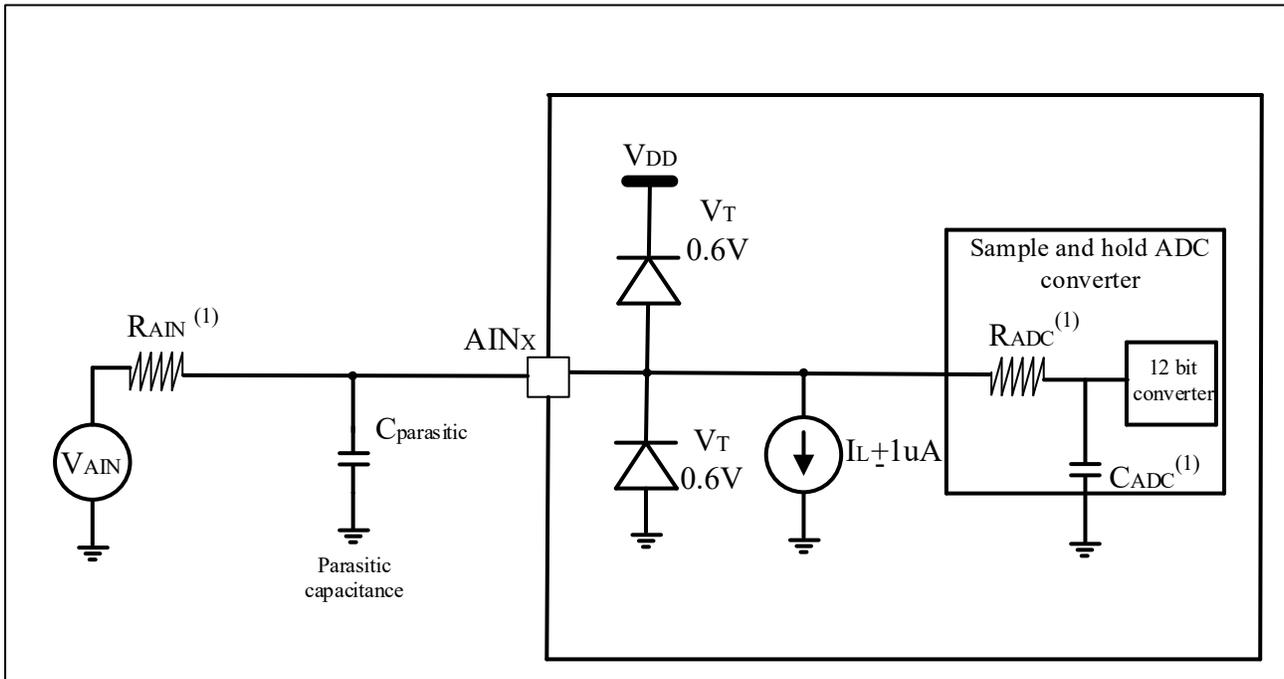
Figure 4-50 ADC Accuracy Characteristics


Figure 4-51 Typical Connection Diagram Using ADC


1. For values of R_{AIN} , R_{ADC} , and C_{ADC} , refer to Table 4-76.
2. $C_{parasitic}$ refers to the parasitic capacitance (approximately 7pF) on the PCB and solder pads (related to soldering and PCB layout quality). A larger $C_{parasitic}$ value will reduce conversion accuracy. The solution is to lower f_{ADC} .

4.3.34 12-bit Digital-to-Analog Converter (DAC) Electrical Parameters

Unless otherwise specified, the parameters in Table 4-79 and Table 4-80 are measured under environmental conditions specified in Table 4-4 (ambient temperature 25°C), f_{HCLK} frequency, and V_{DDA} supply voltage.

Table 4-79 DAC 1MSPS Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
V_{DDA}	Analog supply voltage	DAC output buffer off, output internal only	2.4	-	3.6	V	
V_{REF+}	Positive reference voltage	DAC output buffer off, output internal only	2.4	-	V_{DDA}		
V_{REF-}	Negative reference voltage	-	VSSA				
R_L	Load resistance when buffer is on	DAC output Buffer on	Connected to VSSA	5	-	-	k Ω
			Connected to VDDA	25	-	-	
R_o	Output impedance	DAC output buffer off	11.6	15	16.2	k Ω	
C_L	Load capacitance	-	-	-	50	pF	
DAC_OUT Max	DAC_OUT output voltage	Output buffer on	0.2	-	$V_{REF+} - 0.2$	V	
		Output buffr off	0	-	V_{REF+}	V	
I_{DD}	DAC DC consumption in idle (standby mode) ($V_{DDD}+V_{DDA}+V_{REF+}$)	-	-	543	732	μ A	
$t_{SETTLING}$	Settling time (full range: 12-bit input code from min to max, DAC_OUT reaches final value ± 1 LSB)	DAC buffer on $C_L \leq 50$ pF, $R_L \geq 5$ k Ω	-	3.1	4.5	μ s	
		DAC buffer off	-	4.9	6.2		
t_{WAKEUP}	Wake-up time from shutdown (DAC enabled to DAC_OUT reaches final value ± 1 LSB)	DACbuffer on, $C_L \leq 50$ pF, $R_L \geq 5$ k Ω	-	3.6	4.5	μ s	
		DACbuffer on, $C_L \leq 10$ pF	-	5.4	6.5		
PSRR	Power Supply Rejection Ratio (relative to VDD33A) (static DC measurement)	DACbuffer on, $C_L \leq 50$ pF, $R_L \geq 5$ k Ω	-	-85	-30	dB	
TW_to_W	Minimum time between two consecutive writes to DACx_DATO register to ensure correct DAC_OUT(1 LSB). DACxy_CTRL.EXOUT = 1, DACxy_CTRL.BxEN = 1	$C_L \leq 50$ pF, $R_L \geq 5$ k Ω	1	-	-	μ s	
	DACxy_CTRL.EXOUT = 1, DACxy_CTRL.BxEN = 0 or DACxy_CTRL.INOUT = 1, DACxy_CTRL.BxEN = 0	$C_L \leq 10$ pF	1.5	-	-		

Voffset	Middle code offset for 1 trim code step	VREF+ =3.6V		-	-	1500	μV
IDDA(DAC)	DAC consumption from VDDA	Output buffer on	No load, middle code(0x800)	-	199	333	μA
			No load, worst code(0xF1C)	-	467	643	
		Output buufer off	No load, middle code(0x800)	-	-	6	
IDDV(DAC)	DAC consumption from VREF+	Output buffer on	No load, middle code(0x800)	-	154	192	μA
			No load, worst code(0xF1C)	-	27	34	
		Output buffer off	No load, middle code(0x800)	-	148	185	
DNL	Differential Non-Linearity)	Output buffer on		-28	-	+36	LSB
		Output buffer off		-9	-	+3	
INL	Integral Non-Linearity	Output buffer on		-2	-	+2	LSB
		Output buffer off		-2	-	+2	
Offset	Offset error (measured at code 0x800)	Output buffer on, CL ≤ 50 pF, RL ≥ 5 kΩ	VREF+ =3.6V	-12	-	12	LSB
			VREF+ =2.3V	-18	-	18	
		Output buffer off, CL ≤ 50 pF, no RL		-12	-	12	
Gain error	Gain error	Output buffer on		-	±2.2	-	%
		Output buffer off		-	±0.5	-	

1. Guaranteed by characterization, not tested in production.

Table 4-80 DAC 15MSPS Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
V _{DDA}	Analog supply voltage	-	2.3	-	3.6	V	
V _{REF+}	Positive reference voltage	-	2.3	-	V _{DDA}	V	
V _{REF-}	Negative reference voltage	-	V _{SSA}			V	
DAC_OUT	DAC_OUT voltage	-	0	-	V _{REF+}	V	
DNL	Nonlinear distortion (deviation between two consecutive codes)	-	-2	-	2	LSB	
INL	Nonlinear accumulation (deviation measured at code i from the line connecting code 0 and code 4095)	CL ≤ 50 pF, no RL	-5	-	5	LSB	
t _{SETTLING}		VDD > 2.7	10%-90%	-	14	19	ns
			5%-95%	-	16	22	

	Settling time (full range: 12-bit input code from min to max, DAC_OUT reaches final value ± 1 LSB)	With One comparator on DAC output	1%-99%	-	21	30	
			32lsb	-	23	32	
			1lsb	-	52	71	
		VDD < 2.7 With One comparator on DAC output	10%-90%	-	18	24	
			5%-95%	-	21	28	
			1%-99%	-	28	36	
			32lsb	-	29	37	
1lsb	-	60	84				
t _{WAKEUP}	Wake-up time from shutdown (DAC enabled to DAC_OUT reaches final value ± 1 LSB)	CL ≤ 10 pF		-	1.6	4	μ s
PSRR	Power supply rejection ratio	VDD > 2.7 V		66	72	-	dB
		VDD < 2.7 V		54	72	-	dB
I _{DDA(DAC)}	DAC consumption from VDDA	No load, middle code(0x800)		-	-	7	μ A
I _{DDV(DAC)}	DAC consumption from VREF+	No load, middle code(0x800)		-	715	930	

4.3.35 Comparator (COMP) Characteristics

Unless otherwise specified, the parameters in Table 4-81 are measured under environmental conditions specified in Table 4-4 (ambient temperature 25°C), f_{HCLK} frequency, and V_{DDA} supply voltage.

Table 4-81 Comparator Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage	-	2.3	-	3.6	V
V_{IN}	Input voltage range	-	0	-	V_{DDA}	
V_{REF}	6bit DAC offset voltage	DAC mid output, $V_{REFP} = 3.3V$	-	± 5	± 12	mV
I_{REF}	6bit DAC static consumption from V_{REFP}	DAC mid output, $V_{REFP} = 3.3V$	-	33	46	μA
		DAC max output, $V_{REFP} = 3.3V$	-	45	61	μA
T_{START}	Comparator start-up settling time	-	-	-	5	μs
t_D	Propagation delay for 200 mV step with 100 mV overdrive	$V_{DDA} \geq 2.7$	-	20	24	ns
		$V_{DDA} < 2.7V$	-	30	45	
V_{OFFSET}	Comparator input offset error	Full common mode range	-	-	± 10	mV
V_{HYS}	Comparator hysteresis	No hysteresis	-	0	-	mV
		Low hysteresis	15	20	25	
		Medium hysteresis	26	30	41	
		High hysteresis	41	50	63	
I_{DDA}	Comparator consumption from V_{DDA}	Static	-	146	-	μA
		With 50 kHz ± 100 mV overdrive square signal	-	150	-	

1. Guaranteed by design, not tested in production.

4.3.36 Voltage Reference Buffer (VREFBUF) Characteristics

Unless otherwise specified, the parameters in Table 4-82 are measured under environmental conditions specified in Table 4-4 (ambient temperature 25°C), f_{HCLK} frequency, and V_{DDA} supply voltage.

Table 4-82 Voltage Reference Buffer Characteristics ⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage	-	2.3	-	3.6	
V_{REFBUF_OUT}	Reference voltage output	VS= 00 & $V_{DDA} \geq 2.8V$	-	2.498	-	V
		VS= 01 & $V_{DDA} \geq 2.4V$	-	2.048	-	
		VS=10 & $V_{DDA} \geq 2.3V$	-	1.802	-	
		VS=11 & $V_{DDA} \geq 2.3V$	-	1.497	-	
TRIM	Trim step resolution	-	-	±5	-	%
CL	Load capacitance	-	0.5	1	2	μF
RESR	Equivalent Series Resistance	-	0	0	2	Ω
PSRR	Power Supply Rejection Ratio	DC	-	45	-	dB
		100KHz	-	70	-	
t_{START}	Start-up time	CL = 1 μF	-	366.1	1080	μs
$I_{DDA(VREFBUF)}$	VREFBUF consumption from VDDA	Iload ≤ 10 mA	-	48	-	μA
I_{INRUSH}	Max $I_{DDA(VREFBUF)}$ at startup phase	Iload = 0	7.42	18.88	-	mA

1. Guaranteed by design, not tested in production.

4.3.37 Temperature Sensor (TS) Characteristics

Unless otherwise specified, the parameters in Table 4-83 are measured under environmental conditions specified in Table 4-4 (ambient temperature 25°C), f_{HCLK} frequency, and V_{DDA} supply voltage.

Table 4-83 Temperature Sensor Characteristics

Symbol	Parameter	Min	Typ	Max	Unit
$T_L^{(1)}$	Linearity V_{SENSE} with respect to temperature	-	-	± 3	°C
Avg_Slope ⁽¹⁾	Average slope	-3.1	-3.4	-4.15	mV/°C
$V_{25}^{(1)}$	Voltage at 25°C	-	1.37	-	V
$t_{START}^{(1)}$	Start-up time	4	-	10	μs
$T_{S_temp}^{(2)(3)}$	ADC sampling time when reading temperature	2	-	-	μs

1. Guaranteed by characterization, not tested in production.

4.3.38 Temperature and VBAT monitoring

Unless otherwise specified, the parameters in Table 4-84 and Table 4-85 are measured under environmental conditions specified in Table 4-4 (ambient temperature 25°C), f_{HCLK} frequency, and V_{DDA} supply voltage.

Table 4-84 VBAT Monitor Characteristics

Symbol	Parameter	Min	Typ	Max	Unit
R	Resistor Bridge for VBAT	-	75	-	KΩ
Q	Ratio on VBAT measurement	-	4	-	-
$E_r^{(1)}$	Error on Q	-10	-	10	%
$t_{svbat}^{(1)}$	ADC Sampling Time When Reading VBAT Input	2	-	-	μs

1. Guaranteed by design, not tested in production.

Table 4-85 VBAT Charging Characteristics

Symbol	Parameter	Min	Typ	Max	Unit
R_{BC}	Battery Charging Resistor Level 1	-	10	-	KΩ
	Battery Charging Resistor Level 2	-	3	-	KΩ

5 Package Size

5.1 BGA240+25 Package Size

Figure 5-1 BGA240+25 Package Dimension

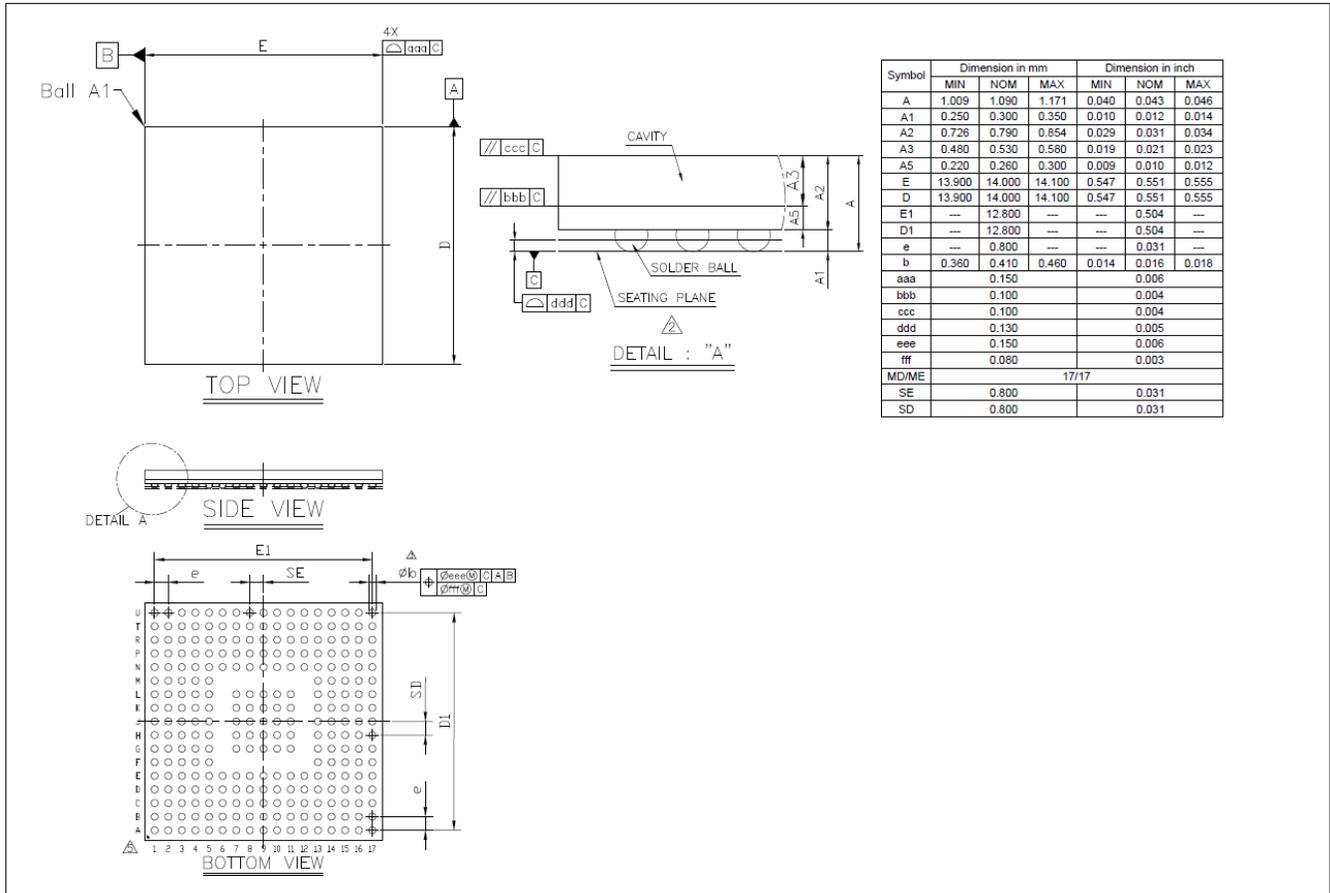


Figure 5-2 Recommended Pads for BGA240+25 Package

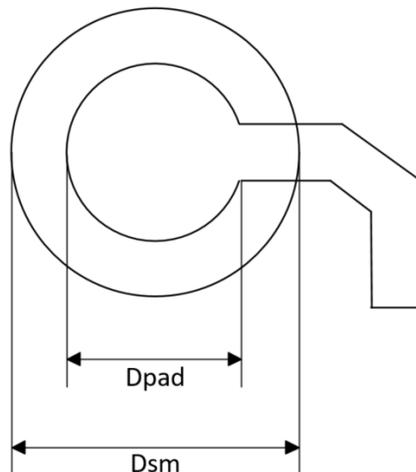
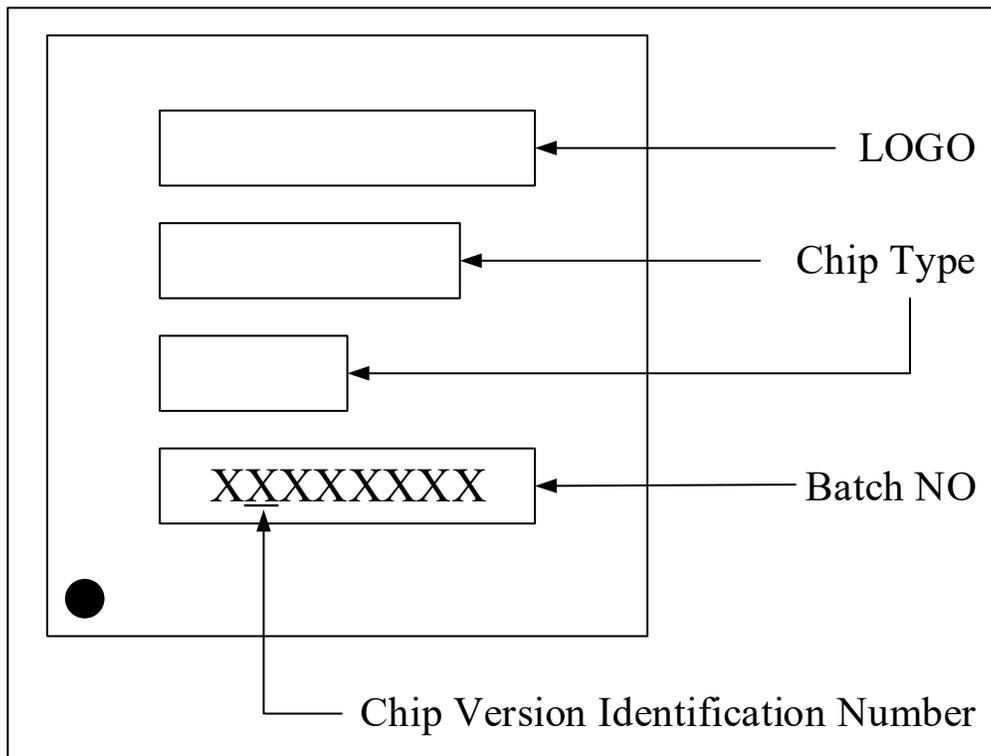


Figure 5-3 Recommended PCB Design Rules for BGA240+25 Package

Dimension	Recommended values
Pitch	0.8 mm
Dpad	0.350 mm
Dsm	0.400 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.350 mm
Stencil thickness	0.100 mm
Pad trace width	0.120 mm

5.2 Silkscreen Description

Figure 5-4 Silkscreen Diagram



6.2 Ordering Code Information

Table 6-1 Ordering Code Information for N32H787 Series

Ordering Model ⁽¹⁾	Package	Package Dimension	Packaging ⁽²⁾	SPQ ⁽³⁾	Temperature Range
N32H787XIB7	BGA240+25	14mm x 14mm	Tray	119	-40°C~105°C
N32H787XKB7	BGA240+25	14mm x 14mm	Tray	119	-40°C~105°C

1. For the latest and detailed ordering information, refer to the Product Selection Guide.
2. This is the standard packaging. For other packaging requirements, please contact Nations Technologies.
3. Standard Packaging Quantity

7 Version History

Version	Date	Changes
V1.2.0	2026.01.19	First release

8 Notice

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